

TSTE19 Power Electronics

Lecture 11

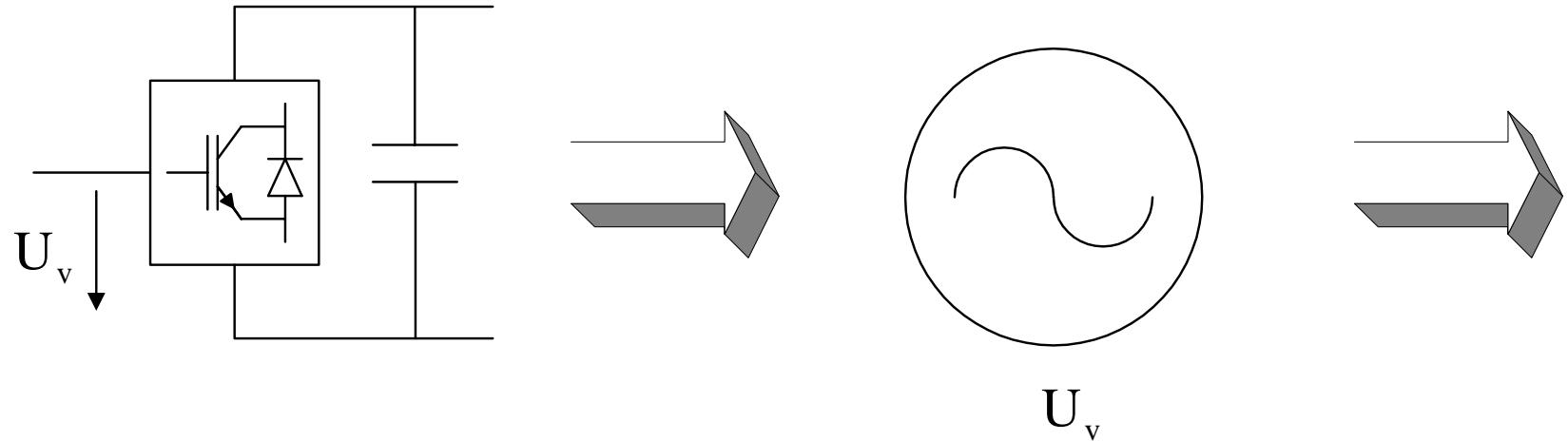
Tomas Jonsson

ISY/EKS

Outline

- Converter control
- Snubber circuits
- Lab 3 introduction

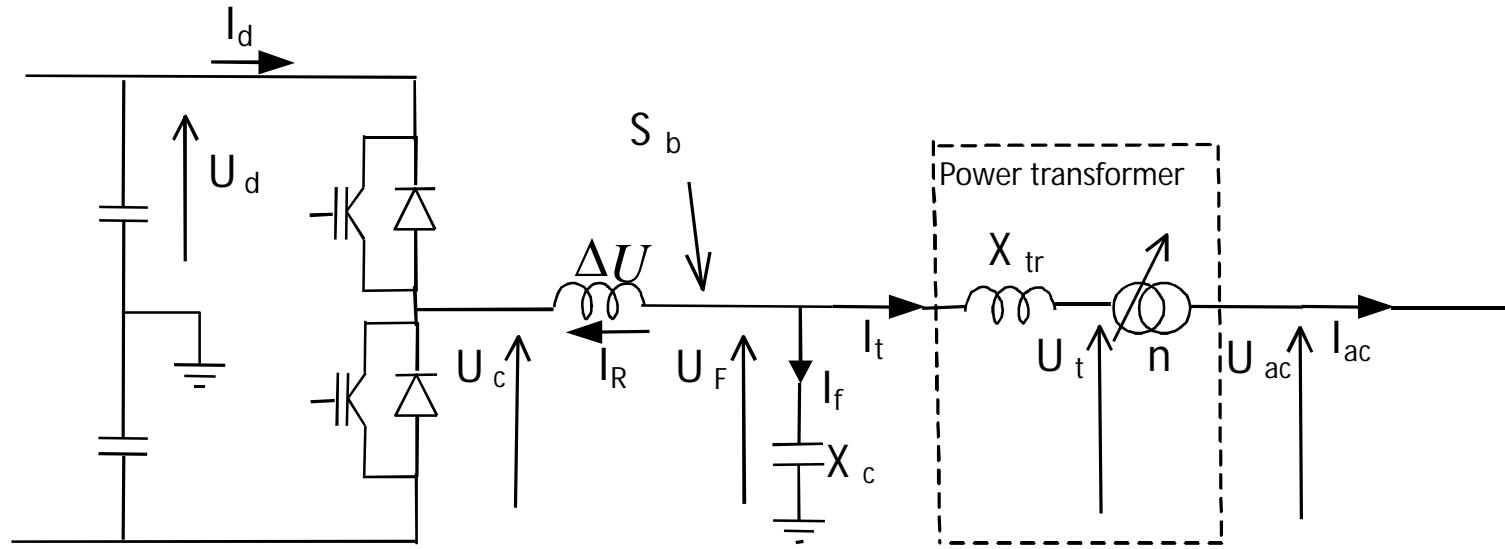
Basic control principle. Voltage Source Converter (VSC)



adjustable

{ amplitude
phase angle
frequency

Control of Active and Reactive Power

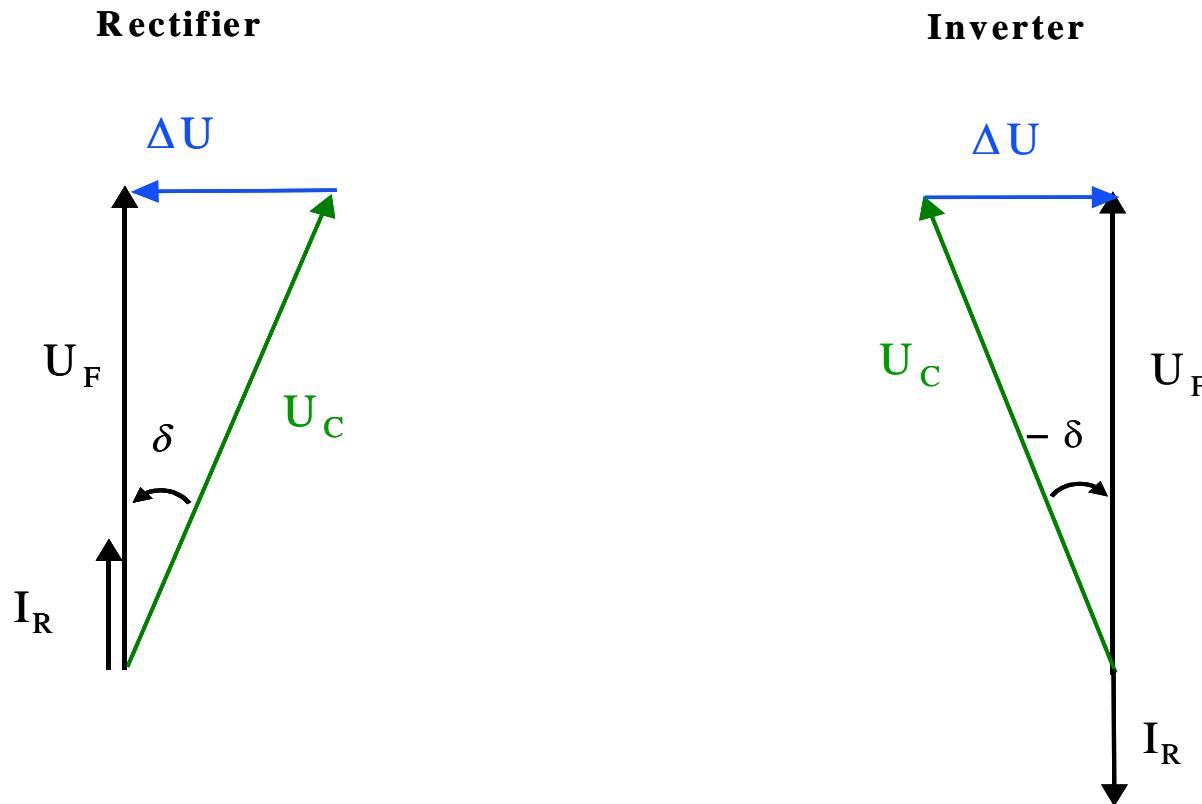


$$\vec{S}_b = P + jQ = \sqrt{3} \times \vec{U}_F \times \vec{I}_R^*$$

$$P = \frac{U_F \times U_C \times \sin \delta}{\omega L}$$

$$Q = -\frac{U_F \times (U_F - U_C \times \cos \delta)}{\omega L}$$

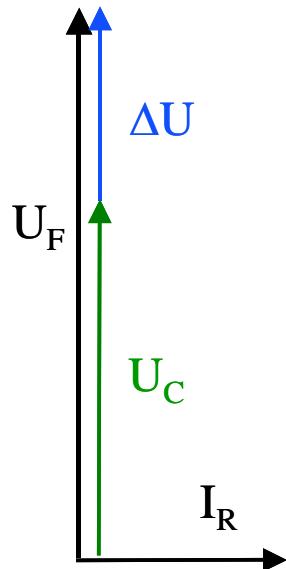
Control of Active Power



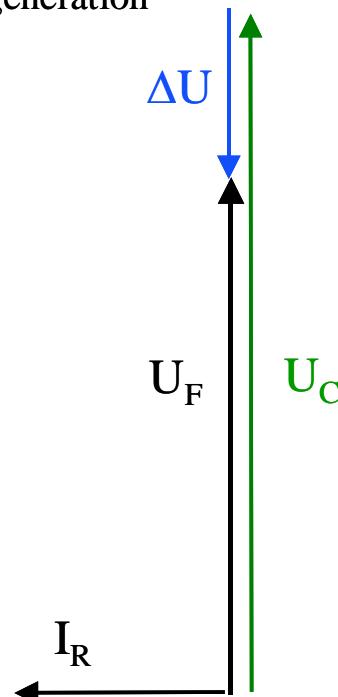
If the U_C is in phase-lag, the active power flows from AC to DC side (rectifier)
If the U_C is in phase-lead, the active power flows from DC to AC side (inverter)

Control of Reactive Power

Reactive power
consumption

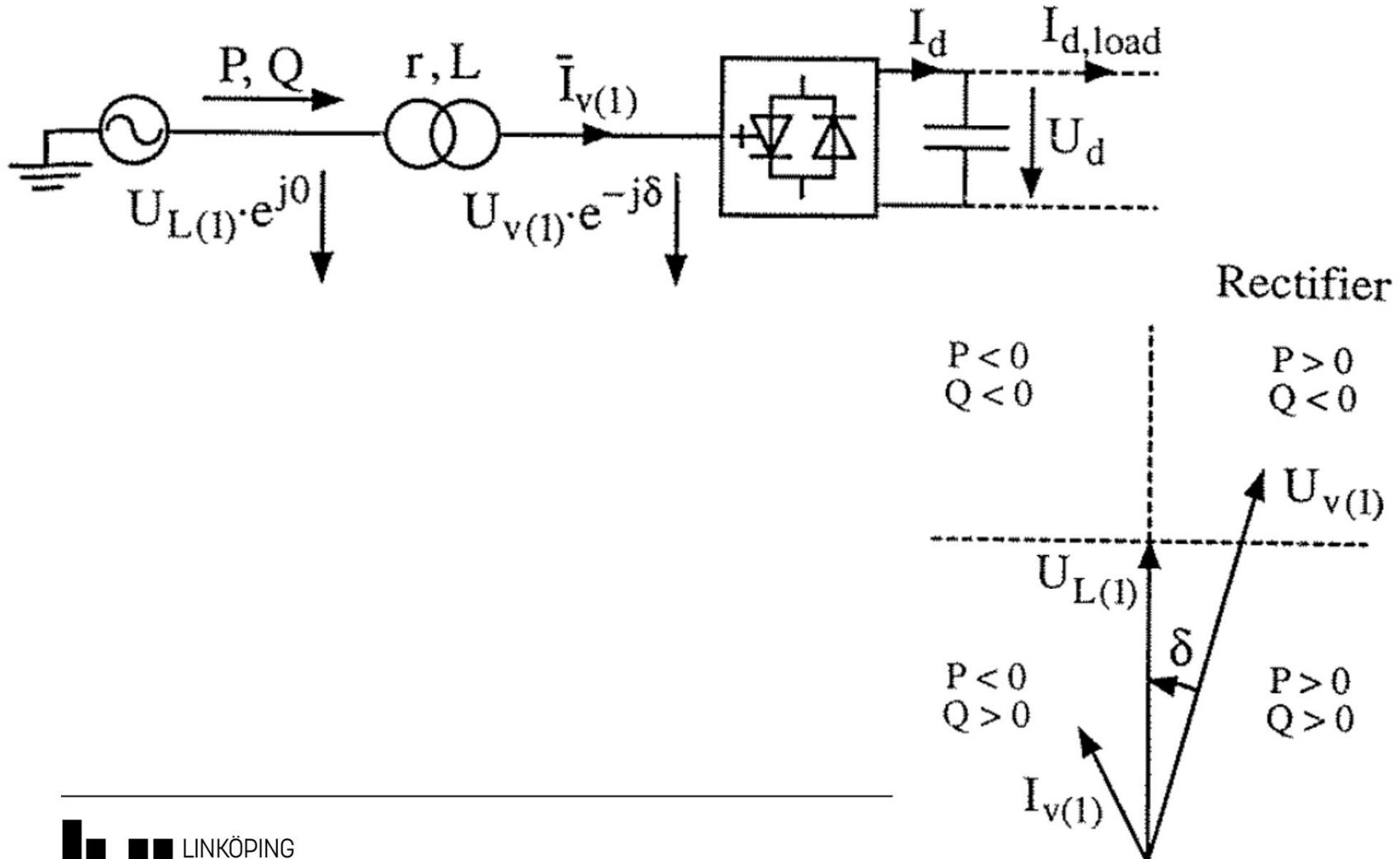


Reactive power
generation

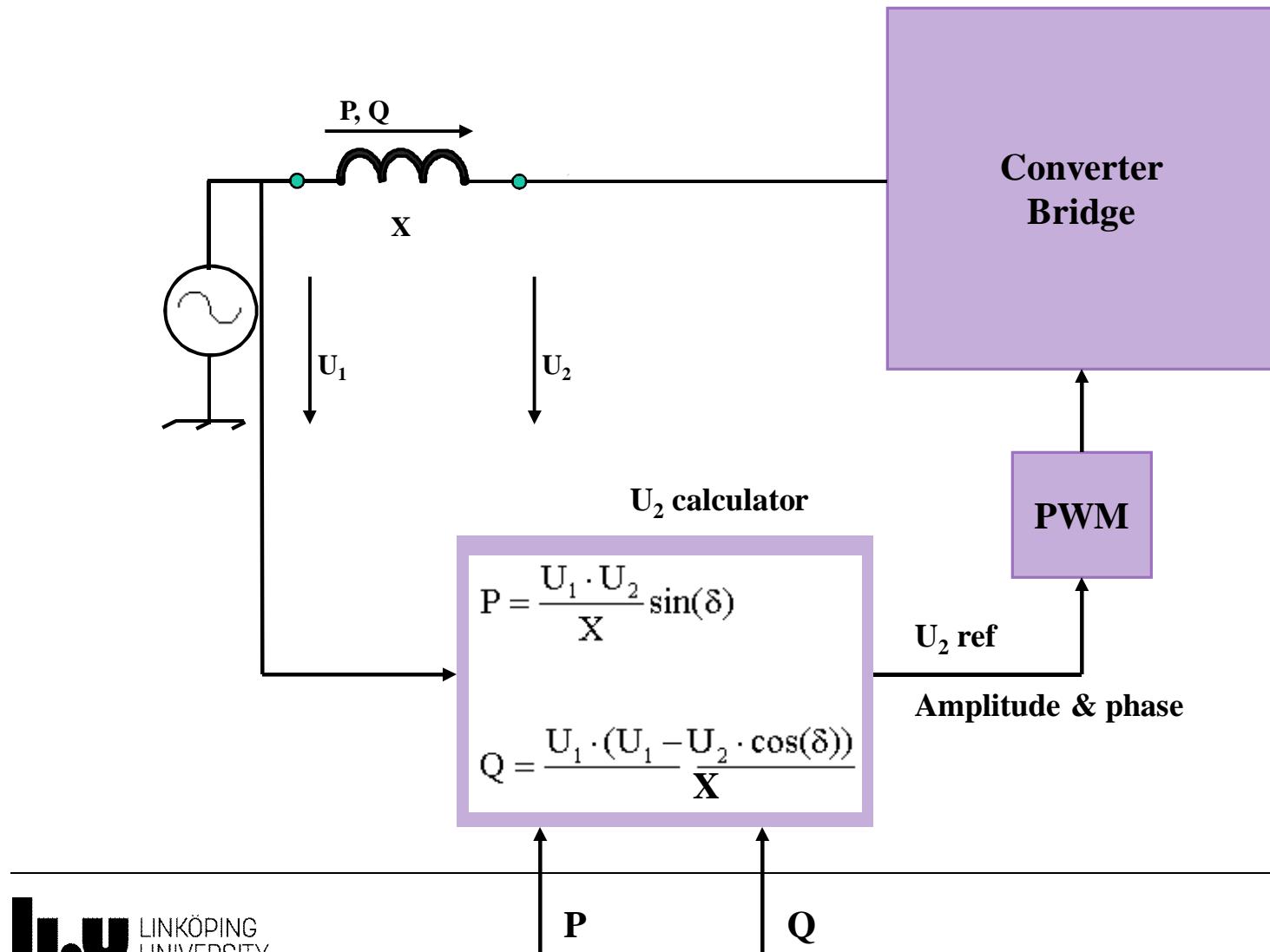


If $U_F > U_C$, there is reactive power consumption.
If $U_C > U_F$, there is reactive power generation.

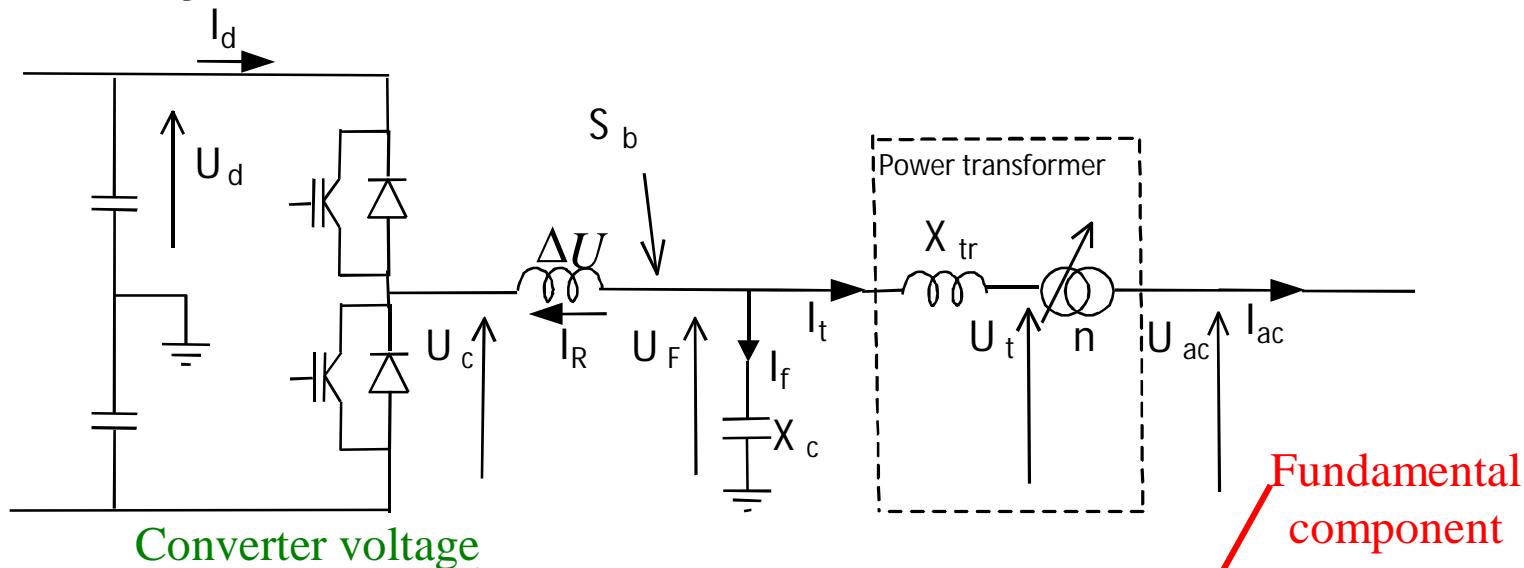
Control of P and Q in 4 quadrants



Calculation of Control Signal

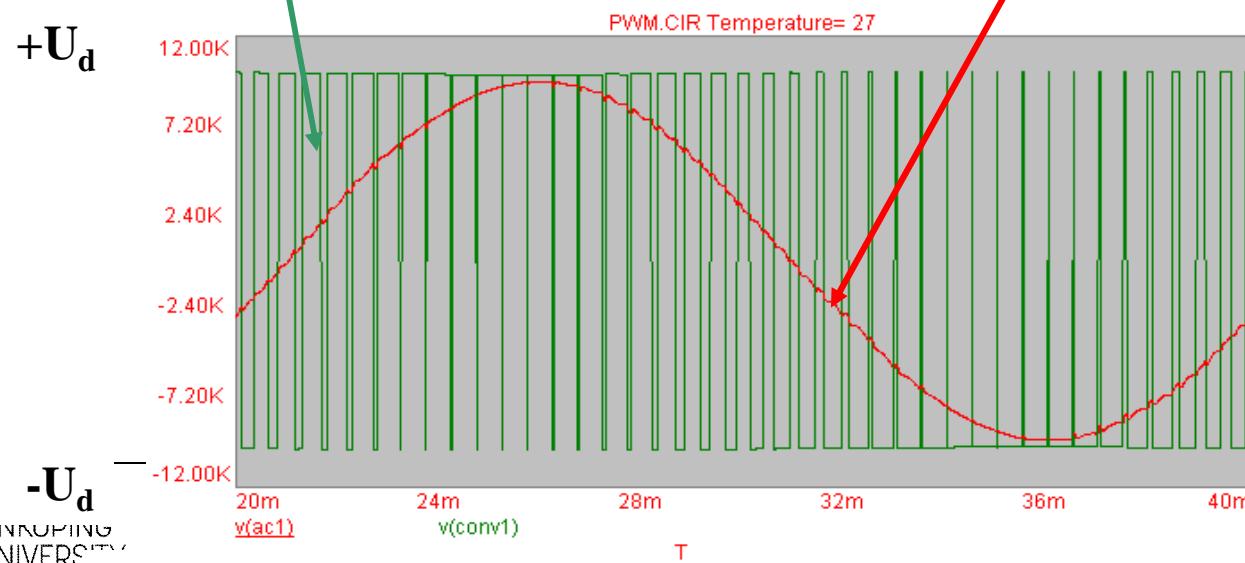


Voltage Source Converter with Pulse Width Modulation

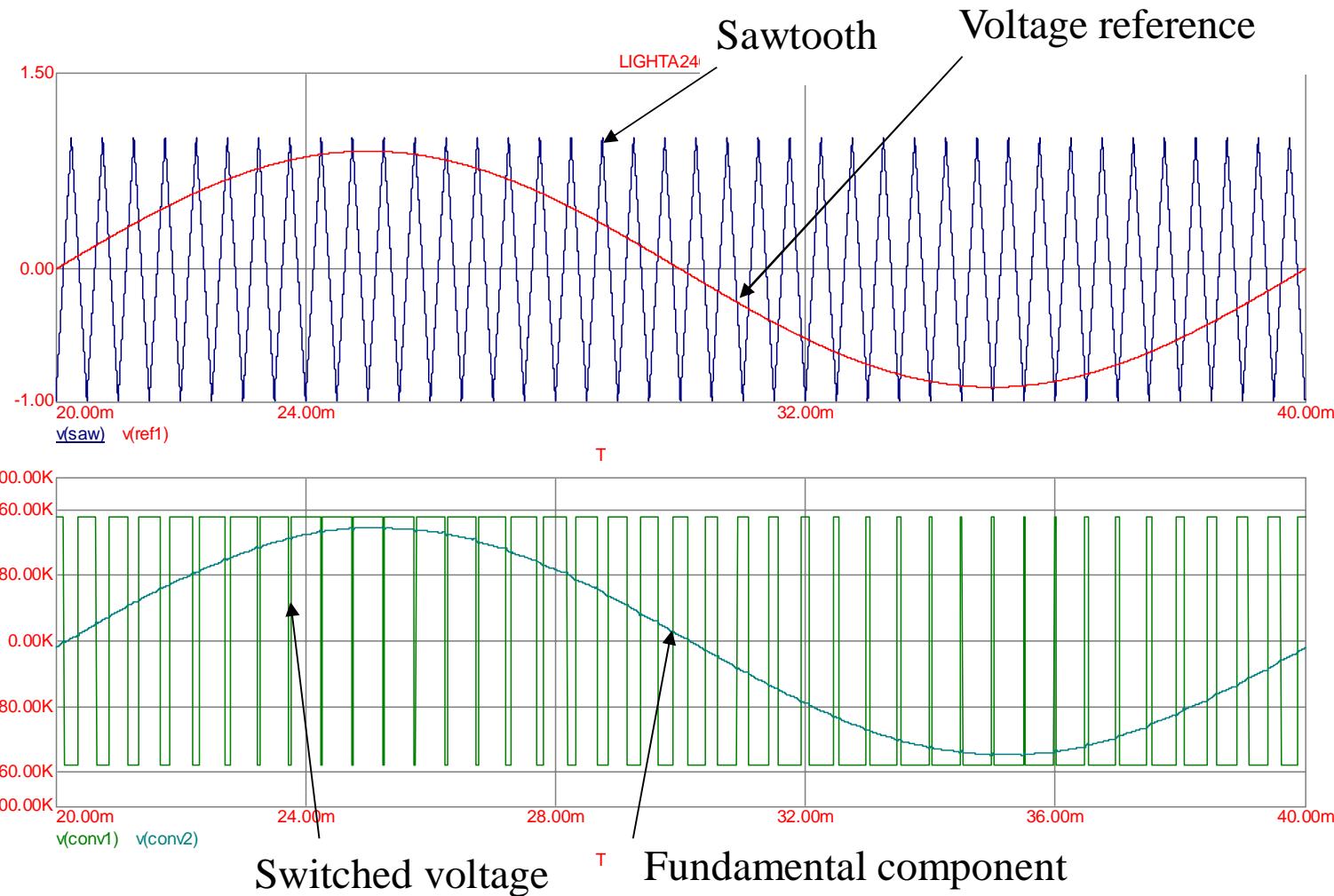


Converter voltage

Fundamental component

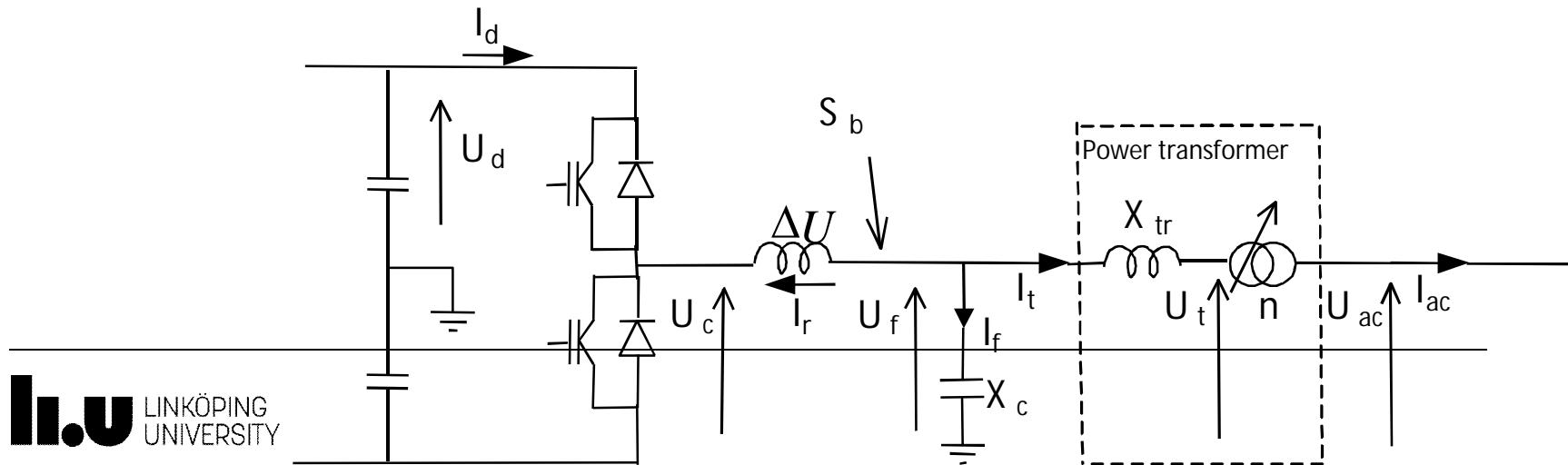


PWM- generation of pulses



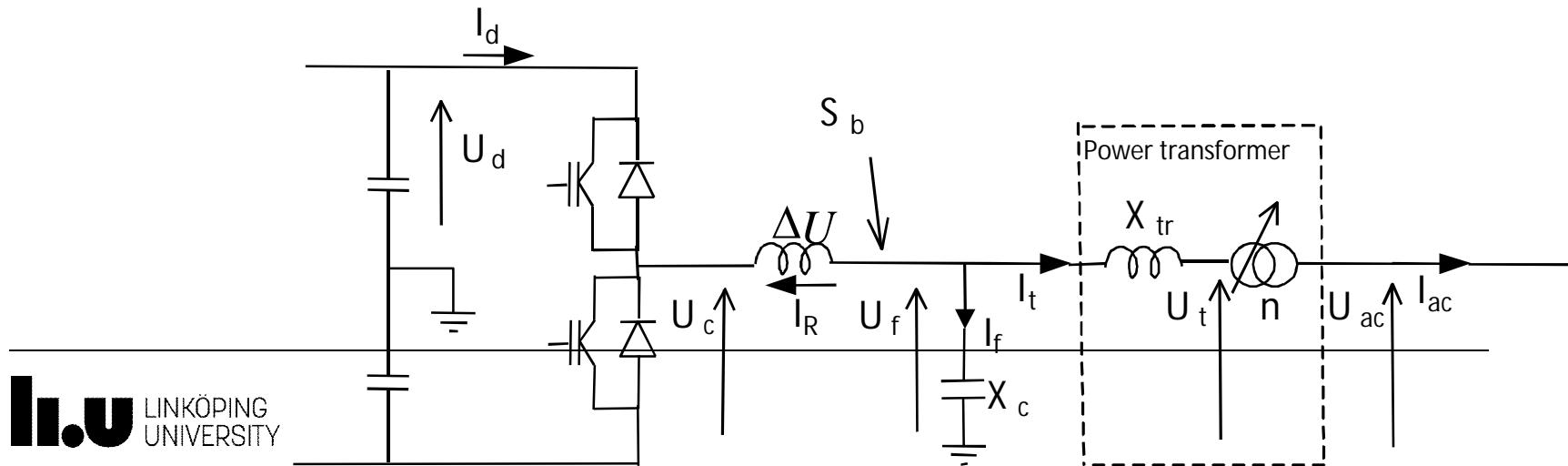
Feed-forward control

- $U_c = U_f + L \frac{di_r}{dt}$
- $U_{cRef} = (\text{Feedforward}) + (\text{Feedback})$
- $U_{cRef} = U_f + L \frac{di_r}{dt} + k(i_r - i_{rRef})$
- $i_{rRef} = \hat{I}_{rRef} \cos(\omega t + \varphi)$

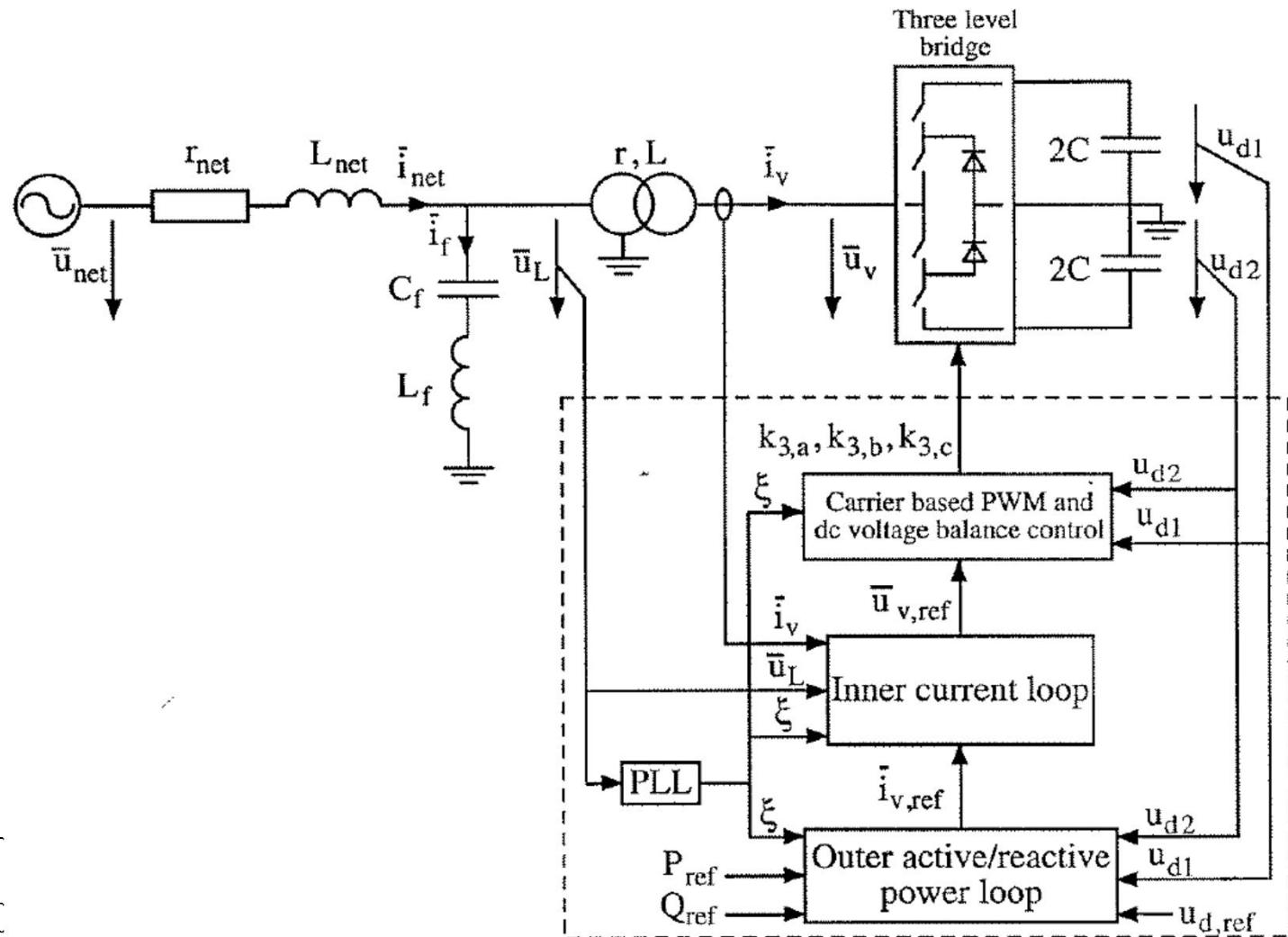


Vector control

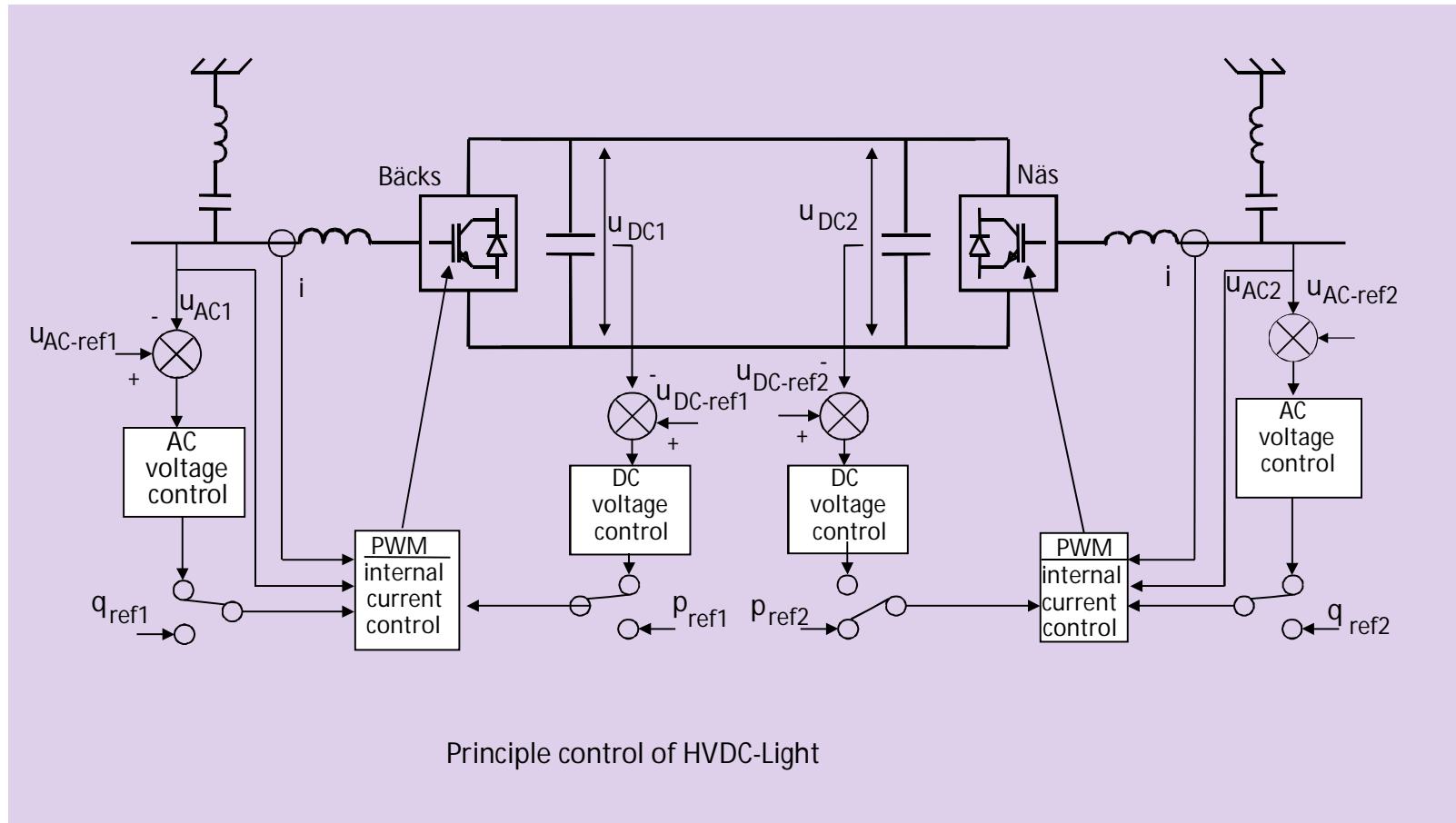
- $\bar{U}_c = \bar{U}_f + j\omega L \bar{I}_R$
- $\bar{I}_{rDQ} = i_r e^{-j\omega t} = \begin{cases} I_{rD} = i_r \cos \omega t \\ I_{rQ} = i_r \sin \omega t \end{cases}$
- $\bar{U}_{cDQref} = \bar{U}_{fDQ} + j\omega L \bar{I}_{rDQ} + k(\bar{I}_{rDQ} - \bar{I}_{rDQref})$
- PLL required to define ωt



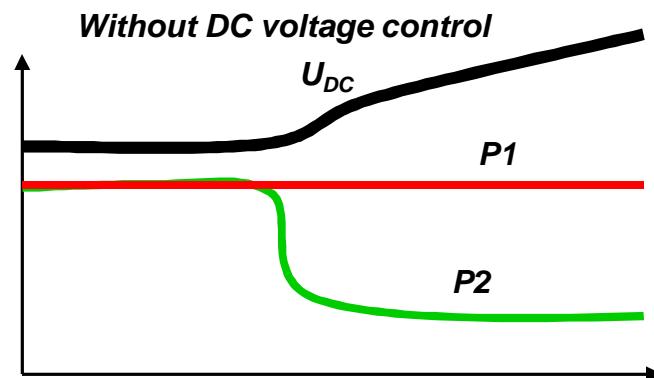
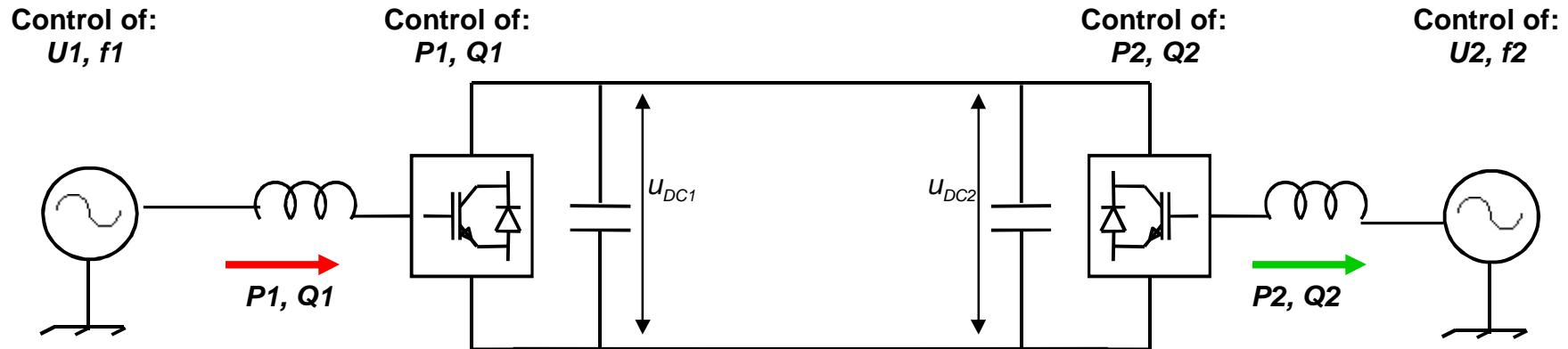
System with feed-forward and vector control



Control of AC - DC – AC converter

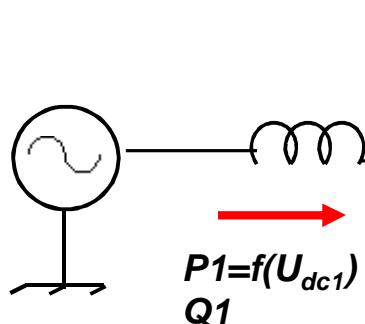


DC Power versus DC voltage

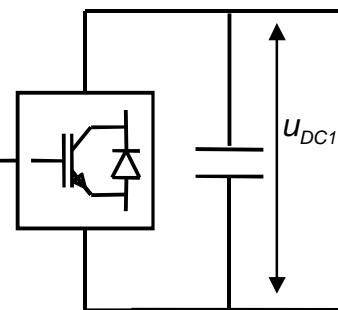


DC voltage control

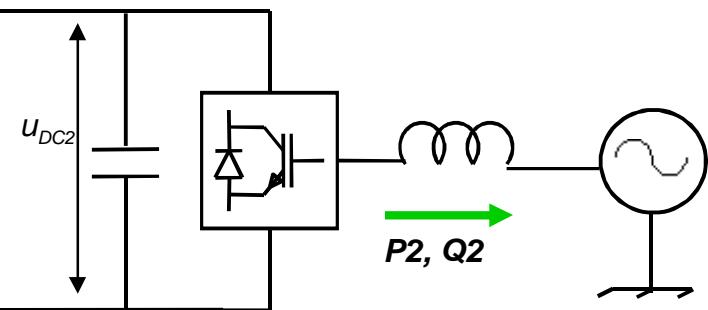
Control of:
 U_1, f_1



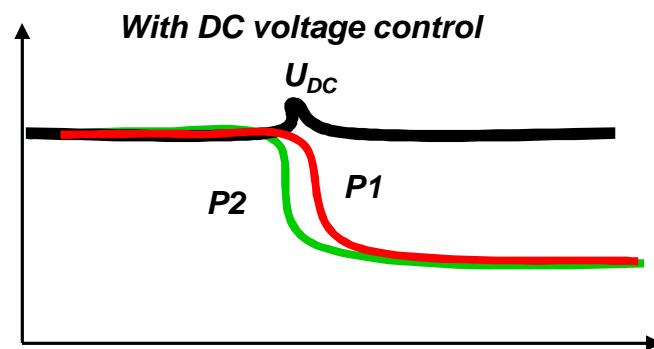
Control of:
 U_d, Q_1



Control of:
 P_2, Q_2



Control of:
 U_2, f_2



Lecture 11

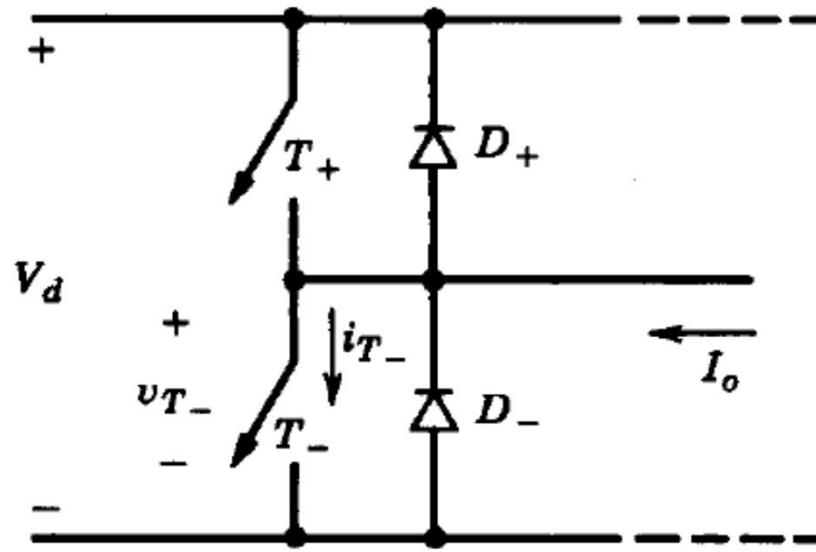
Snubber circuits

Problem with switching converters

- Switches turns on/off while conducting large currents
 - Recovery time create large power dissipation
- di/dt generates EMI (Electromagnetic interference)
- Small size requires higher switching frequencies

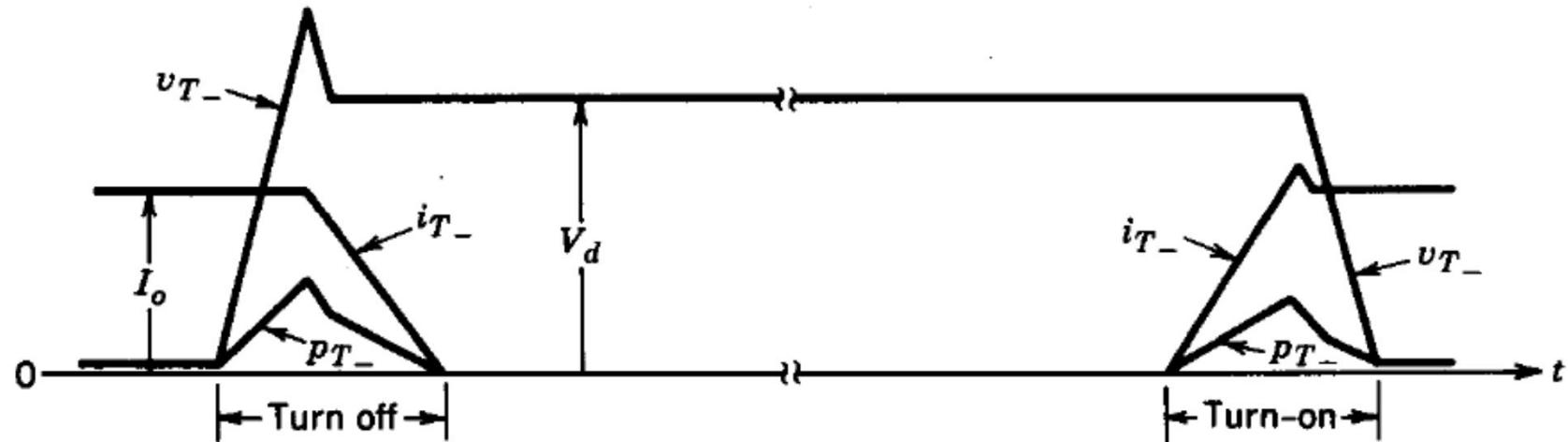
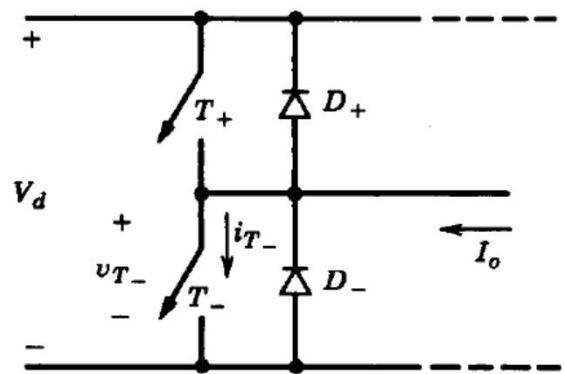
Example, full bridge leg

- Finite di/dt and dv/dt
- Parasitics: L, C, R
- I_o can be both positive and negative



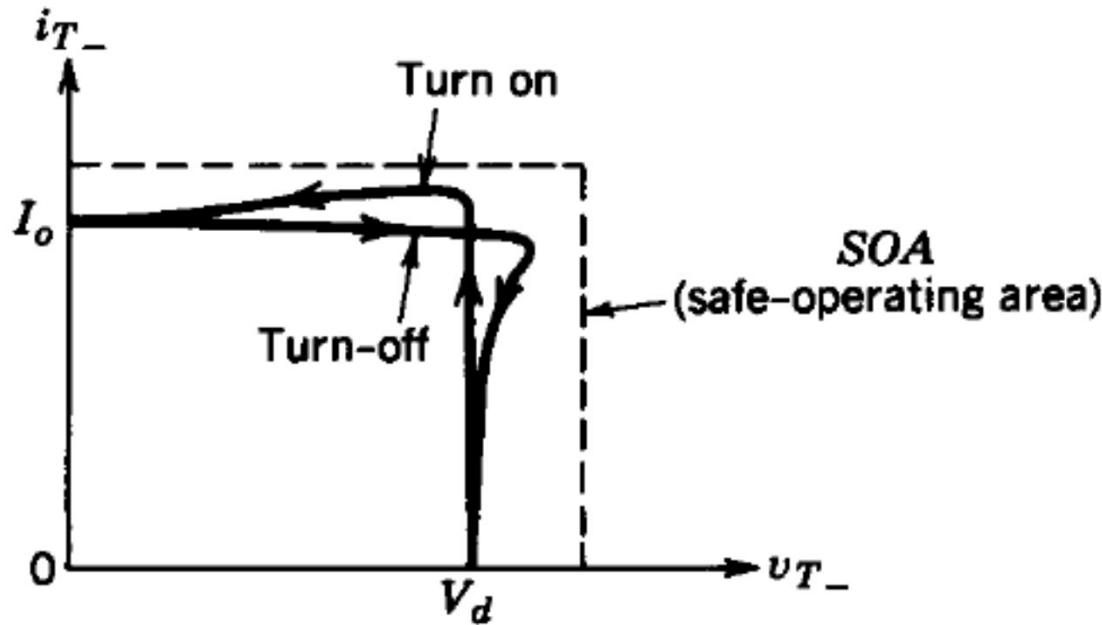
Hard switching waveform

- Stray inductance gives voltage overshoot
- Stray capacitance gives current overshoot
- Parasitics limits di/dt and dv/dt
- $P_{T-} = v_{T-} i_{T-}$



Switch voltage and current

- Short moments of high power dissipation
- Device must cope with the power dissipation
- Overshoot increases required SOA

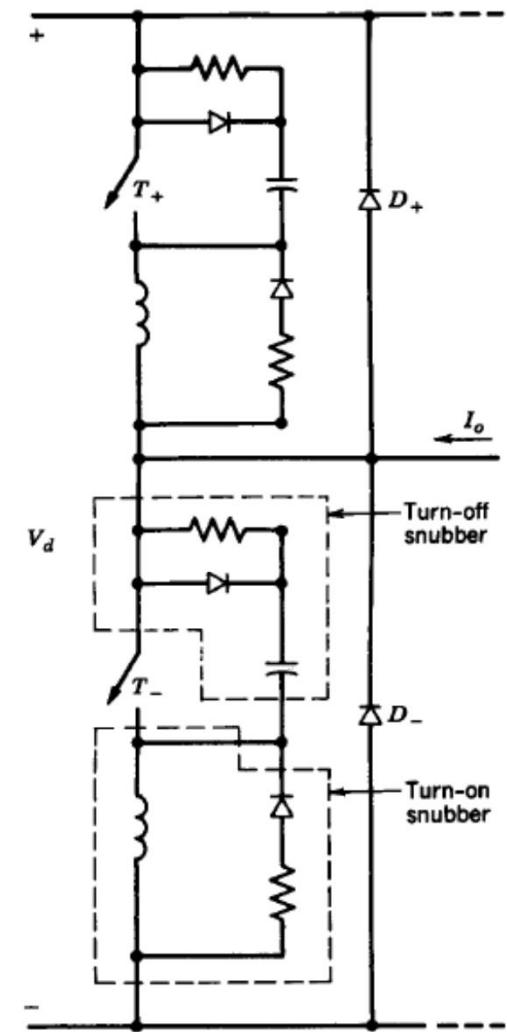
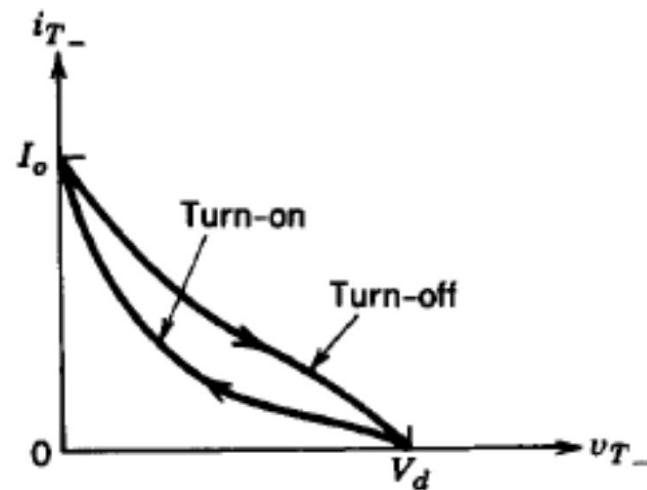


Component characteristic goal

- High di/dt and dv/dt to reduce power loss
- Short recovery time diodes
- Components must cope with short time full power dissipation
- Large stress on components due to power dissipation changes (material stress etc)

Snubber circuits

- Connected in parallel/serial with the switches
- Turn-on snubber
 - Inductor limits di/dt
 - Capacitance limits dv/dt
- Power now lost in snubber instead of switch



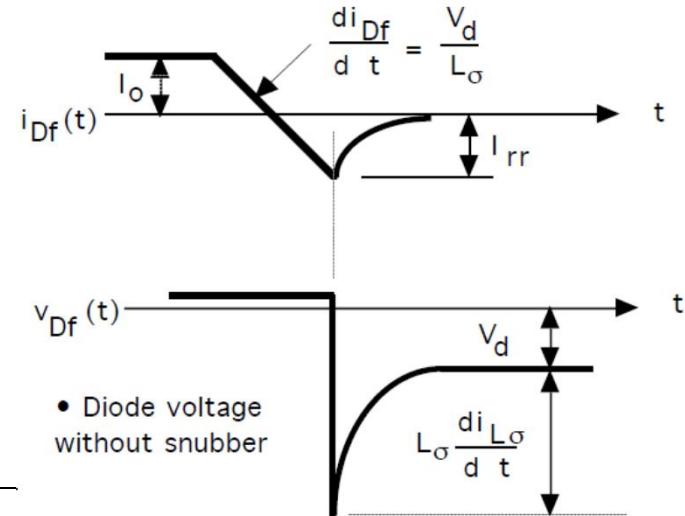
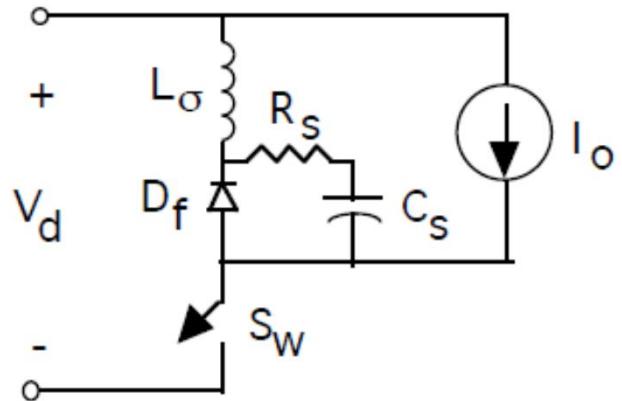
Snubber circuits

- Protect semiconductors
 - Limit voltages applied during turn-off transients
 - Limit device currents during turn-on transients
 - Limit the rate of rise (di/dt) of currents
 - Limit the rate of rise (dv/dt) of voltages
 - Shape the switching trajectory at turn on and turn off
- Three major classes
 - Unpolarized series RC snubbers
 - Polarized RC snubbers
 - Polarized LR snubbers

Diode snubbers

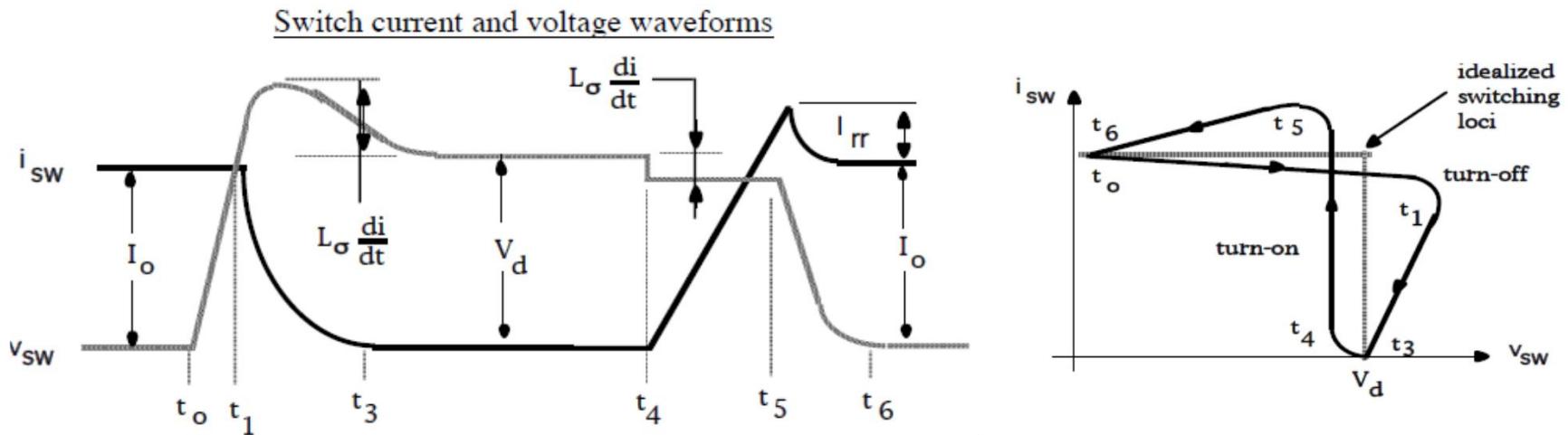
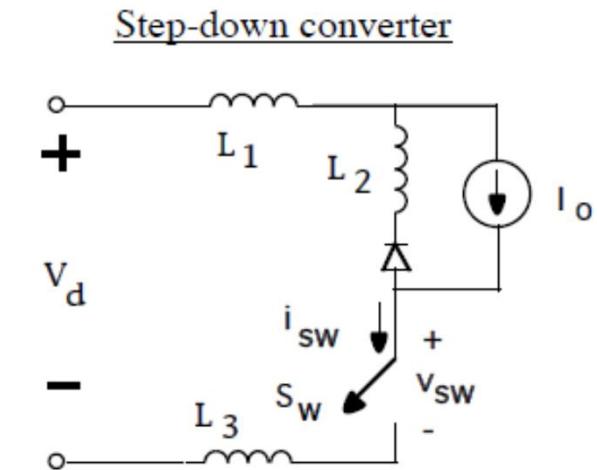
- L_σ stray inductance
- R C snubber circuit
- Problem when switch turns on
 - Current starts to flow in wrong direction
 - When diode turns off then L_σ tries to force continued current
- Diode breakdown if

$$V_d + L_\sigma \frac{di_{L\sigma}}{dt} > BV_{VB}$$



Snubber circuits for controlled switches

- Step-down example
 - $L_\sigma = L_1 + L_2 + L_3$ stray inductances
- Voltage and current overshoot due to inductances
- Three snubber types
 - Turn-off, turn-on, over-voltage

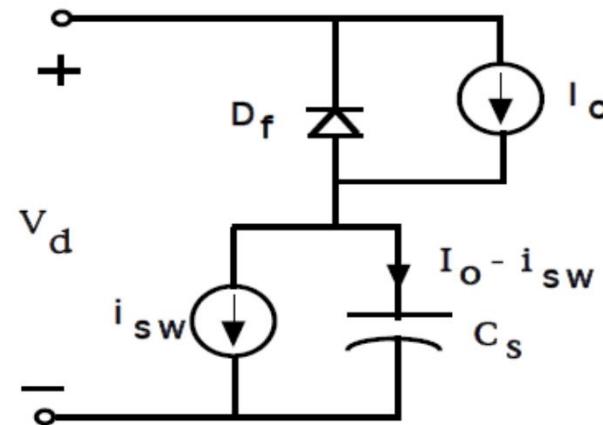
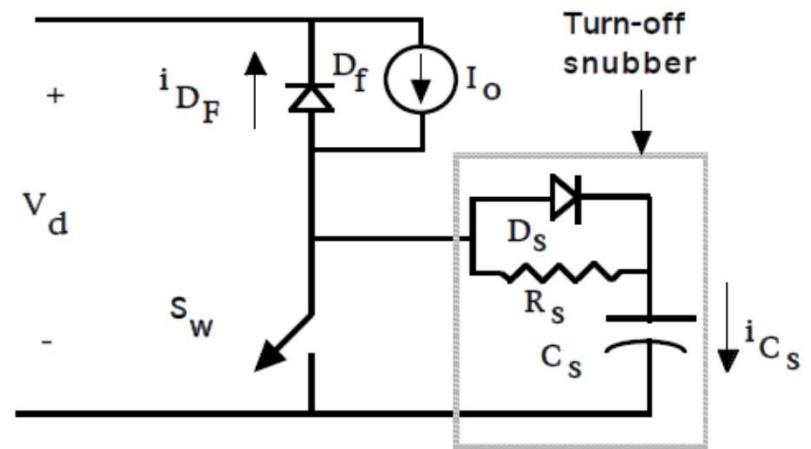


Turn-off snubber circuit for controlled switches

- Diode to only include R_s at switch turn-on
- Simplified circuit for switch turn-off

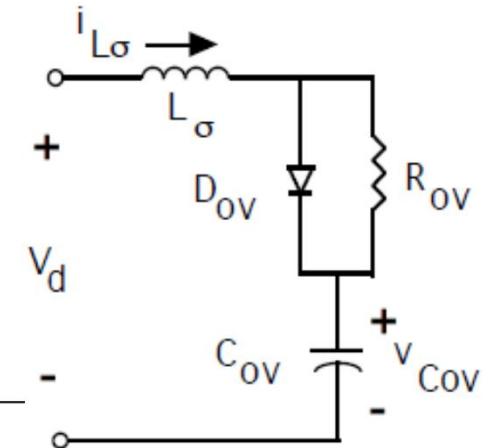
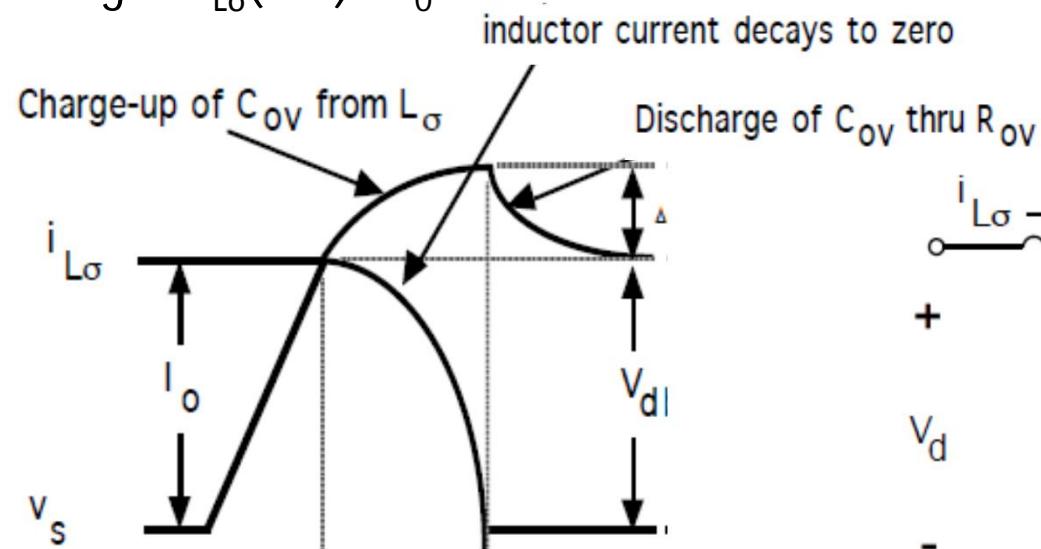
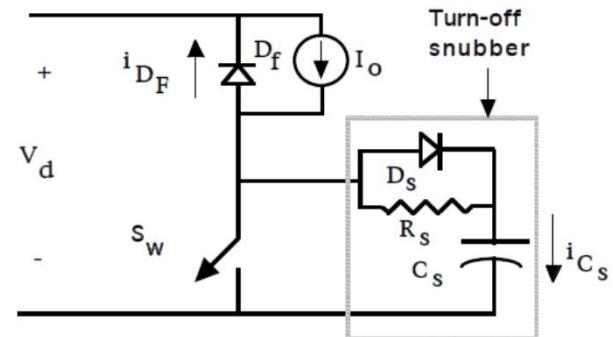
$$i_{sw}(t) = I_0 \left(1 - \frac{t}{t_{fi}} \right)$$

- Switch current at switch turn-off not affected by snubber circuit



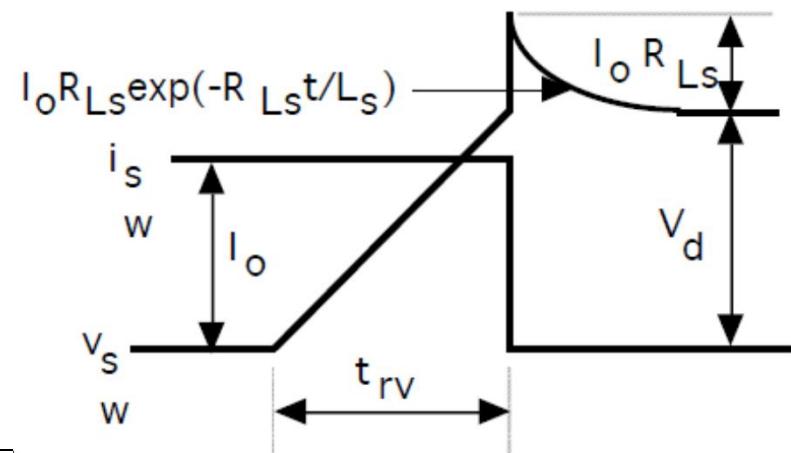
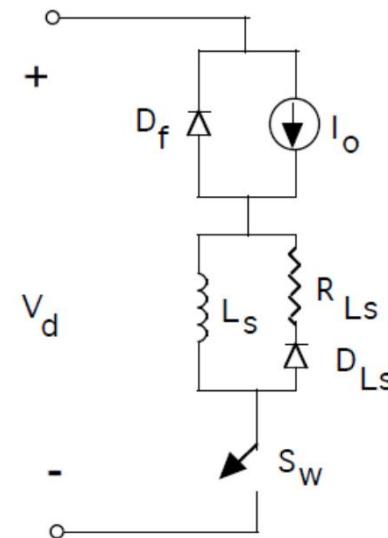
Overvoltage snubber function

- At transistor switch-off completed $t = 0$
 - $V_{COV} = V_D$
 - I_0 goes through D_f
 - Fast switch give $i_{L\sigma}(t=0) = I_0$



Turn-on snubber

- To limit dI/dt through switch at turn-on
- Turn-off Thyristors (GTO, IGCT) has limited dI/dt capability
- At switch turn-off, stored energy in L_s must be dissipated.
- D_{LS} and R_{LS} forms discharge circuit for the inductor L_s



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