

# TSEA44: Computer hardware – a system on a chip

Lecture 4: The lab system and JPEG encoding

## Agenda

- Array/memory hints
- Cache in a system
  - The effect of cache in combination with accelerator
- Introduce JPEG encoding of images
  - DCT transform
  - Data reduction

## Practical issues

- Forming groups
  - Require pass on lab0
  - Send email to me (to get shared folder access)
  - Try to form groups of 2
    - Groups of 1 to 3 is ok; 3 is ok, 2 is preferred, 1 is ok
    - See exam webpage of course for list of students
    - Each group have their own directory to store files  
/courses/TSEA44/labs/labgrpXX

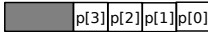
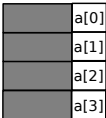
## Practical issues

- Next lecture is an invited lecture from AXIS

## Some tips about arrays/memories

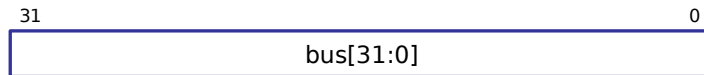
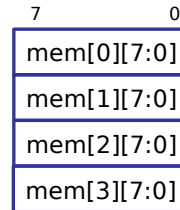
- FPGA memories can be created using
  - Flipflops; asynchronous read, synchronous write
  - Distributed using LUTs; asynchronous read, synchronous write, 16x1 each
  - BRAMs; synchronous read, synchronous write, 512x32, 1024x16 ....
- Memories can be designed
  - Using templates (BRAMs)
  - Inferred (distributed)

## Some tips about arrays/memories

- Usually describe memory as arrays
- Two ways to describe arrays in SystemVerilog
  - Packed, e.g., logic [3:0] p;
    - Guaranteed to be continuous 
    - Typical for samples, values
  - Unpacked, e.g., logic u [3:0];
    - Support other data types 
    - Typical for multiple unit of same type

## Unpacked arrays

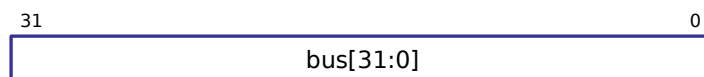
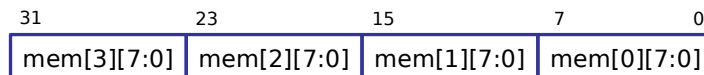
```
wire [31:0] bus;
reg [7:0] mem [0:3]; // a 4-byte memory
...
assign bus[31:24] = mem[3];
```



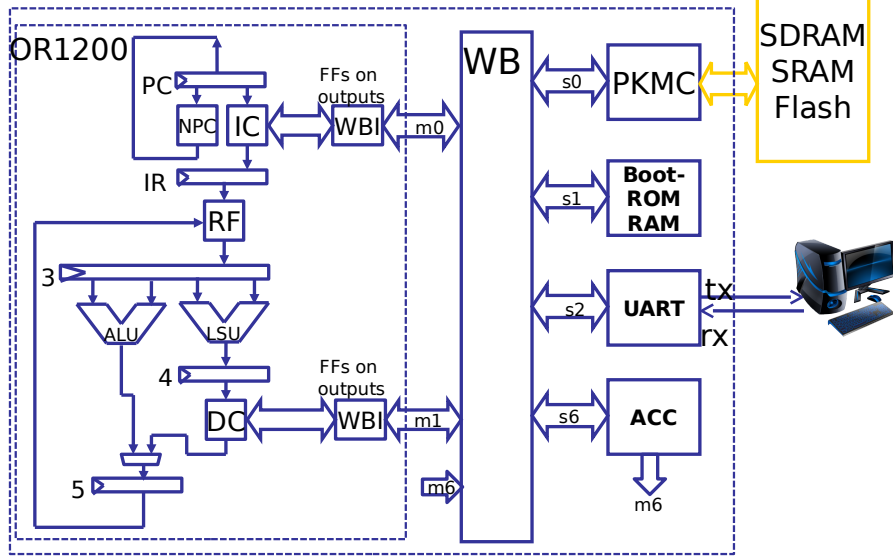
## Packed arrays

```
wire [31:0] bus; // a packed array
reg [3:0][7:0] mem; // so is this
// both are continuous

assign bus = mem;
assign bus[31:16] = mem[3:2];
```



## Our computer system

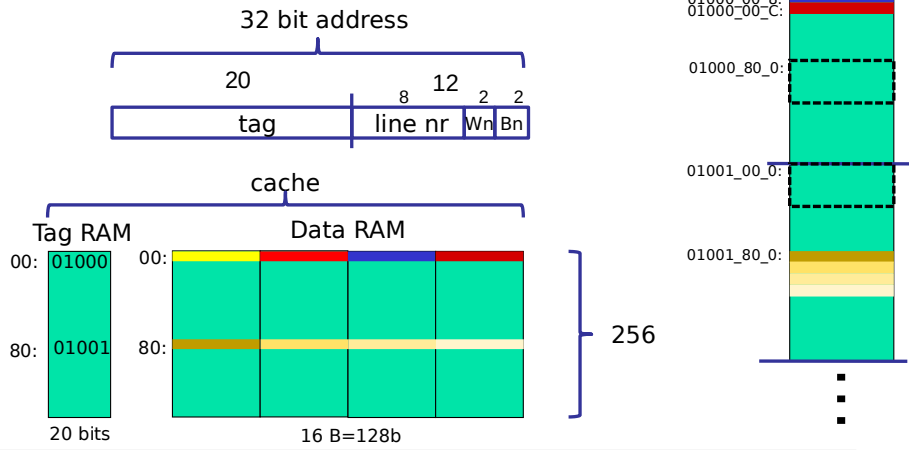


## Caches

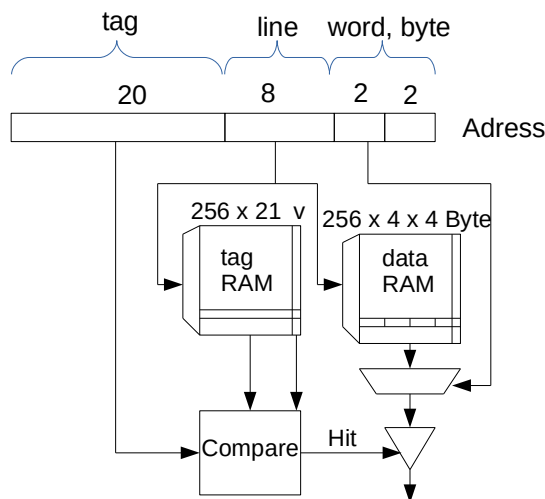
- Essential! Required to get good (close to 1) instructions per clock cycle (IPC)
- Expect to fetch 1 instruction each clock cycle
  - Internal (FPGA ROM/RAM) memory have a latency of 3 clockcycles
  - External (SRAM/SDRAM/FLASH) have a latency of 4 clockcycles
- **Size:** (depending on FPGA) there are up to 120 x 2KB block RAMs
  - => Select 8KB each for IC and DC
- **Type:** direct mapped (or set associative)

# 4 KB cache example (direct mapped)

More than 1 word is fetched on a cache miss  
 A cache line is 4 words = 16 bytes (256x128 bits)

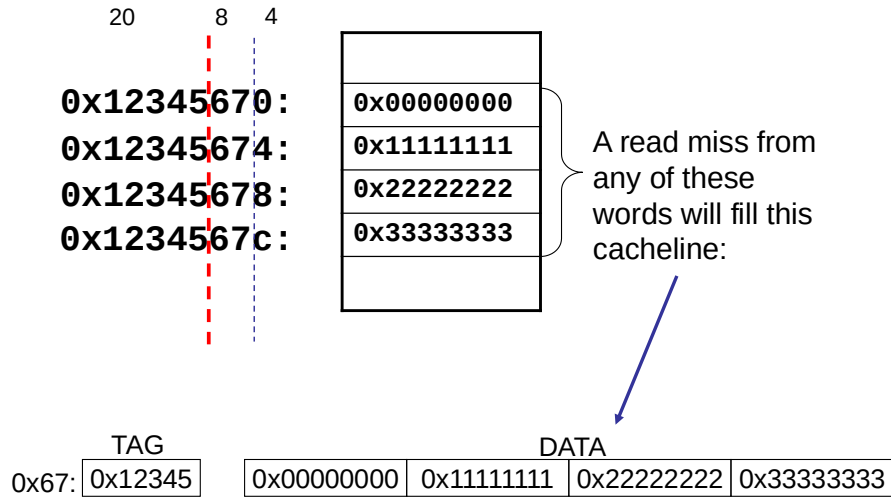


# 4 KB direct mapped cache



v is valid bit: indicate if cache line contains data

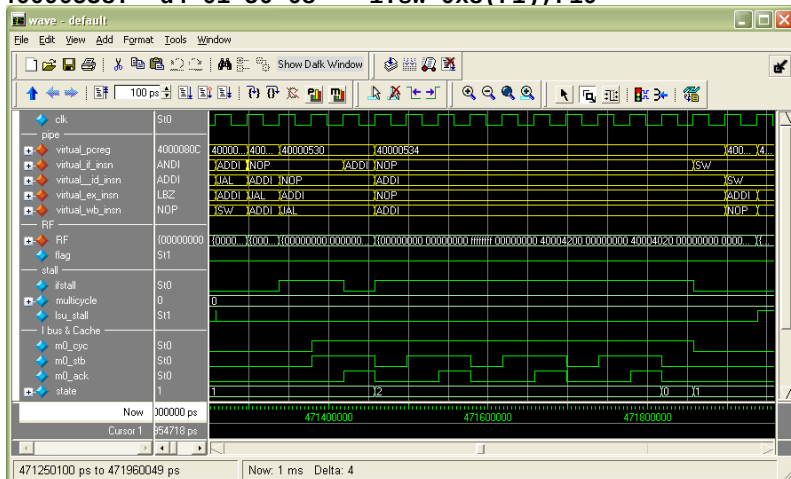
## A closer look at a cacheline



## An IC cache miss

```

40000530: 9c 21 ff e4  l.addi r1,r1,0xffffffffe4
40000534: d4 01 48 04  l.sw 0x4(r1),r9
40000538: d4 01 50 08  l.sw 0x8(r1),r10
    
```



## Cache policy

Cacheline = 4 words = 16 Bytes

### Instruction cache

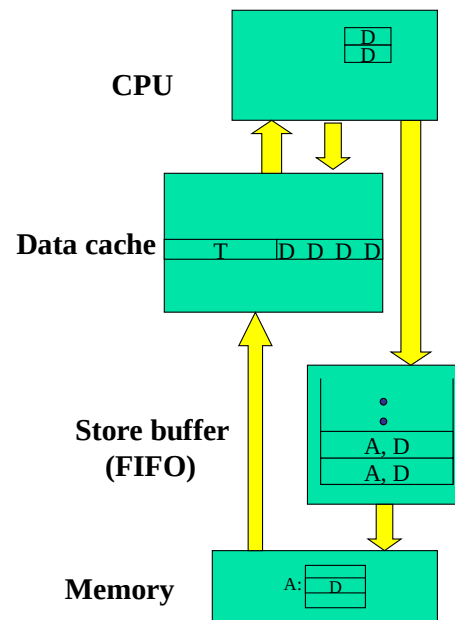
	hit	miss
read	read from cache	fill (replace) cacheline from memory

### Data cache

	hit	miss
read	read from cache	fill (replace) cacheline from memory
write	write to cache write thru to memory	write to memory only

## Or1200 store buffer

- In a write-through data cache is every write equivalent to a cache miss!
- A store (write) buffer is placed between CPU and memory
- Writes are placed in a queue, so that the data cache is available on the next clock cycle

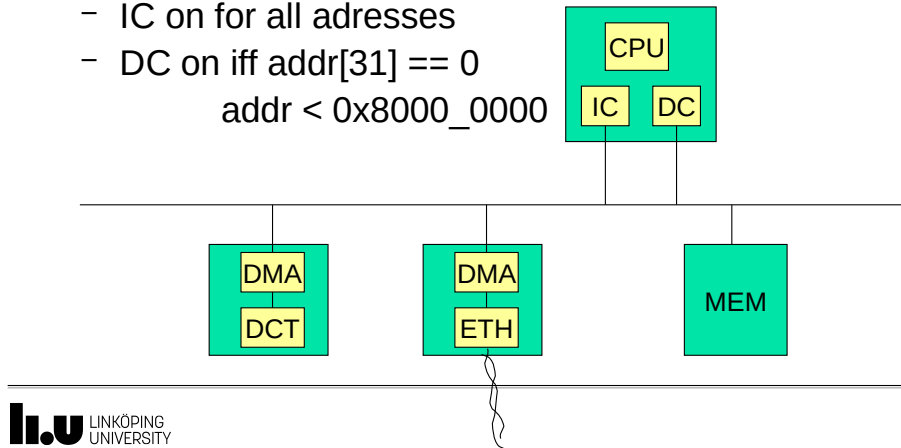




## Watch out!

- Caches can be incoherent when using DMA
  - Write to memory not updating CPU caches
- Parts of memory should be non-cacheable
  - IC on for all addresses
  - DC on iff  $\text{addr}[31] == 0$

$\text{addr} < 0x8000\_0000$



## Accelerator interfacing

- Accelerator should implement functionality that is time-consuming to run on the CPU
- Interfacing the accelerator require additional data moves
- Simplest case (for the processor)
  - CPU send data to accelerator
  - CPU gets data from accelerator
    - Data available immediately, no waiting
    - Usually difficult to implement, processing takes time

## Accelerator interfacing, cont.

- More common case: Accelerator require some time to process data
  - CPU send data to accelerator
  - CPU waits for some time (N clock cycles)
    - No useful work performed by processor
  - CPU gets data from accelerator
  - Worse if time required to wait is unknown
    - Busy wait on the bus: Ask accelerator, but not get a respons for many clock cycles => Stalling CPU, locking bus

## Accelerator interfacing, cont.

- Common for the accelerator to have large amount of data to receive, process, and return
- Simplest approach: Use CPU to feed accelerator with data

Mem->CPU                      Feed data to accelerator, uses CPU  
CPU-> Accelerator

...wait  
Accelerator->CPU              Return data from accelerator, uses CPU  
CPU -> Mem

## Accelerator interfacing, cont.

- Want to reduce load on CPU: let the accelerator do the data moves by itself: DMA! (Direct Memory Access)

CPU setups DMA controller in accelerator (startadress, length)

Mem -> Accelerator    Feed data to accelerator, CPU do other things  
...processing

Accelerator->Mem    Return data from accelerator, CPU do other things

A drawback: Both accelerator and CPU compete for the bus  
Even worse if a number of accelerators work on  
data in sequence (Accelerator1 -> Accelerator2 ->...)

## Accelerator interfacing, cont.

- Stop communication between accelerators from going over the bus
  - Use special memories interconnecting only accelerators
  - Remove bus use (increase availability for the CPU)
  - The memories are unavailable to the CPU

CPU->Accelerator (setup startadress, length etc.)

Mem->Accelerator1

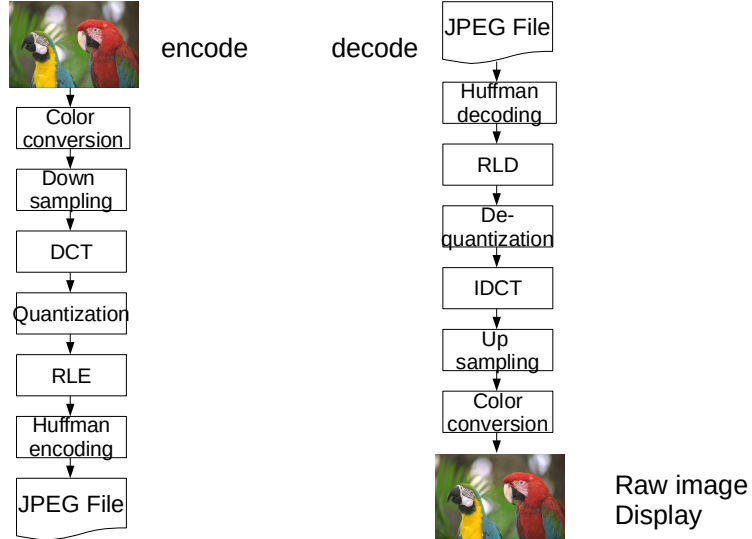
... process in Accelerator1, store result in extra memory

... process in Accelerator2, read input from extra memory

Accelerator2->Mem

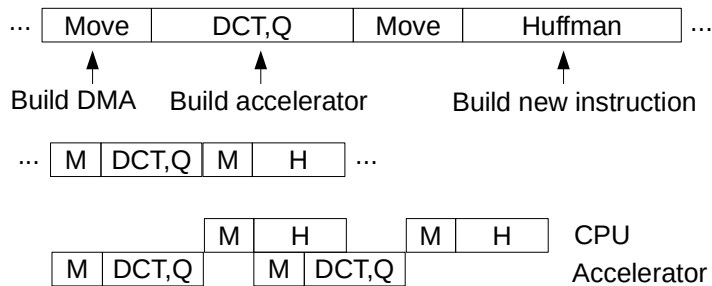


# JPEG Encoding/decoding algorithm



# Problem definition

- JPEG compression of testbild.raw 512x400 pixels
  - JPEG works on 8x8 blocks => 3200 blocks
  - Unaccelerated JPEG takes more than 32 000 000 clock cycles => 1 block takes more than 10 000 clock cycles!



## Color Conversion

$$Y = 0.299 R + 0.587 G + 0.144 B$$

$$Cb = -0.1687 R - 0.3313 G + 0.5 B + 2^{P_s-1}$$

$$Cr = 0.5 R - 0.4187 G - 0.0813 B + 2^{P_s-1}$$



Y



R



Cb



G



Cr



B



Y = luminance  
Cb/Cr = chrominance

## Resampling

Y



Cb



Cr



Data reduction  
50%

## 8-point 1-D DCT/IDCT

$$T(k) = c(k) \sum_{x=0}^7 v(x) \cos\left(\frac{(2x+1)k\pi}{16}\right), \quad k=0\dots7$$

$$v(x) = \sum_{k=0}^7 c(k) T(k) \cos\left(\frac{(2x+1)k\pi}{16}\right), \quad x=0\dots7$$

$$c(0) = \sqrt{\frac{1}{8}}$$

$$c(k) = \frac{1}{2}, \quad k \neq 0$$

$$C(x;k) = \cos\left(\frac{(2x+1)k\pi}{16}\right)$$

↑ coord      ↑ freq

## 8x8-point 2-D DCT/IDCT

$$T(k,l) = c(k,l) \sum_{x=0}^7 \sum_{y=0}^7 v(x,y) C(y;l) C(x;k), \quad k,l=0\dots7$$

$$v(x,y) = \sum_{k=0}^7 \sum_{l=0}^7 c(k,l) T(k,l) C(y;l) C(x;k), \quad x,y=0\dots7$$

$$c(0,0) = \frac{1}{8} \quad k=l=0$$

$$c(k,l) = \frac{1}{4} \quad \text{else}$$

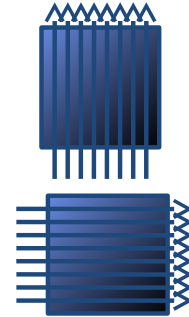
$$C(x;k) = \cos\left(\frac{(2x+1)k\pi}{16}\right)$$

# Simplifications

## 1. Separation in x and y

$$T(k,l) = c(k,l) \sum_{x=0}^7 \left\{ \sum_{y=0}^7 v(x,y) C(y;l) \right\} C(x;k)$$

$$= c(k,l) \sum_{x=0}^7 B(x,l) C(x;k)$$

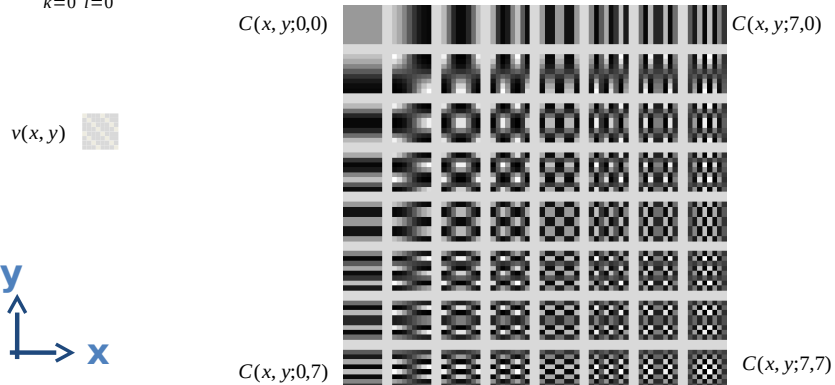


## 2. 1-D DCT can be simplified for N=8

# Meaning of the transform

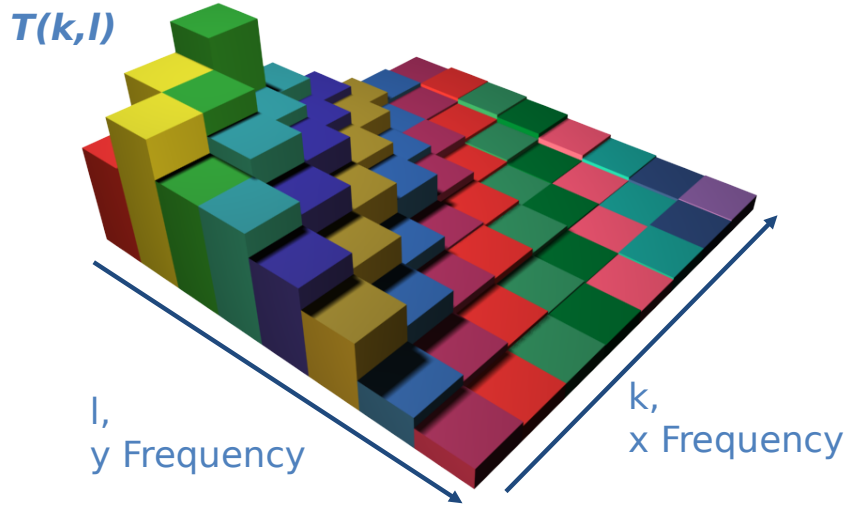
$$v(x,y) = \sum_{k=0}^7 \sum_{l=0}^7 T(k,l) c(k,l) C(y;l) C(x;k) =$$

$$= \sum_{k=0}^7 \sum_{l=0}^7 T(k,l) C(x,y;k,l)$$





# Quantization



# Data Reduction

- Transform, rounded division result  $Y_q = \text{round} ( \text{DCT}_2(Y)/Q_L )$

$$Y = \begin{bmatrix} 162 & 162 & 162 & 161 & 162 & 157 & 163 & 161 \\ 162 & 162 & 162 & 161 & 162 & 157 & 163 & 161 \\ 162 & 162 & 162 & 161 & 162 & 157 & 163 & 161 \\ 162 & 162 & 162 & 161 & 162 & 157 & 163 & 161 \\ 162 & 162 & 162 & 161 & 162 & 157 & 163 & 161 \\ 164 & 164 & 158 & 155 & 161 & 159 & 159 & 160 \\ 160 & 160 & 163 & 158 & 160 & 162 & 159 & 156 \\ 159 & 159 & 155 & 157 & 158 & 159 & 156 & 157 \end{bmatrix}$$

$$\text{DCT}_2(Y) = \begin{bmatrix} 259 & 5 & 3 & 0 & 0 & -1 & -5 & 6 \\ 8 & -1 & 1 & -5 & 2 & 3 & -4 & 3 \\ -5 & 0 & -2 & 2 & -1 & 0 & 2 & -2 \\ 2 & 1 & 2 & 1 & -1 & -1 & 0 & 1 \\ -1 & -1 & 0 & -1 & 2 & 1 & -1 & -1 \\ 1 & 0 & -2 & 0 & -2 & 1 & 2 & 1 \\ -2 & 0 & 3 & 2 & 2 & -2 & -1 & -1 \\ 1 & 0 & -2 & -2 & -1 & 2 & 1 & 1 \end{bmatrix}$$

$$Q_L = \begin{bmatrix} 16 & 11 & 10 & 16 & 24 & 40 & 51 & 61 \\ 12 & 12 & 14 & 19 & 26 & 58 & 60 & 55 \\ 14 & 13 & 16 & 24 & 40 & 57 & 69 & 56 \\ 14 & 17 & 22 & 29 & 51 & 87 & 80 & 62 \\ 18 & 22 & 37 & 56 & 68 & 109 & 103 & 77 \\ 24 & 35 & 55 & 64 & 81 & 104 & 113 & 92 \\ 49 & 64 & 78 & 87 & 103 & 121 & 120 & 101 \\ 72 & 92 & 95 & 98 & 112 & 100 & 103 & 99 \end{bmatrix}$$

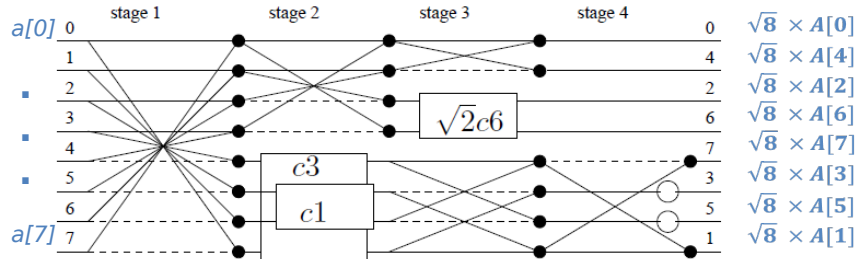
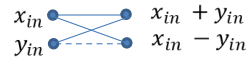
$$Y_q = \begin{bmatrix} 16 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

# Loefflers algorithm (fast DCT)

- 1-D 8-point DCT can be simplified

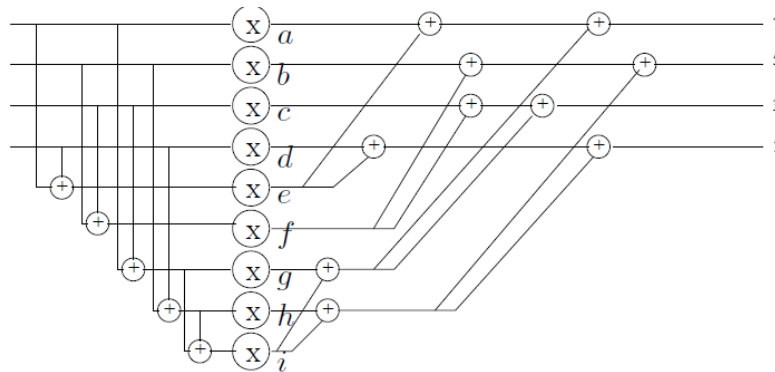
○ => multiplication with  $\sqrt{2}$

$$A[u] = c[u] \cdot \sum_{x=0}^7 a[x] \cos\left(\frac{2\pi}{32}(2x+1)u\right)$$



$$\begin{matrix} x_{in} \\ y_{in} \end{matrix} \rightarrow \boxed{cn} \rightarrow \begin{matrix} x_{out} \\ y_{out} \end{matrix} \Rightarrow \begin{cases} x_{out} = x_{in} \cdot \cos n\pi/16 + y_{in} \cdot \sin n\pi/16 \\ y_{out} = -x_{in} \cdot \sin n\pi/16 + y_{in} \cdot \cos n\pi/16 \end{cases}$$

# Final modification



$$k_3(k_1x + k_2y) = k_3k_1x + k_3k_2y$$

precompute

## RLE = run length encoding, Example:

Raw data: 0 0 0 1 1 1 1 0 0 0 0 1 0

Encoded as: 3:0, 4:1, 4:0, 1:1, 1:0

Alternative (if only zeroes are plentiful):

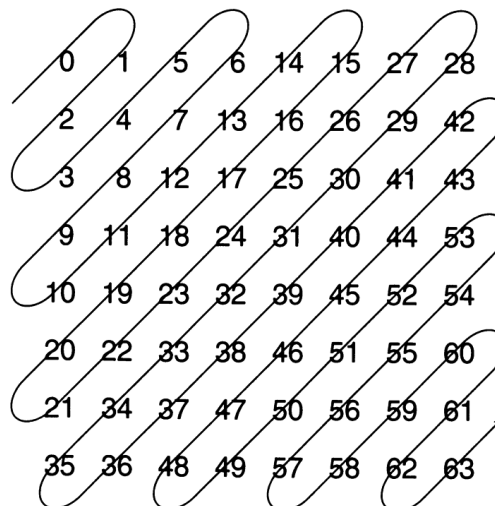
Raw data: 5 0 0 0 7 0 0 9 0 0 0 0 0 0 0

Encoded as: 5:3, 7:2, 9:DONE

Special code

## Zigzag Pattern

- Increase possibility of zeros at the end of the sequence
  - Small energy in highest frequencies



## Magnitude encoding (DC only)

Encoded value	DC Value Range
0	0
1	[-1] [1]
2	[-3, -2] [2, 3]
3	[-7, -4] [4, 7]
4	[-15, -8] [8, 15]
5	[-31, -16] [16, 31]
6	[-63, -32] [32, 63]
7	[-127, -64] [64, 127]
8	[-255, -128] [128, 255]
9	[-511, -256] [256, 511]
10	[-1023, -512] [512, 1023]
11	[-2047, -1024] [1024, 2047]

## An example of RLE

### 1) After Q

22	12	0	-12	0	0	0	0
0	0	-8	0	0	0	0	0
4	0	0	0	0	0	0	0
0	0	0	0	0	0	0	1
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

### 2) After zig-zag

```

22
12
0 4
0 0 -12
-8
0000000000000000
0000000000000000
000000000000001
    
```

### 3) After RLE

```

Value raw bits (amplitude value)
05 10110
04 1100      -12 =>
13  100      12-1, force MSB=0
24  0011      => 0011
04  0111
F0           -8 =>
F0           8-1, force MSB=0
D1          1  => 0111
00
Run of 0:s  Magnitude (number of raw bits)
    
```

### 4) Huffman coding

- Value are HC (variable length) using table lookup
- raw bits are left untouched

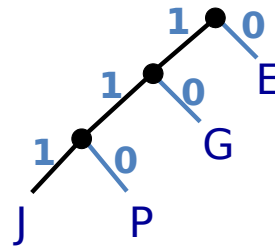
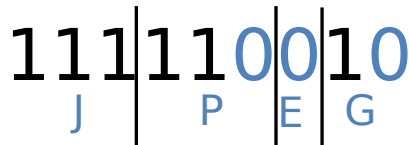
# Huffman encoding/decoding

- Analogy: Morse Code



- Binary codes

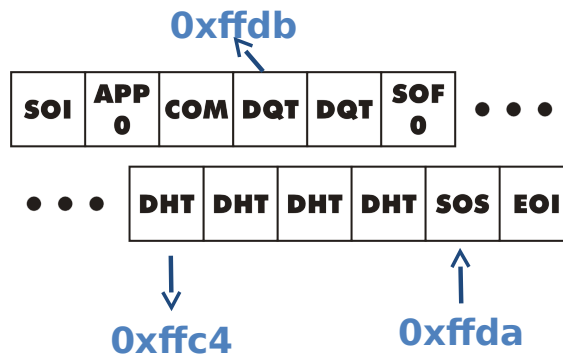
- Mutually exclusive codes
- Binary tree



# JFIF Format

- JPEG File Interchange Format

- Markers
- Data



## Finally

- AC and DC values are treated differently
- Two Huffman LUTs are used
- DC
  - Differential, magnitude encoding, Huffman table lookup
- AC
  - As mentioned, raw bits left untouched, Huffman table lookup
- Example: value 04, raw bits 1100 => ....10111100....

in	code	length
0x00	1010	4
0x01	00	2
0x02	01	2
0x03	100	3
0x04	1011	4
0x05	11010	5
...	...	...

max length=16