

Approximation of elementary functions

TSTE18 Digital Arithmetic Seminar 10

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- ▶ Errors
- ▶ Range reduction
- ▶ Tables
- ▶ (Piecewise) polynomial approximations
- ▶ Bi-/multi-partite tables

- ▶ CORDIC
- ▶ Convergence-based approximation

Errors

- ▶ Consider an approximation $\tilde{f}(X) \approx f(X)$ with an error $\epsilon(X) = \tilde{f}(X) - f(X)$
- ▶ X is a B -bit number, so there are 2^B different inputs to consider
- ▶ Mean error and error variance are interesting statistical measures of the error
- ▶ Different error measures are possible
 - ▶ Maximum absolute error: $\max |\epsilon(X)|$
 - ▶ Mean square error: $\frac{1}{2^B} \sum_X \epsilon(X)^2$
 - ▶ Mean absolute error: $\frac{1}{2^B} \sum_X |\epsilon(X)|$
- ▶ Often we consider the maximum absolute error and state the number of correct fractional bits: $-\log_2 \max |\epsilon(X)|$
- ▶ Different applications may have different requirements
- ▶ A faithfully rounded approximation is correct within one ulp

Range reduction

- ▶ For many functions it is possible to find a modified input which gives a simple relation to the original input and also for the required output
- ▶ Hence, the range of the arguments that must be evaluated can be reduced
- ▶ Examples:
 - ▶ $\sin(X) = \sin(X + 2\pi)$ – Can add/subtract an arbitrary integer multiple of 2π
 - ▶ $\sin(X) = -\sin(-X)$ – Can change sign before evaluation and then again after
 - ▶ For sin, cos, tan it is enough to evaluate arguments between $0 \leq X \leq \pi/2$ (actually $0 \leq X \leq \pi/4$)
 - ▶ $\sqrt{X} = \frac{\sqrt{4X}}{2}$ – enough to evaluate arguments between $k \leq X < 4k$ for some k
 - ▶ $\frac{1}{X} = \frac{1}{2^m X}$ – enough to evaluate arguments between $k \leq X < 2k$ for some k

Range reduction

Tables

- ▶ This procedure is called range reduction
- ▶ Useful for evaluating $\sin(10^{20})$ etc
- ▶ More advanced techniques also available for e.g. \log
- ▶ Note that when reducing 10^{20} to a value between $0 \leq X \leq \pi/2$ a rather large value is required (1.6×10^{19}) to be multiplied 2π
- ▶ An error in π will be amplified 10^{19} times...

- ▶ The simplest way to approximate an arbitrary function is to use a table storing all the required values
- ▶ Table size assuming B input bits and W output bits: $W \times 2^B$ memory bits
- ▶ Approximation error is easily controlled to within 0.5 up by selecting the correct values
- ▶ Becomes very large for long input word lengths

Polynomial approximation

- ▶ An alternative is to use a polynomial to approximate the value
- ▶ The Taylor-series expansion gives a good initial approximation
- ▶ The expansion of $f(X)$ about $X = a$ is

$$f(X) = \sum_{i=0}^{\infty} f^{(i)}(a) \frac{(X-a)^i}{i!} \quad (1)$$

with the error of omitting all terms of degree higher than m is

$$f^{(m+1)}(a + \mu(X-a)) \frac{(X-a)^{m+1}}{(m+1)!} \quad (2)$$

for some $0 < \mu < 1$

Polynomial approximation

- ▶ The expansion of $f(X)$ about $X = 0$ is the Maclaurin-series expansion
- ▶

$$f(X) = \sum_{i=0}^{\infty} f^{(i)}(0) \frac{(X-0)^i}{i!} \quad (3)$$

$$f^{(m+1)}(\mu X) \frac{(X)^{m+1}}{(m+1)!} \quad (4)$$

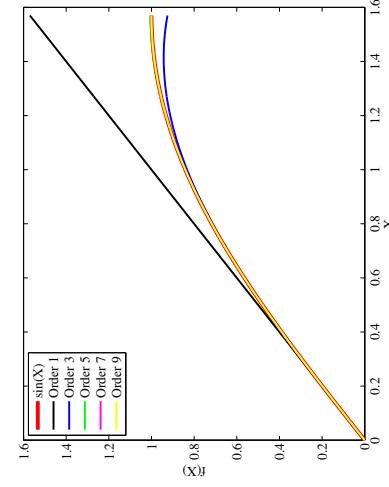
for some $0 < \mu < 1$

Polynomial approximation

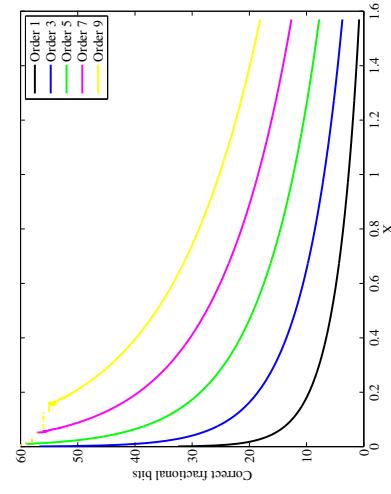
Polynomial approximation

- Consider the function $\sin(X)$ with a Maclaurin expansion as

$$\sin(X) \approx X - \frac{X^3}{3!} + \frac{X^5}{5!} - \frac{X^7}{7!} + \dots \quad (5)$$



- Approximation error/correct fractional bits



Polynomial approximation

Piecewise polynomial approximation

- Possible to use multiple polynomials for different segments
- Simplest way is to divide the range in similarly sized blocks
- Can use MSBs to decide block
- Compute Taylor expansion for $\sin\left(\frac{\pi X}{2}\right)$ about $X = 1/2$ ($\pi/4$ rad)

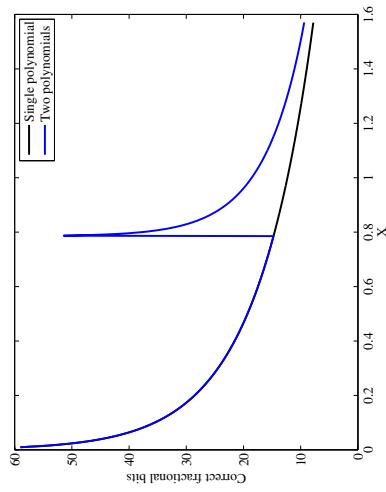
$$\begin{aligned} \tilde{f}(X) &= \frac{\sqrt{2} - \sqrt{2}\pi^2(X - \frac{1}{2})^2}{16} - \frac{\sqrt{2}\pi^3(X - \frac{1}{2})^3}{96} + \\ &\quad \frac{\sqrt{2}\pi^4(X - \frac{1}{2})^4}{768} + \frac{\pi\sqrt{2}(X - \frac{1}{2})}{4} \\ &\approx 0.1794X^4 - 0.8155X^3 + 0.0818X^2 + 1.551X + 0.00196 \end{aligned} \quad (7)$$

- For a fixed-point representation it may make sense to scale the input argument in some cases
- For example, for $\sin(X)$ the input range $0 \leq X \leq \pi/2$ maps badly to the $0 \leq X \leq 1 - 2^{-B}$ range commonly used
- Better to approximate $\sin\left(\frac{\pi X}{2}\right)$

$$\sin\left(\frac{\pi X}{2}\right) \approx \frac{\pi X}{2} - \frac{\pi^3 X^3}{8 \times 3!} + \frac{\pi^5 X^5}{32 \times 5!} - \frac{\pi^7 X^7}{128 \times 7!} + \dots \quad (6)$$

Piecewise polynomial approximation

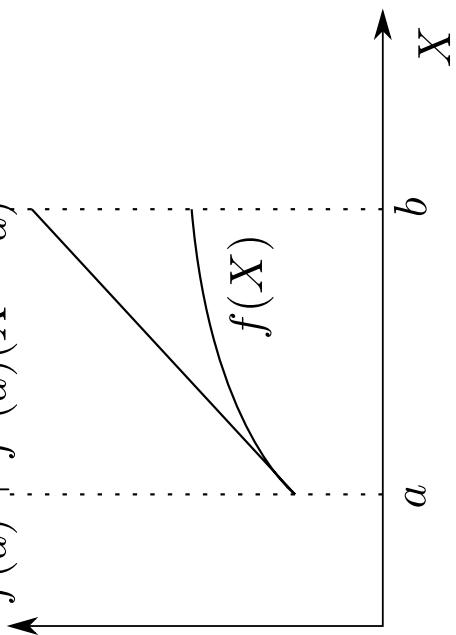
- ▶ Approximation error using two polynomials



Piecewise polynomial approximation

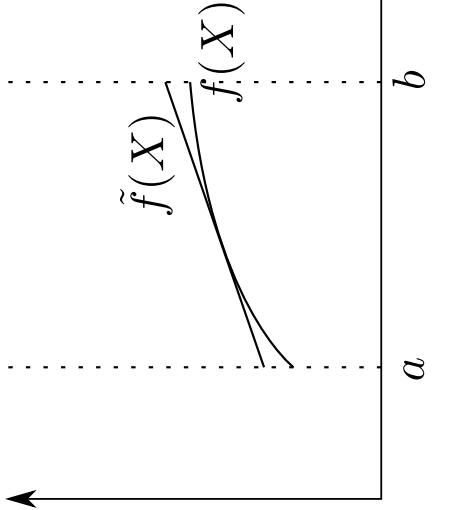
- ▶ Consider a first order approximation of a segment

$$f(a) + f'(a)(X - a)$$



Piecewise polynomial approximation

- ▶ Possible to obtain better approximation expanding around the mid-point

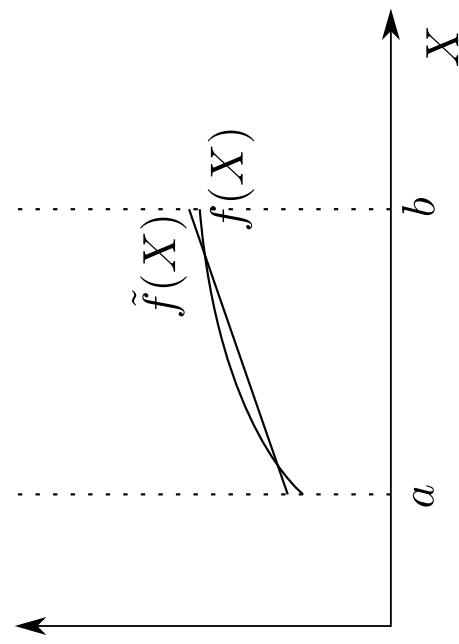


Piecewise polynomial approximation

- ▶ Some observations:
 - ▶ In general there is a trade-off between number of segments (size of coefficients memories) and polynomial order (number of coefficient memories and arithmetic operations)
 - ▶ We have not yet considered finite word length coefficients expanded

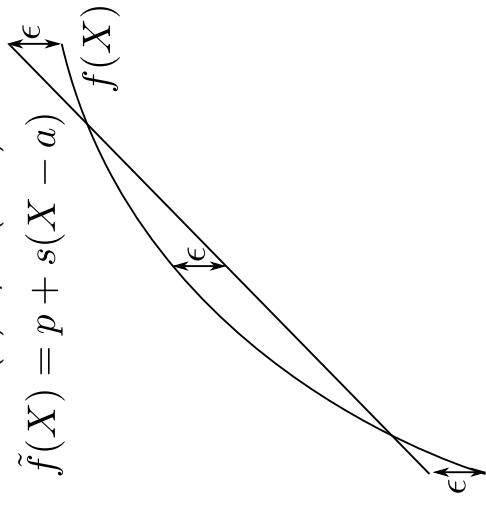
Piecewise polynomial approximation

- Possible to obtain an even better approximation



Piecewise polynomial approximation

- Assume a function $\tilde{f}(X) = p + s(X - a)$



Piecewise polynomial approximation

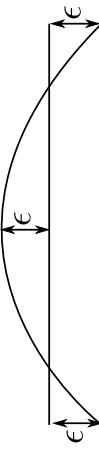
- Using the observation that the errors are the same gives

$$\begin{aligned} f(a) - (p + s(a - a)) &= -\epsilon \\ f(m) - (p + s(m - a)) &= \epsilon \\ f(b) - (p + s(b - a)) &= -\epsilon \end{aligned}$$

$$\begin{bmatrix} 1 & 0 & -1 \\ 1 & m-a & 1 \\ 1 & b-a & -1 \end{bmatrix} \begin{bmatrix} p \\ s \\ \epsilon \end{bmatrix} = \begin{bmatrix} f(a) \\ f(m) \\ f(b) \end{bmatrix} \quad (8)$$

- But where is m ?

- Consider the error function $\epsilon(X) = f(X) - (p + s(X - a))$



- m is where the first derivative of $\epsilon(X)$ is zero

$$f'(m) - s = 0 \quad (9)$$

- Need to determine s
- Slope, s

$$s = \frac{f(b) - f(a)}{b - a} \quad (10)$$

- Solve for m by using $f'(m) = s$

Piecewise polynomial approximation

- Now, since s and m are known

$$\begin{bmatrix} 1 & -1 \\ 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} P \\ \epsilon \end{bmatrix} = \begin{bmatrix} f(a) \\ f(m) - s(m-a) \\ f(b) - s(b-a) \end{bmatrix} \quad (11)$$

- As the first and last row of the matrix are linearly dependent, remove one of them

$$\begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} P \\ \epsilon \end{bmatrix} = \begin{bmatrix} f(a) \\ f(m) - s(m-a) \end{bmatrix} \quad (12)$$

and solve the equation system

$$\begin{bmatrix} P \\ \epsilon \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} f(a) \\ f(m) - s(m-a) \end{bmatrix} \quad (13)$$

$$= \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} f(a) \\ f(m) - s(m-a) \end{bmatrix} \quad (14)$$

Piecewise polynomial approximation

- Possible to find better polynomial coefficients for higher-order polynomials as well
- Example: compute a two-segment linear approximation for $\sin(\frac{\pi X}{2})$ using a Taylor expansion and the method earlier described

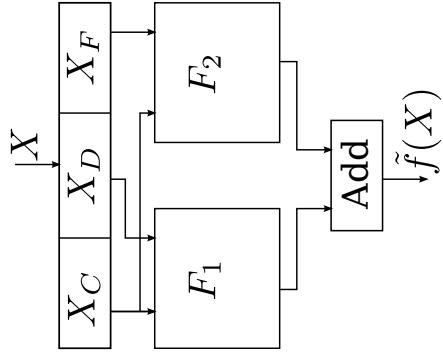
Bi-partite approximation

- Assuming equal partitions, a total of $2^{\frac{B}{3}+1}$ words are required compared to 2^B

- The polynomial schemes use multipliers which may be costly
- Consider $\sin(X)$ where X is split into three different parts

$$X = (X_C X_D X_F)$$

$$\begin{aligned} \sin(X) &= \sin(X_C + X_D + X_F) \\ &= \sin(X_C + X_D) \cdot \cos(X_F) + \cos(X_C + X_D) \cdot \sin(X_F) \\ &= \sin(X_C + X_D) \cdot \cos(X_F) + \cos(X_C) \cdot \cos(X_D) \cdot \sin(X_F) - \\ &\quad \sin(X_C) \cdot \sin(X_D) \cdot \sin(X_F) \\ &\approx \sin(X_C + X_D) + \cos(X_C) \cdot \sin(X_F) \\ &= F_1(X_C, X_D) + F_2(X_C, X_F) \end{aligned}$$

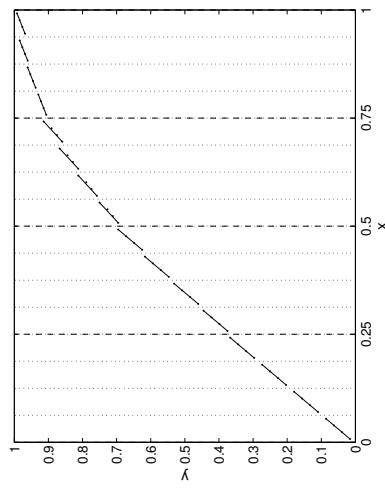


Bi-partite approximation

Bi-partite approximation

Bi-partite approximation

- Can be seen as a piecewise linear approximation where each slope line is tabulated and used in several segments



- In the general case

$$\begin{aligned} F_1(X_C, X_D) &= f(X_C X_D) \\ F_2(X_C, X_F) &= f'(X_C) \cdot X_F \end{aligned}$$

- Can be improved by

- Using the mid-point derivative
- Starting from the mid-point and add/subtract the table value (will also reduce the number of words with a factor 2)
- Split into several tables (multi-partite) corresponding to different derivatives