

# TSEA44: Computer hardware – a system on a chip

Lecture 7: DMA, lab3, testbenches

## Lab reports

- Lab1: Section 3.7.2 is good reading
  - Specifies what to include (code, diagrams, state graphs)
  - Specifies things to discuss in the report
- Same type of section found for the other lab tasks also
- Include all code you have written/modified
  - Assume the reader have access to the original lab setup

## Today

- Hints for documentation
- DMA
- Lab3
- Testbenches

## Creating schematics

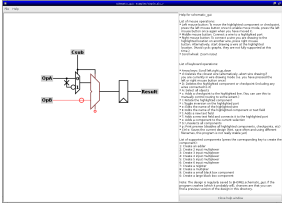
- Alternatives
  - Openoffice/libreoffice diagram tool (I use this for slides)
  - Inkscape (potentially very nice looking, very cumbersome though)
  - Dia (decent if you have RTL library for it)
  - TikZ (if you really like latex)
  - MS Paint (I'm only kidding)
  - Hand drawn schematics from whiteboard/paper
    - Quality problems...
  - Visio (if you have a license for it)

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## schematic\_gui

- Previous examiners (Andreas Ehliar) hobby project
- [http://github.com/ehliar/schematic\\_gui](http://github.com/ehliar/schematic_gui)
  - Tutorial at [https://github.com/ehliar/schematic\\_gui/blob/master/tutorial/tutorial.md](https://github.com/ehliar/schematic_gui/blob/master/tutorial/tutorial.md)
- Accessible also on computers in the lab
 

```
module load TSEA44
schematic_gui
```



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## Array slicing

The size of the part select or slice must be constant, but the position can be variable.

```
logic [31:0] b;
logic [7:0] a1, a2;

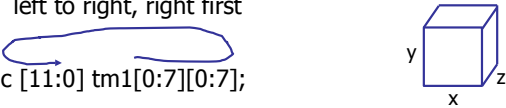
a1 = b[x -: 8]; // OK fixed width
a2 = b[y +: 8]; // OK fixed width
d = b[x:y]; // not OK
```

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## Packed arrays, how to use them

left to right, right first



```
logic [11:0] tm1[0:7][0:7];
logic [0:7][0:7][11:0] tm2;
```

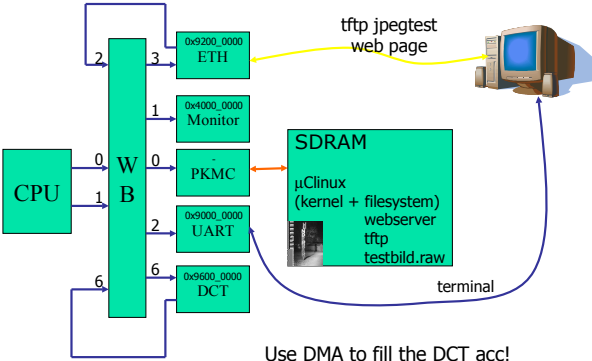
```
tm1[0][0] // DC component
tm2[0][0] // "-"
```

```
tm2[0] // 
tm2[0:7][0] // 
```

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## Lab 3 - DMA



Use DMA to fill the DCT acc!

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### Proposed architecture

- Design FSM
- Change here
- Modify jpegfiles

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### State diagram

The DMA accelerator has to release the bus regularly so that other components can access it. Do it for every line you read. When we finish the first block, we start the DCT accelerator.

Same as WAITREADY except that we go to the IDLE state when done.

The DMA module is not doing anything.

The DMA module is fetching an 8x8 block. Once the block is fetched we go to the WAITREADY state and start the DCT transform.

In this state we wait until the program tells us that it has read the result of the transform by writing to the control register.

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### Address generation

- We want to transfer block by block (8x8)
- Address generator must know format (width, height) of image

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### A measurement: make sim\_jpeg

Copy 16 words from SDRAM to DCT (DMA)

Copy 32 words from DCT to SDRAM

DCT

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### A closer look at the DMA

Release bus for m0, m1, m2  
 ⇒ If CPU is waiting it will get the bus

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### A hint

How long time do these blocks take?

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### DCT => Memory (Software)

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### Burst Read

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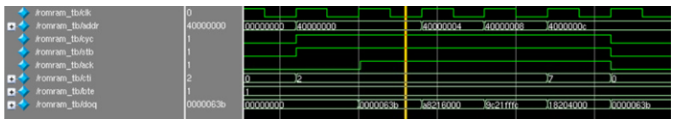
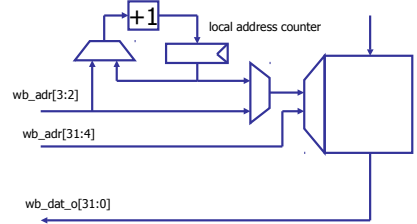
## Burst cycle types


Signal group	Value	Description
cti	000	Classic cycle
	001	Constant address burst cycle
	010	Incrementing burst cycle
	011-110	Reserved
	111	End of burst
bte	00	Linear burst
	01	4-beat wrap burst
	10	8-beat wrap burst
	11	16-beat wrap burst



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## Changes in the slave







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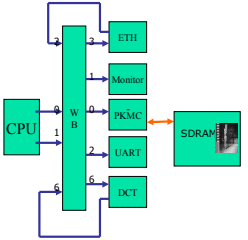
## Burst access

- Note: Only the SRAM memory controller i the Leela memory controller has burst support
  - It is a graphics controller not used in our lab setup



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## Why not write DMA? (acc -> memory)




```

// This the main encoding loop
void encode_image(void)
{
    int i;
    int MCU_count = width*height/DCTSIZE2;
    short MCU_block[DCTSIZE2];

    for(i = 0; i < MCU_count; i++)
    {
        forward_DCT(MCU_block);
        encode_mcu_huff(MCU_block);
    }
}
    
```

- I/O is on 0x90, 0x91, ..., 0x99 other addr to PKMC
- Noncacheable data mem addr >= 0x8000\_0000, SDRAM 0x0, SRAM 0x2000\_0000 or 0xc000\_0000
- MCU\_block must be in noncacheable area
- Skip MCU\_block, let encode\_mcu\_huff read from acc

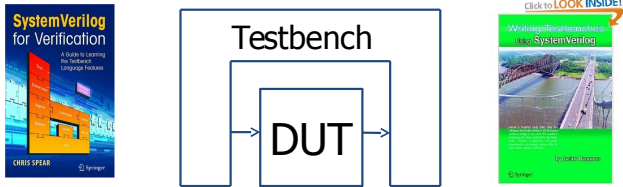
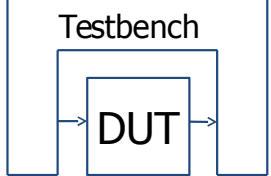


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## Testbenches

Spear,Chris:  
*System Verilog for verification.*  
Springer

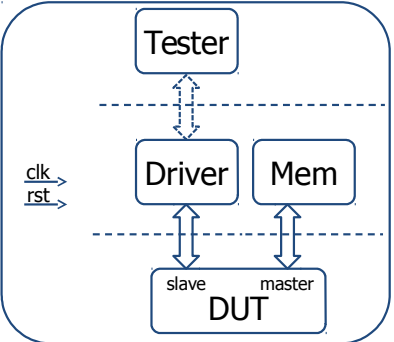
Bergeron,Janick:  
*Writing testbenches using System Verilog.*  
Springer

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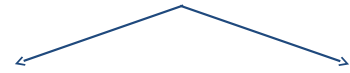
## An example: A TB for your design



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## Testbenches



**Like an FSM (same as DUT)**

- complicated to design
- hard to test timing
- hard to test flow

**Like High-Level Software (very different from DUT)**

- easy to design
- easy to test timing
- easy to test flow

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## Testbench: top level

```

module jpeg_top_tb();
    logic    clk = 1'b0;
    logic    rst = 1'b1;
    wishbone wb(clk,rst), wbm(clk,rst);

    initial begin
        #75 rst = 1'b0;
    end

    always #20 clk = ~clk;

    // Instantiate the tester
    tester tester0();

    // Instantiate the drivers
    wishbone_tasks wb0(.*) ;

    // Instantiate the DUT
    jpeg_top dut(.*) ;
    mem mem0(.*) ;
endmodule // jpeg_top_tb
    
```

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## Testbench: Hi-level tester

```

program tester();
int result = 0;
int d = 32'h01020304;
initial begin
for (int i=0; i<16; i++) begin
jpeg_top_tb.wb0.m_write(32'h96000000 + 4*i, d); // fill immem
d += 32'h04040404;
end
jpeg_top_tb.wb0.m_write(32'h96001000, 32'h01000000); // start ax
while (result != 32'h80000000)
jpeg_top_tb.wb0.m_read(32'h96001000, result); // wait for ax
for (int j=0; j<8; j++) begin
for (int i=0; i<4; i++) begin // print outmem
jpeg_top_tb.wb0.m_read(32'h96000800 + 4*i + j*16, result);
$fwrite(1, "%5d ", result >>> 16);
$fwrite(1, "%5d ", (result << 16) >>> 16);
end
end
end
endprogram // tester
    
```

## DMA? Easy!

```

// Init DMA-engine
jpeg_top_tb.wb0.m_write(32'h96001800, 32'h0);
jpeg_top_tb.wb0.m_write(32'h96001804, ?);
jpeg_top_tb.wb0.m_write(32'h96001808, ?);
jpeg_top_tb.wb0.m_write(32'h9600180c, ?);
jpeg_top_tb.wb0.m_write(32'h96001810, ?); // start DMA engine

for (int blocky=0; blocky< HEIGHT; blocky++) begin
for (int blockx=0; blockx< WIDTH; blockx++) begin
// Wait for DCTDMA to fill the DCT accelerator
result = 0;
while (?) // wait for block to finish
jpeg_top_tb.wb0.m_read(32'h96001810, result);
$display("blocky=%5d blockx=%5d", blocky, blockx);
for (int j=0; j<8; j++) begin
for (int i=0; i<4; i++) begin
jpeg_top_tb.wb0.m_read(32'h96000800 + 4*i + j*16, result);
$fwrite(1, "%5d ", result >>> 16);
$fwrite(1, "%5d ", (result << 16) >>> 16);
end
end
$fwrite(1, "\n");
jpeg_top_tb.wb0.m_write(?); // start next block
end
end
    
```

## Testbench: mem

```

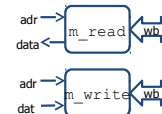
module mem(wishbone.slave wbm);
logic [7:0] rom[0:2047];
logic [1:0] state;
logic [8:0] adr;
integer blockx, blocky, x, y, i;
initial begin
// A test image, same as dma_dct_hw.c
for (blockx=0; blockx< HEIGHT; blocky++)
for (blockx=0; blockx< WIDTH; blocky++)
for (i=1, y=0; y<8; y++)
for (x=0; x<8; x++)
rom[blockx*8+x+(blocky*8*y)*PITCH] = i++; // these are not wishbone cycles
end
assign wbm.err = 1'b0;
assign wbm.rty = 1'b0;
always_ff @(posedge wbm.clk)
if (wbm.rst)
state <= 2'h0;
else
case (state)
2'h0: if (wbm.stb) state <= 2'h1;
2'h1: state <= 2'h2;
2'h2: state <= 2'h0;
endcase
assign wbm.ack = state[1];
always_ff @(posedge wbm.clk)
adr <= wbm.adr[8:0];
assign wbm.dat_i = {rom[adr], rom[adr+1],
rom[adr+2], rom[adr+3]};
endmodule // mem
    
```

## wishbone\_tasks.vv

- May/may not consume time
- May/not be synthesizable
- Do not contain **always/initial**
- Do not return values. Pass via output

```

module wishbone_tasks(wishbone.master wb);
int result = 0;
reg oldack;
reg [31:0] olddat;
always_ff @(posedge wb.clk) begin
oldack <= wb.ack;
olddat <= wb.dat_i;
end
    
```



```

// *****
task m_read(input [31:0] adr,
output logic [31:0] data);
begin
@(posedge wb.clk);
wb.adr <= adr;
wb.stb <= 1'b1;
wb.we <= 1'b0;
wb.cyc <= 1'b1;
wb.sel <= 4'hf;
@(posedge wb.clk);
#1;
while (!oldack) begin
@(posedge wb.clk);
#1;
end
wb.stb <= 1'b0;
wb.we <= 1'b0;
wb.cyc <= 1'b0;
wb.sel <= 4'h0;
data = olddat;
end
endtask // m_read
// *****
task m_write(input [31:0] adr,
input [31:0] dat);
// similar to m_read
endtask // m_write
endmodule // wishbone_tasks
    
```

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### Race conditions

Threads executing in parallel in no particular order

```

always_ff @(posedge clk) begin
    b <= a;
end

always_ff @(posedge clk) begin
    c <= b;
end
    
```

Δ cycles

b <sup>+</sup> = a	b = b <sup>+</sup>
c <sup>+</sup> = b	c = c <sup>+</sup>

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### Hm...

```

TB
initial begin
    @(posedge clk);
    stb <= 1;
end

@(posedge clk);
while (ack == 0)
    @(posedge clk);
stb <= 0;
end

DUT
always_ff @(posedge clk)
case (ack)
0: if (stb)
    ack <= 1;
1: ack <= 0;
endcase;
    
```

Nonblocking assignment (<=) => no race condition  
 Blocking assignment (=) => race condition

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### Race conditions

```

always_ff @(posedge clk) begin
    count = count + 1;
end

always_ff @(posedge clk) begin
    $write("count=%d\n", count);
end

always_ff @(posedge clk) begin
    count <= count + 1;
end

always_ff @(posedge clk) begin
    $write("count=%d\n", count);
end
    
```

Δ cycles

count = count + 1	count <sup>+</sup> = count + 1	count = count <sup>+</sup>
print count	print count	

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### program block

- Purpose: Identifies verification code
- A program is different from a module
  - Only initial blocks allowed
  - Executes last
  - (module -> clocking/assertions -> program)
  - No race situation in previous example!

**The Program block functions pretty much like a C program  
 Testbenches are more like software than hardware**

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### Hm... TB (program) DUT (module)

```

@ (posedge clk);
stb <= 1;

@ (posedge clk);
#1;
while (oldack == 0) begin
@ (posedge clk);
#1;
end
stb <= 0;
    
```

```

always_ff @ (posedge clk)
case (ack)
0: if (stb) ack <= 1;
1: ack <= 0;
endcase;
    
```

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### Clocking block

```

interface wishbone(input clk,rst);
wire stb,ack;

clocking cb @ (posedge clk);
input ack;
output stb;
endclocking // cb

modport tb (clocking cb,
input clk,rst);

endinterface // wishbone
    
```

```

module tb();
logic clk = 1'b0;
logic rst = 1'b1;

// instantiate a WB
wishbone wb (clk,rst);

initial begin
#75 rst = 1'b0;
end

always #20 clk = ~clk;

// Instantiate the DUT
jpeg_top dut(.);

// Instantiate the tester
tester tester0(.);
mem mem0(.);
endmodule // jpeg_top_tb
    
```

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### Clocking block

SystemVerilog adds the clocking block that identifies clock signals, and capture the timing and synchronization requirements of the blocks being modeled.

A clocking block assembles signals that are synchronous to a particular clock, and makes their timing explicit.

The clocking block is a key element in cycle-based methodology, which enables users to write testbenches at a higher level of abstraction. Rather than focusing on signals and transitions in time, the test can be defined in terms of cycles and transactions.

Possible to simulate setup and hold time

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### Clocking block

```

program tester(wishbone.tb wb);
...
initial begin
for (int i=0; i<3; i++) begin
wb.cb.stb <= 0;
##1;
wb.cb.stb <= 1;
while (wb.cb.ack==0)
##1;
end
endprogram // tester
    
```

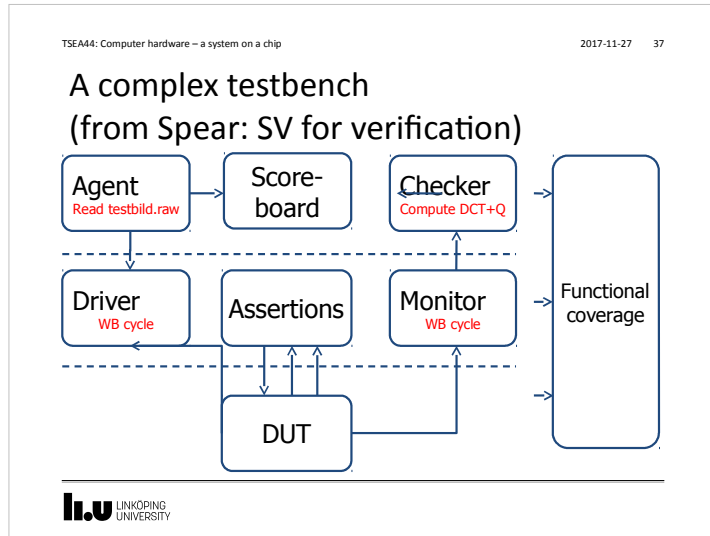
```

module jpeg_top(wishbone wb);
reg state;

assign wb.ack = state;

always_ff @ (posedge wb.clk)
if (wb.rst)
state <= 1'b0;
else if (state)
state <= 1'b0;
else if (wb.stb)
state <= 1'b1;
endmodule // jpeg_top
    
```

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### OOP

```

program class_t;

class packet;
// members in class
integer size;
integer payload [];
integer i;
// Constructor
function new (integer size);
begin
    this.size = size;
    payload = new[size];
    for (i=0; i < this.size; i++)
        payload[i] = $random();
    end
endfunction
// Task in class (object method)
task print ();
begin
    $write("Payload : ");
    for (i=0; i < size; i++)
        $write("%x ",payload[i]);
    $write("\n");
    end
endtask

// Function in class (object method)
function integer get_size();
begin
    get_size = this.size;
end
endfunction
endclass

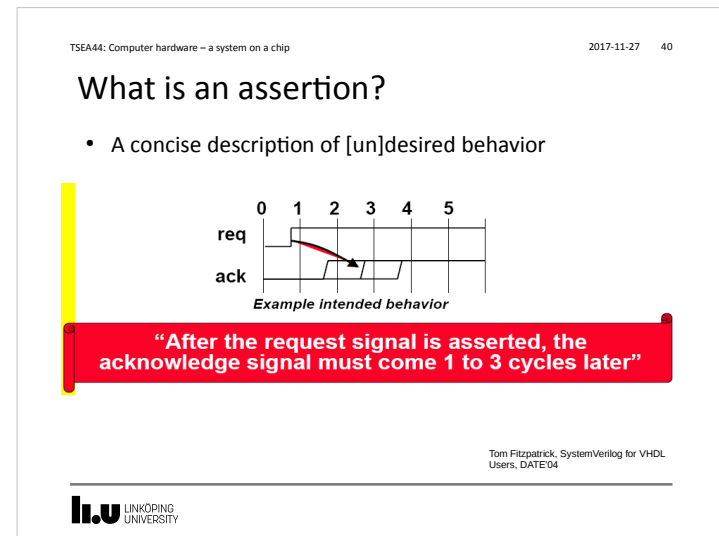
packet pkt;

initial begin
    pkt = new(5);
    pkt.print();
    $display ("Size of packet %0d",
        pkt.get_size());
end

endprogram
    
```

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- ### Object Oriented Programming
- SV includes OOP
  - Classes can be defined
    - Inside a program
    - Inside a module
    - Stand alone
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### Assertions

Example intended behavior

**SVA Assertion**

```
property req_ack;
@ (posedge clk) req ##[1:3] $rose(ack);
endproperty
as_req_ack: assert property (req_ack);
```

**VHDL**

```
sample_inputs : process (clk)
begin
if rising_edge(clk) then
STROBE_REQ <= REQ;
STROBE_ACK <= ACK;
end if;
end process;
protocol: process
variable cycle_cnt : Natural;
begin
loop
wait until rising_edge(CLK);
exit when (STROBE_REQ = '0') and (REQ = '1');
end loop;
cycle_cnt := 0;
loop
wait until rising_edge(CLK);
cycle_cnt := cycle_cnt + 1;
exit when ((STROBE_ACK = '0') and (ACK = '1')) or (cycle_cnt = 3);
end loop;
if ((STROBE_ACK = '0') and (ACK = '1')) then
report "Assertion failure" severity Error;
else
report "Assertion success" severity Note;
end if;
end process protocol;
```

Tom Fitzpatrick, SystemVerilog for VHDL Users, DATE04

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### Sequential regular expressions

- Describing a sequence of events
- Sequences of Boolean expressions can be described with a specified time step in-between
- ##N delay operator
- [\*N] repetition operator

```
sequence s1;
@ (posedge clk) a ##1 b ##4 c ##[1:5] z;
endsequence
```

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### Assertions

- Assertions are built of
  - Boolean expressions
  - Sequences
  - Properties
  - Assertion directives

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### Properties

- Declare property by name
- Formal parameters to enable property reuse
- Top level operators
  - not desired/undesired
  - disable iff reset
  - |->, |=> implication

```
property p1;
disable iff (rst)
x |-> s1;
endproperty
```

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## Assertion Directives

- `assert` – checks that the property is never violated
  - `cover` – tracks all occurrences of property
- a1: `assert p1 else $display("grr");`

```
property s2a;
  @(posedge clk) disable iff (rst)
    $rose(stb) |-> ##[0:16] $rose(ack);
endproperty

a_s2a:assert property (s2a) else
  $display(" (%0t) (%m) Delayed ack on addr %h",
    $time, adr);
```

## Coverage

```
// DUT With Coverage
module simple_coverage();

  logic [7:0] addr;
  logic [7:0] data;
  logic par;
  logic rw;
  logic en;

  // Coverage Group
  covergroup memory @ (posedge en);
    address : coverpoint addr {
      bins low = {0,50};
      bins med = {51,150};
      bins high = {151,255};
    }
    parity : coverpoint par {
      bins even = {0};
      bins odd = {1};
    }
    read_write : coverpoint rw {
      bins read = {0};
      bins write = {1};
    }
  endgroup

  // Task to drive values
  task drive (input [7:0] a, input [7:0] d,
    input r);
    #5 en <= 1;
    addr <= a;
    rw <= r;
    data <= d;
    par <= ^d;
    $display ("%2tns Address :%d data %x,
      rw %x, parity %x",
      $time,a,d,r, ^d);
  endtask

  #5 en <= 0;
  rw <= 0;
  data <= 0;
  par <= 0;
  addr <= 0;
  rw <= 0;
endtask

// Testvector generation
initial begin
  en = 0;
  repeat (10) begin
    drive ($random,$random,$random);
  end
  #10 $finish;
end
endmodule
```

## Coverage

- *Code coverage (code profiling)*
  - reflects how thorough the HDL code was exercised
- *Functional Coverage (histogram binning)*
  - perceives the design from a user's or a system point of view
  - Have you covered all of your typical scenarios?
  - Error cases? Corner cases? Protocols?
- Functional coverage also allows relationships,
  - "OK, I've covered every state in my state machine, but did I ever have an interrupt at the same time? When the input buffer was full, did I have all types of packets injected? Did I ever inject two erroneous packets in a row?"

## Report

```
# @ 5ns Address : 36 data 81, rw 1, parity 0
# @ 15ns Address : 99 data 0d, rw 1, parity 1
# @ 25ns Address : 101 data 12, rw 1, parity 0
# @ 35ns Address : 13 data 7c, rw 1, parity 1
# @ 45ns Address : 237 data 8c, rw 1, parity 1
# @ COVERGROUP COVERAGE: rw 0, parity 0
# @ 65ns Address : 229 data 77, rw 0, parity 0
# @ Covergroups : 143 data f2, rw 0, parity 1
```

ModelSim says:

	Metric At Least	Goal/ Status
TYPE /simple_coverage/memory	44.4%	100 Uncovered
Coverpoint memory::address	33.3%	100 Uncovered
covered/total bins:	1	3
bin low	9	1 Covered
bin med	0	1 ZERO
bin high	0	1 ZERO
Coverpoint memory::parity	50.0%	100 Uncovered
covered/total bins:	1	2
bin even	9	1 Covered
bin odd	0	1 ZERO
Coverpoint memory::read_write	50.0%	100 Uncovered
covered/total bins:	1	2
bin read	9	1 Covered
bin write	0	1 ZERO

Report generator:

TOTAL COVERGROUP COVERAGE: 44.4% COVERGROUP TYPES: 1

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### Cross coverage


```

enum { red, green, blue } color;
bit [3:0] pixel_adr;

covergroup g1 @(posedge clk);
  c: coverpoint color;
  a: coverpoint pixel_adr;
  AxC: cross color, pixel_adr;
endgroup;
    
```

Sample event  
3 bins for color  
16 bins for pixel  
48 (=16 \* 3) cross products

Tom Fitzpatrick, SystemVerilog for VHDL Users, DATE04



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### Constrained randomization

```

program rc;

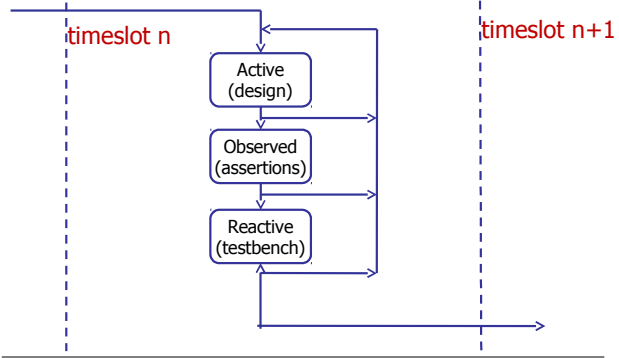
class Bus;
  rand bit[31:0] addr;
  rand bit[31:0] data;
  constraint word_align {addr[1:0] == 2'b0;
                        addr[31:24] == 8'h99;}
endclass // Bus

initial begin
  Bus bus = new;
  repeat (50) begin
    if ( bus.randomize() == 1 )
      $display ("addr = 0x%h data = 0x%h\n",
              bus.addr, bus.data);
    else
      $display ("Randomization failed.\n");
  end
end
endprogram // rc
    
```



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### SV enhanced scheduling




timeslot n

timeslot n+1

Active (design)

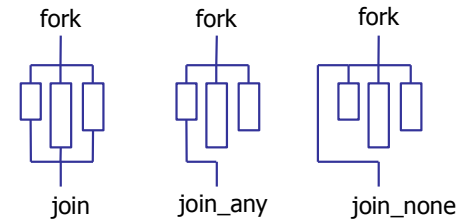
Observed (assertions)

Reactive (testbench)



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### Parallel threads



fork


fork

fork

join

join\_any

join\_none



## An example-sketch

- WB arbitration test
  - Instantiate 4 wishbone\_tasks

```

program tester2();
...
initial begin
...
  fork
    begin // 2
      for (int i; i<100; i++)
        jpeg_top_tb.wb2_m_write(32'h100, 32'h0);
      end
    ...
    begin // 6
      for (int i; i<100; i++)
        jpeg_top_tb.wb6_m_write(32'h20000000, result);
      end
    ...
  join
...
end
endprogram

```

