

TSTE19 Power Electronics

Lecture 1

Tomas Jonsson

ICS/ISY

Tomas Jonsson

- Education
 - M. Sc. degree in Electrical Engineering from the Lund Institute of Technology, 1987
- Work Experience
 - Master thesis work at ABB HVDC Ludvika
 - ABB AB, Sweden since 1988.
 - HVDC control system design, Ludvika (1988 – 1992)
 - HVDC commissioning engineer, New Zealand HVDC project (1992-1993)
 - HVDC system development engineer, Ludvika (1993 – 1996)
 - HVDC system development manager, Ludvika (1997 – 1998)
 - Brazil-Argentina HVDC interconnection project (1998)
 - ABB Corporate Research HVDC & FACTS development projects, Västerås (1999-2009)
 - ABB Grid Systems, R&D project manager, including mentoring of R&D group in Chennai India
 - Since 2013, Senior Principal Engineer in the area of high power converters for power transmission at ABB Grid Systems.



HVDC Transmission Technologies

HVDC Classic, line commutated converters



- Power control
- Terminals demand reactive power
- Reactive power balance by shunt bank switching
- Minimum system short circuit capacity of twice rated power

Capacitor Commutated Converters (CCC)



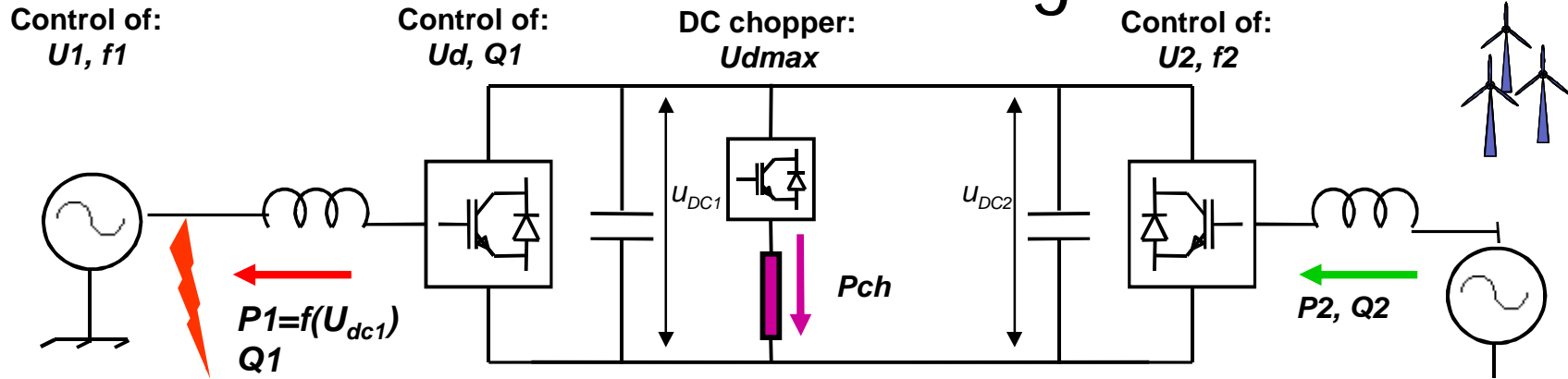
- Power control
- Weak systems, long cables
- Reactive power from series capacitor
- Minimum system short circuit capacity of rated power

HVDC Light[®] , *forced commutated converters (VSC)*

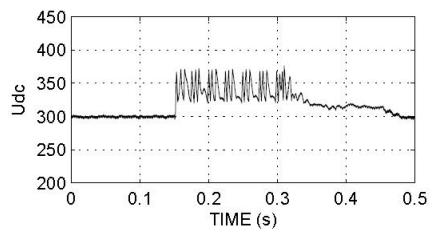
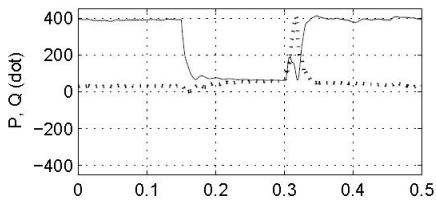
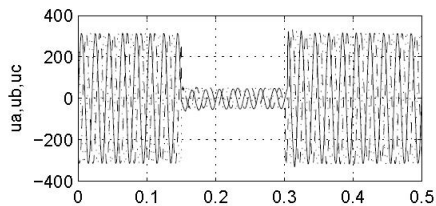


- Real and Reactive Power control
- Dynamic voltage regulation
- Modular and expandable
- Black start capability
- No short circuit restriction

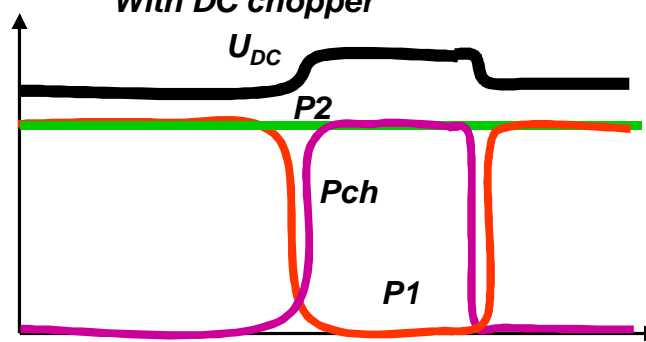
Example of HVDC control task: Fault ride through



On-shore

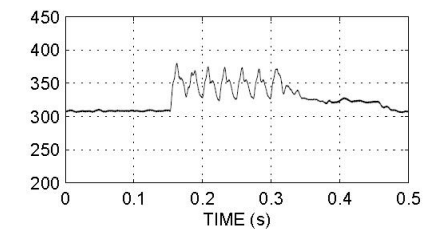
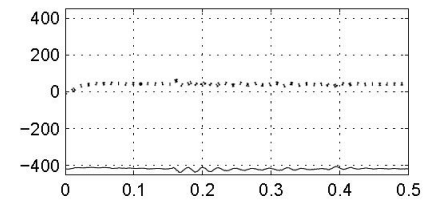
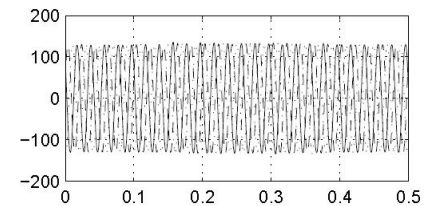


With DC chopper



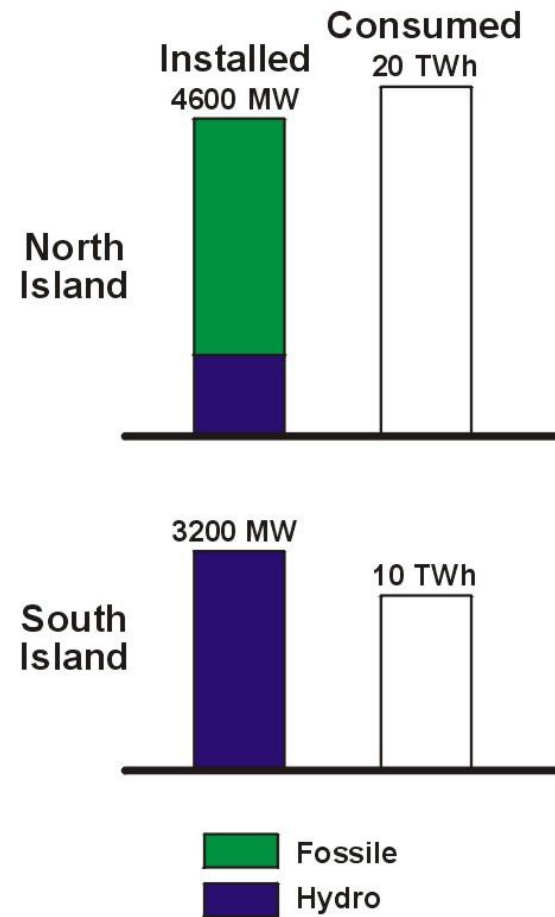
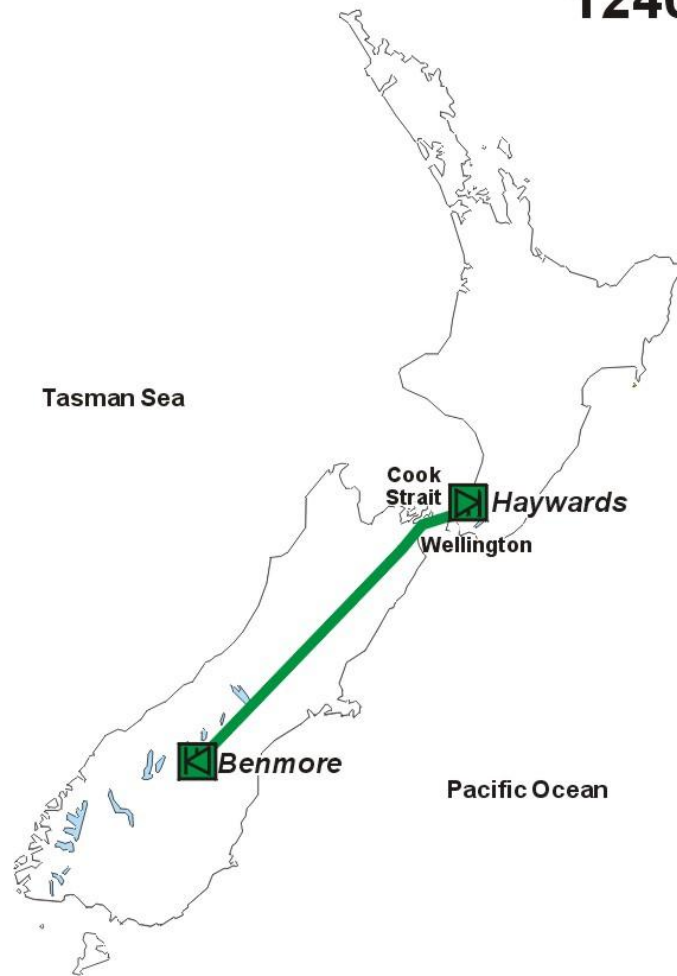
- DC-chopper decouples windpark from on-shore grid
- Minimum impact on wind production during on-shore grid faults

Off-shore



DC hybrid link, New Zealand, 1240 MW

New Zealand 1240 MW



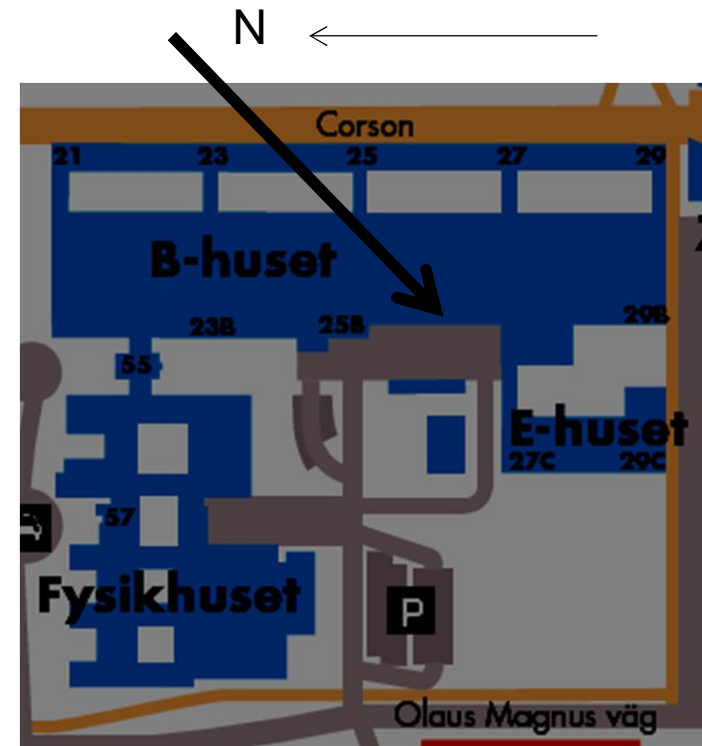
Course staff

Lectures

- Tomas Jonsson
- 013 28 17 21
- tomas.u.jonsson@liu.se
- Office 3D:513
(2nd floor, between entrance 25 & 27)

Lab's

- Martin Nielsen Lönn

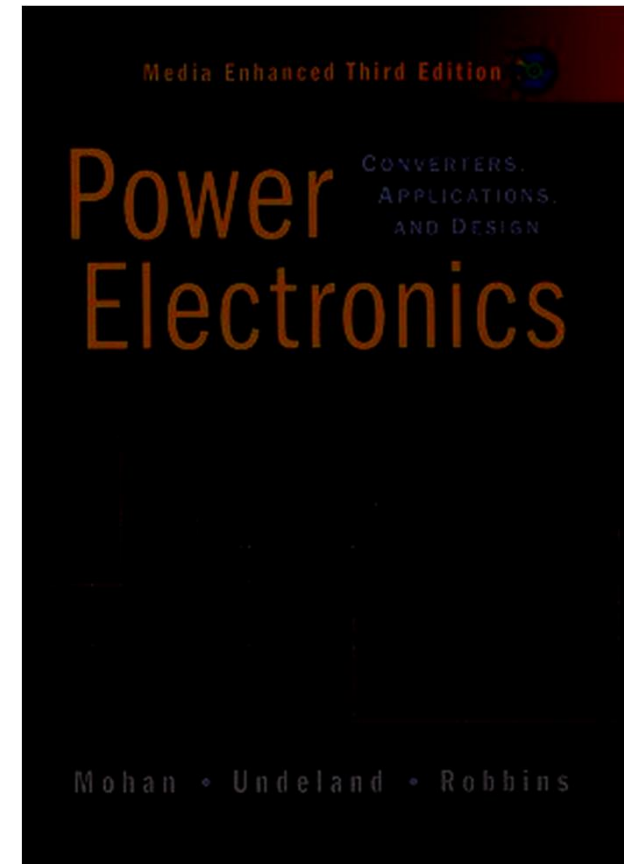


Course Contents

- Course web page
<http://www.isy.liu.se/edu/kurs/TSTE19/>
- 16 Lectures (incl exercises)
 - Introduce and explain material
 - Problem solving
 - Lab preparation
- 3 labs
 - Lab 1 & 2: Multisim simulation of power circuits
 - Lab 3: Control & measurements on power circuit
 - Lab notes will be available on course web page

Literature

- Power Electronics:
Converters, Applications, and Design,
3rd Edition
- N. Mohan, T. M. Undeland, W. P. Robbins
- ISBN: 978-0-471-22693-2
- Wiley & sons., Inc. 2003
- Will sometimes indicate
corresponding Swedish term in {}



Lecture plan part 1

Date	Room	Number	Content
Tue 3/11 13-15	R34	1	Course introduction "Energy conversion through power electronics" an overview of applications. Power electronic systems [1], Circuit theory [3-2]
Wed 4/11 10-12	R35	2	Diode rectifier, part 1: Diode semiconductor theory [19,20], operation [5.2], harmonics
Tue 10/11 13-15	R26	3	Diode rectifier, part 2: Commutation [5.3], reactive power [3.2], circuit simulation [4]
Wed 11/11 10-12	R42	4	Phase controlled converter: Thyristor semiconductor theory [23], thyristor converter operation [6.2 – 6.4]
Mon 16/11 8-10	R18	5	Power semiconductor devices and rating: Semiconductor switches (MOSFET, IGBT, GTO) [21-22, 24-26], data sheet, rating, cooling [29]
Wed 18/11 10-12	R35	6	DC/DC converter, part 1: Switch-mode power supply [10], step-down [7.3], step-up [7.4]
Tue 24/11 13-15	R35	7	DC/AC inverter, part 1: Half-bridge [8.3], commutation, PWM [8.2]
Wed 25/11 10-12	R34	8	DC/AC inverter, part 2: Full-bridge [8.3], harmonics

Lecture plan part 2

Date	Room	Number	Content
Tue 1/12 13-15	R36	9	DC/AC inverter, part 3: Blanking time [8.5], gate control [28]
Wed 2/12 10-12	R37	10	Design review of full-bridge circuit for Lab3: Principles, component selection, control
Tue 8/12 13-15	R18	11	Control & protection: Current control modes [8-6], snubbers [27], short circuit
Wed 9/12 10-12	R23	12	DC/AC – AC/DC: Rectifier vs. inverter operation [8.7], 3-phase converter [8.4]
Tue 15/12 13-15	R19	13	Switch-mode DC/DC converter, part 2: Buck-boost, converters with isolation [10-4], resonant converters
Wed 16/12 10-12	R22	14	Utility applications [17]: HVDC, TCR, TSC, STATCOM
Mon 21/12 8-12	P30	15	Motor drive applications [12-13]: Induction motors [14]
Tue 22/12 13-15	P18	16	Preparation for exam

Lab schedule

Date	Room	Number	Content
Thu 19/11 17-21	Freja	1	Computer lab on diode bridge rectifier, phase controlled converter
Thu 3/12 17-21	Freja	2	Computer lab on VSC full-bridge Inverter, dc/dc buck
Thu 10/12 17-21	Transistorn	3	Measurement lab on VSC full-bridge inverter
Tue 15/12 17-21	Transistorn	1-3	Spare. Opportunity to complete any of Labs 1-3

Lab3: Full-bridge PWM inverter

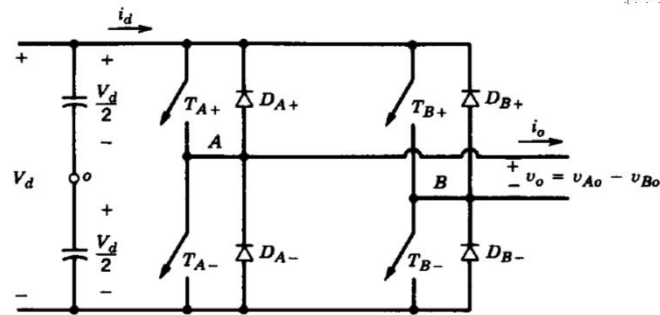
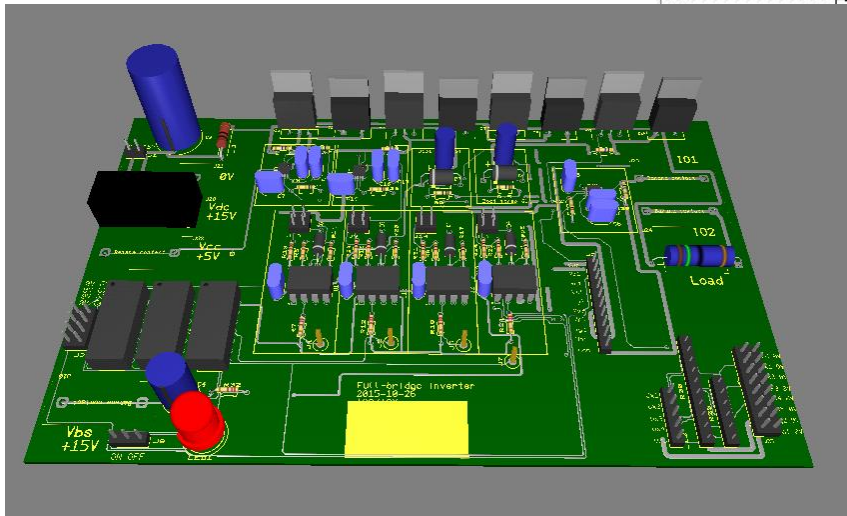
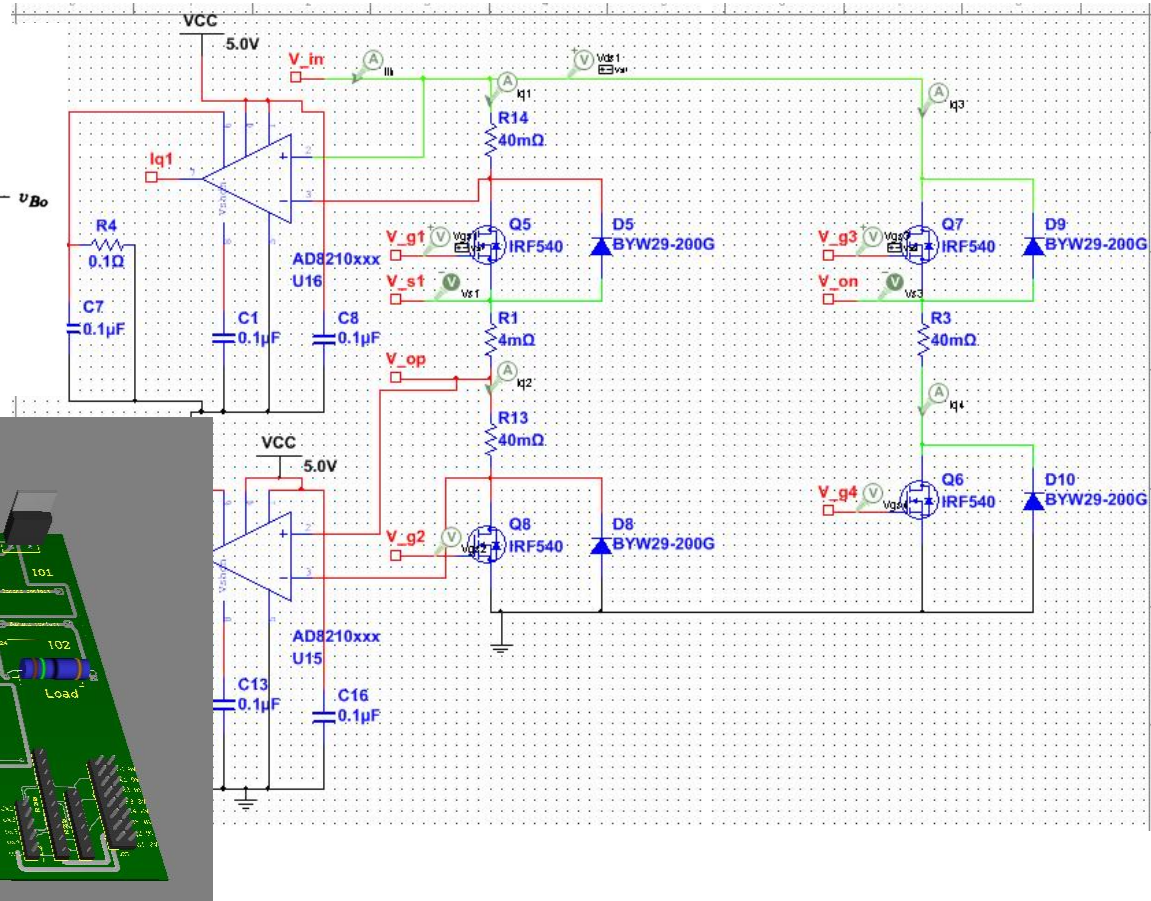


Figure 8-11 Single-phase full-bridge inverter.



Examination

- 3 Lab tasks completed and presented (during the lab)
 - Simulation and measurement tasks
- Written exam

Lecture 1

Power electronic systems from nW to GW

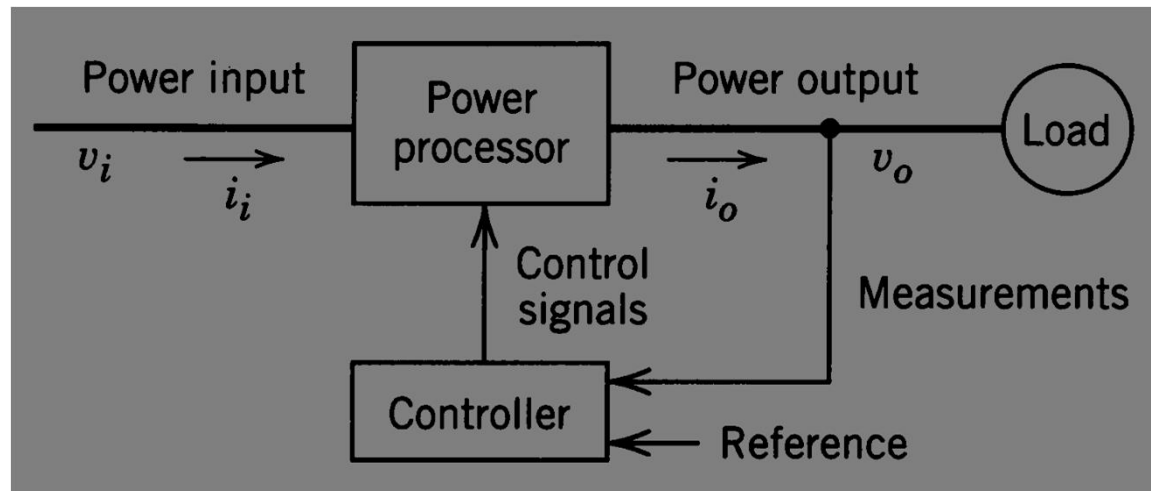
Power electronic systems [Ch 1]

Circuit theory [Ch 3-2]

Exercises [1-1 – 1-5, 3-3 – 3-5]

Power Electronic Systems

- Transfer electric power from source into load, controlling voltage/current applied to the load



Power electronic systems

- Power conversion
 - Frequency transformation, e.g. AC to DC, DC to AC
 - Voltage level transformation, 230V to 12V
 - Current control/limitation
 - Power control, charging v.s. discharging
 - Control related to load variations
 - Control related to source variations

Goals of the power transformation

- High efficiency

$$\eta = \frac{P_{out}}{P_{in}} \approx 1$$

- Accurate output voltages/currents
 - Voltage/current ripple
 - Correct for varying load impedance
- Small size
- Low cost
- :

Lecture 1, Power electronics over 18 decades (10^{-8} W - 10^{10} W)

MEMS $P = 10^{-8} = 10$ nW (200 mV, 50 nA)

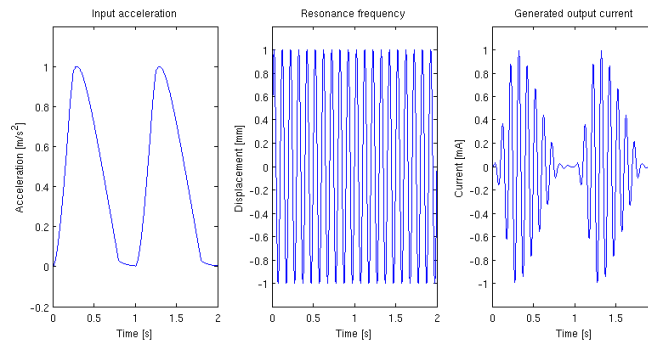
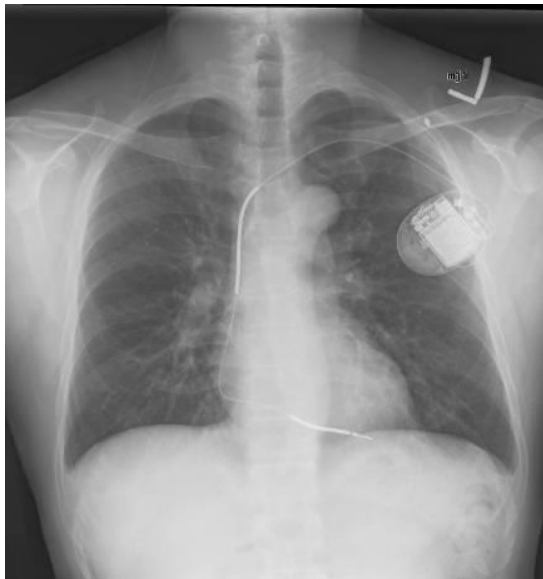
Electric Vehicle battery charger $P = 1$ kW – 50 kW

Wind turbine speed/power control $P=5$ MW

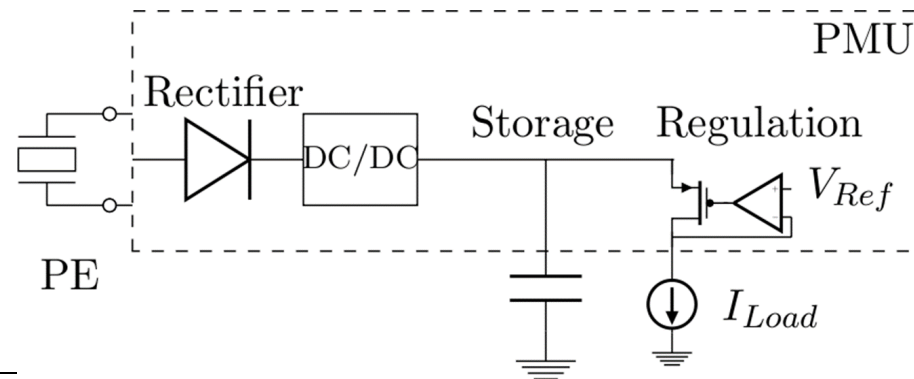
HVDC power transmission $P = 10^{10} = 10$ GW (± 800 kV, 6 kA)

MEMS for pace maker power supply

- Energy harvesting from human heart vibrations for power supply of pace maker implants.

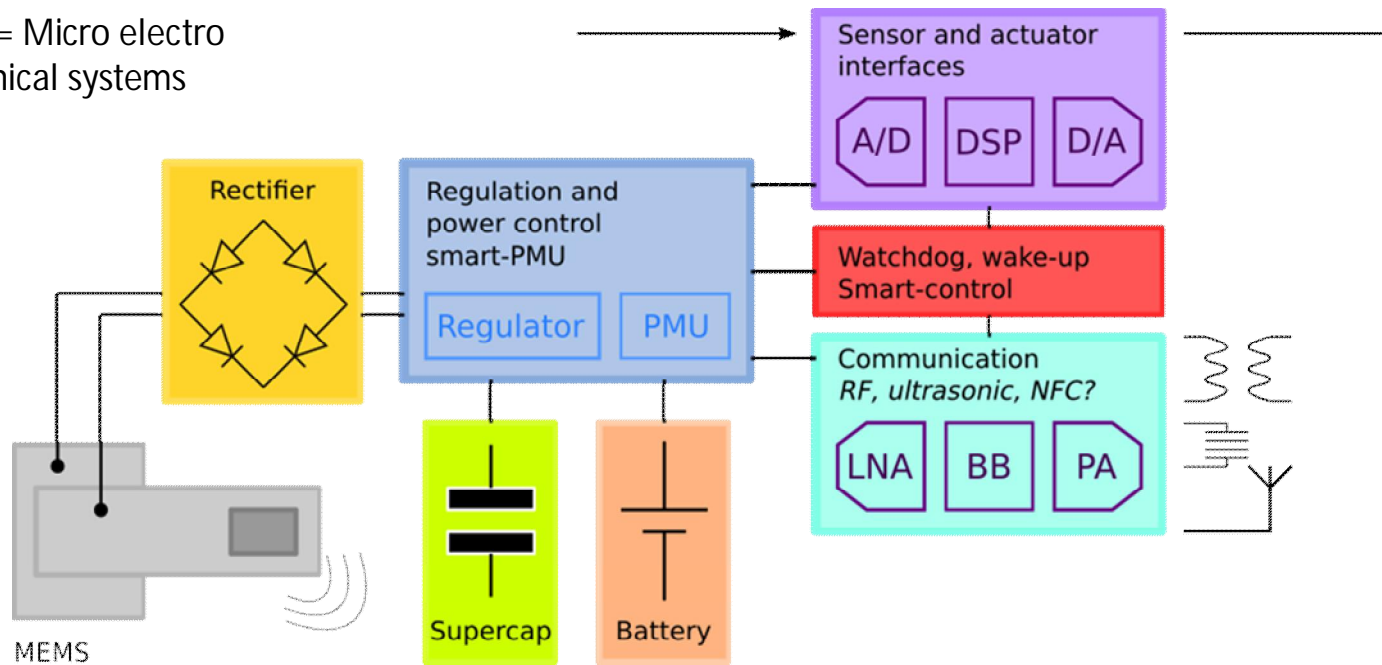


Requirement	Value
Power	300 nW
Output voltage	300 mV



Soil moisture sensor node

MEMS = Micro electro mechanical systems

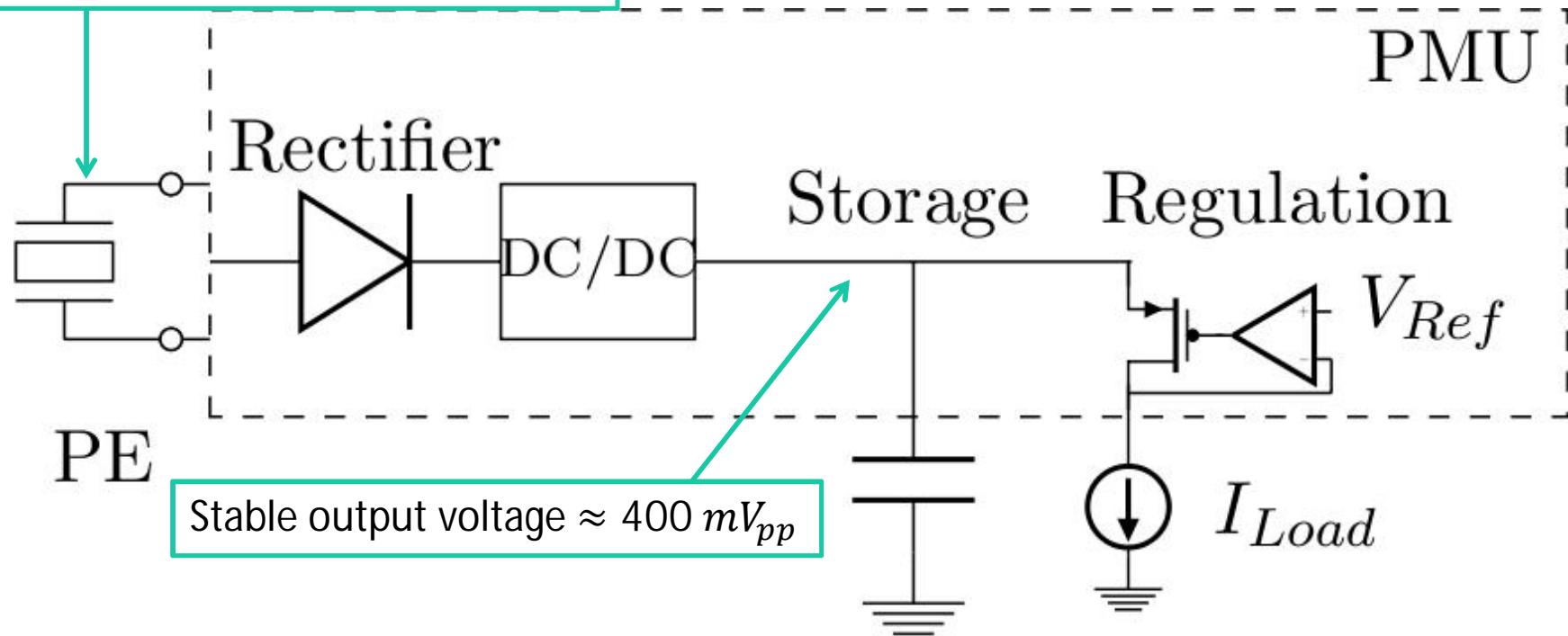


Only wakes up every hour to measure soil moisture

Requirement	Value
Power	25 nW
Output voltage	400 mV

Soil moisture sensor PMU

Varying input, $\approx 150 - 250 \text{ mV}_{pp}$



Stable output voltage $\approx 400 \text{ mV}_{pp}$

Picks up vibration in the ground or the human body, rectifies and boost the voltage to store it in a supercapacitor

Battery charging

- AC-DC converter
- Power conversion from AC power source to DC load
 - Battery
 - Mobile phone ...



Review of Battery Charger Topologies, Charging Power Levels, and Infrastructure for Plug-In Electric and Hybrid Vehicles

Murat Yilmaz, *Member, IEEE*, and Philip T. Krein, *Fellow, IEEE*

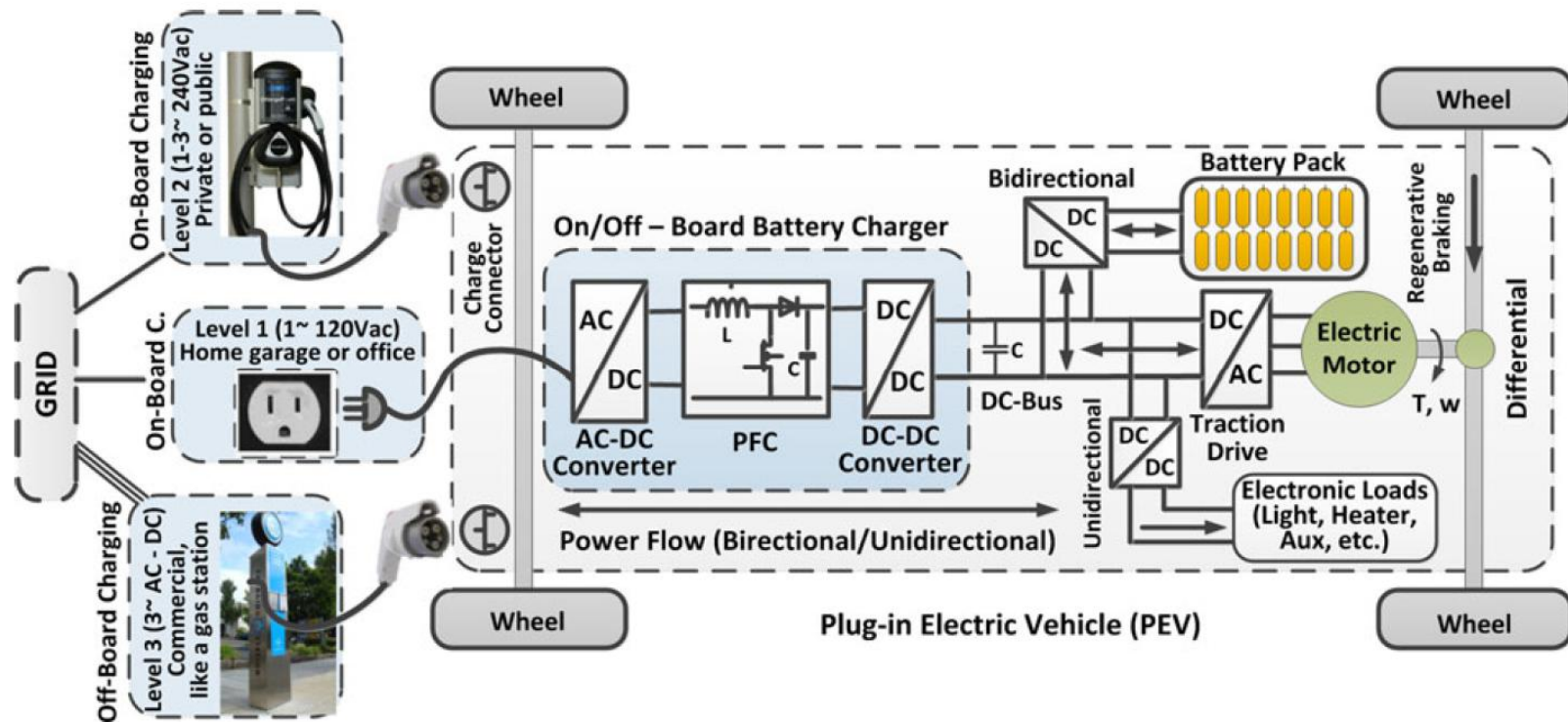


Fig. 6. On/off board charging system and power levels for EVs.



Fig. 5. SAE's J1772 *combo connector* for ac or dc Level 1 and Level 2 charging [65].

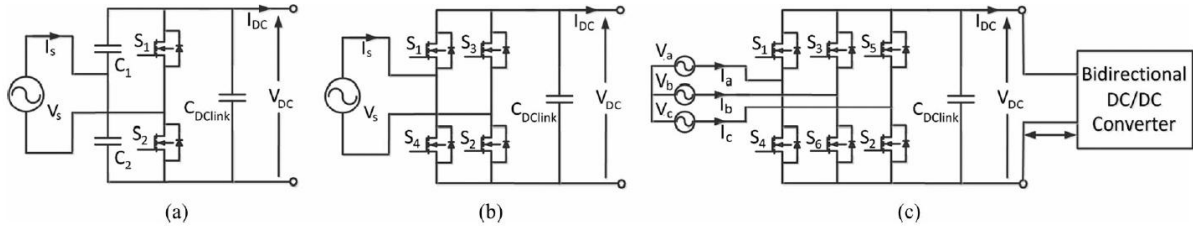


Fig. 4. Bidirectional chargers: (a) single-phase half-bridge, (b) single-phase full-bridge, and (c) three-phase full-bridge.

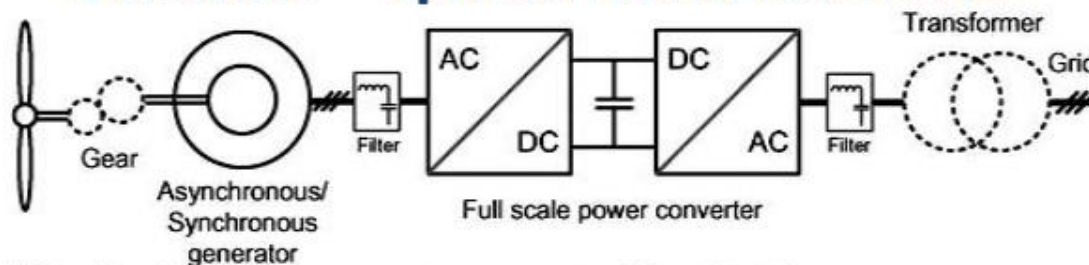
TABLE II
CHARGING CHARACTERISTICS AND INFRASTRUCTURES OF SOME MANUFACTURED PHEVs AND EVs

	Battery Type and Energy	All-Electric Range	Connector Type	Level 1 Charging		Level 2 Charging		DC Fast Charging	
				Demand	Charge Time	Demand	Charge Time	Demand	Charge Time
Toyota Prius PHEV(2012)	Li-Ion 4.4kWh	14 miles	SAE J1772	1.4kW (120V)	3 hours	3.8kW (240V)	2.5 hours	N/A	N/A
Chevrolet Volt PHEV	Li-Ion 16kWh	40 miles	SAE J1772	0.96–1.4 kW	5–8 hours	3.8kW	2–3 hours	N/A	N/A
Mitsubishi i-MiEV EV	Li-Ion 16kWh	96 miles	SAE J1772 JARI/TEPCO	1.5kW	7 hours	3kW	14 hours	50kW	30 minutes
Nissan Leaf EV	Li-Ion 24kWh	100 miles	SAE J1772 JARI/TEPCO	1.8kW	12–16 hours	3.3kW	6–8 hours	50 + kW	15-30 minutes
Tesla Roadster EV	Li-Ion 53kWh	245 miles	SAE J1772	1.8kW	30 + hours	9.6–16.8 kW	4–12 hours	N/A	N/A

Wind turbine converter control

Oregon TECH

Variable – speed wind turbines



Wu B., Lang Y., Zargari N., Kouro S., "Power conversion and control of wind energy systems," Wiley-IEEE press, 2011, pp.16-35

- ❖ Achieve maximum efficiency over a wide range of wind speeds compared with fixed speed wind turbines which only reach peak efficiency at a particular wind speed
- ❖ variable speed systems could lead to maximize the capture of energy during partial load operation
- ❖ Can use either induction generator or a synchronous generator
- ❖ Can operate gearless, lowers the cost

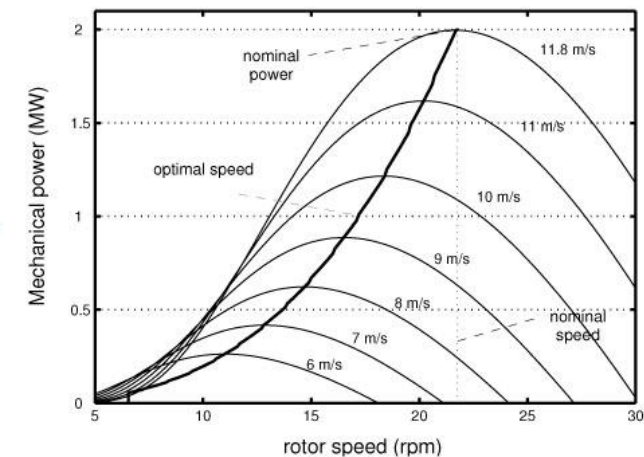
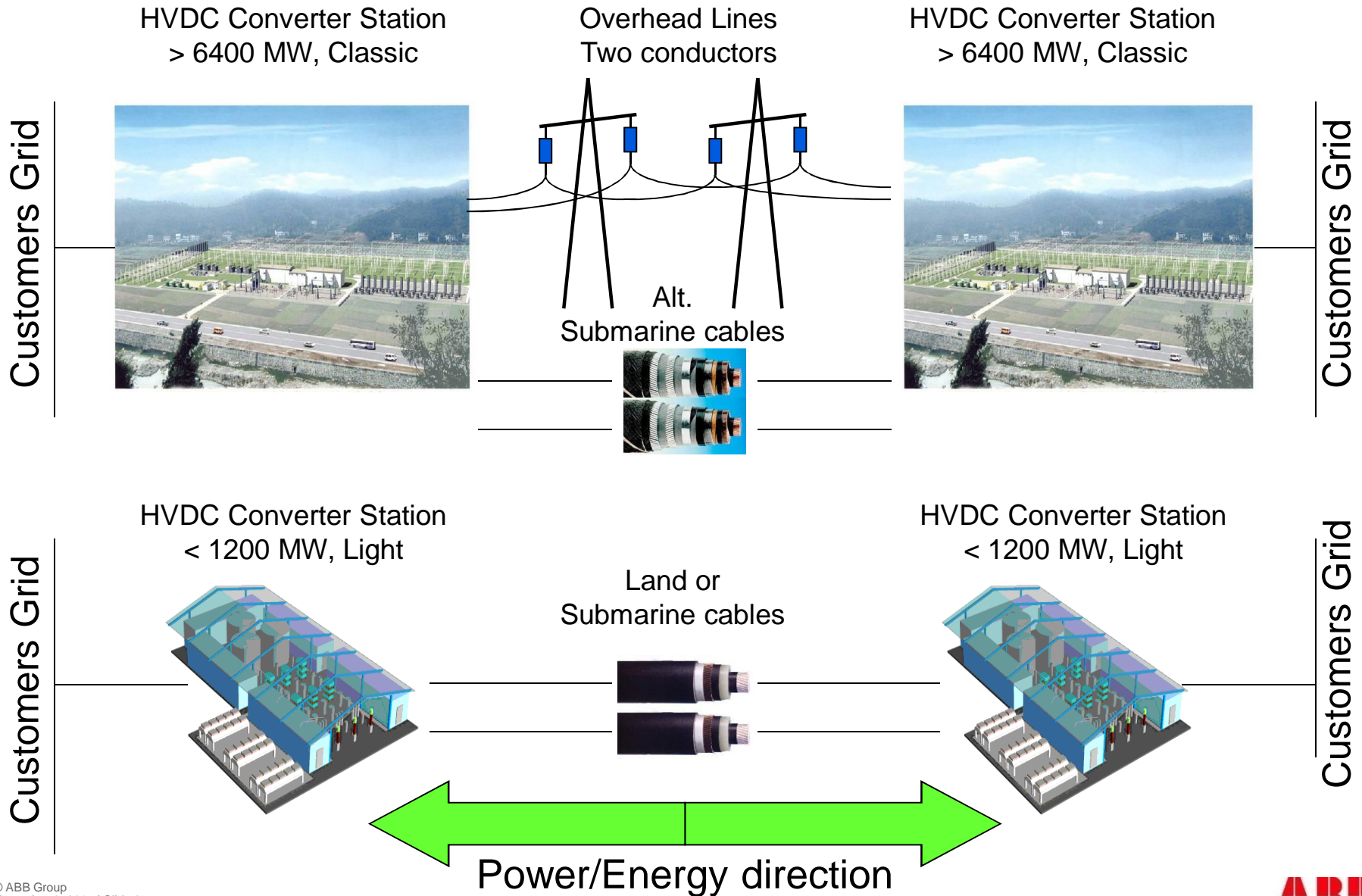


Fig. 8 Output power for different values of wind speed (m/s).

Lecture 1, Power electronics of 20 decades (10^{-10} W - 10^{10} W)

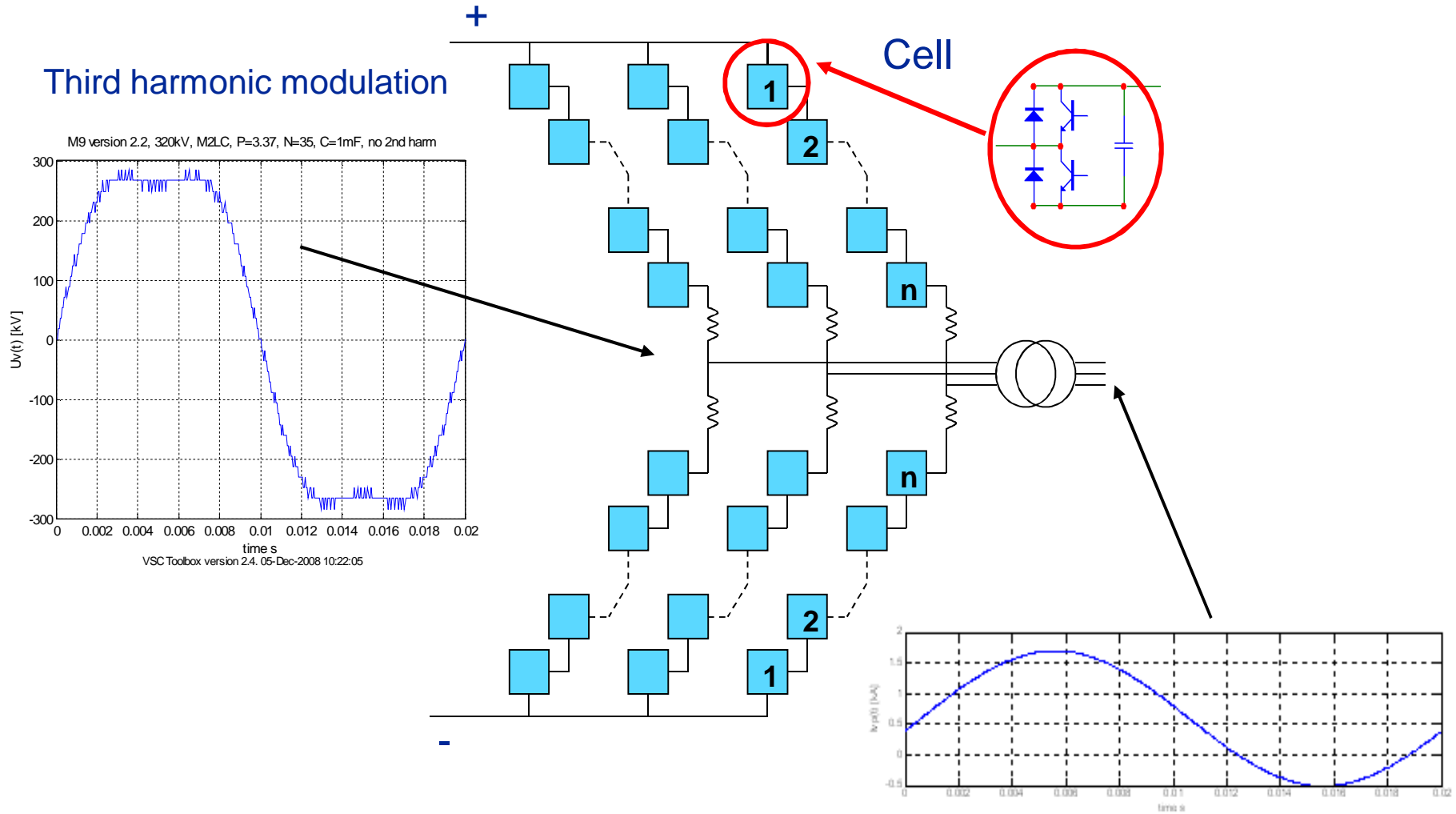
HVDC

What is an HVDC Transmission System?



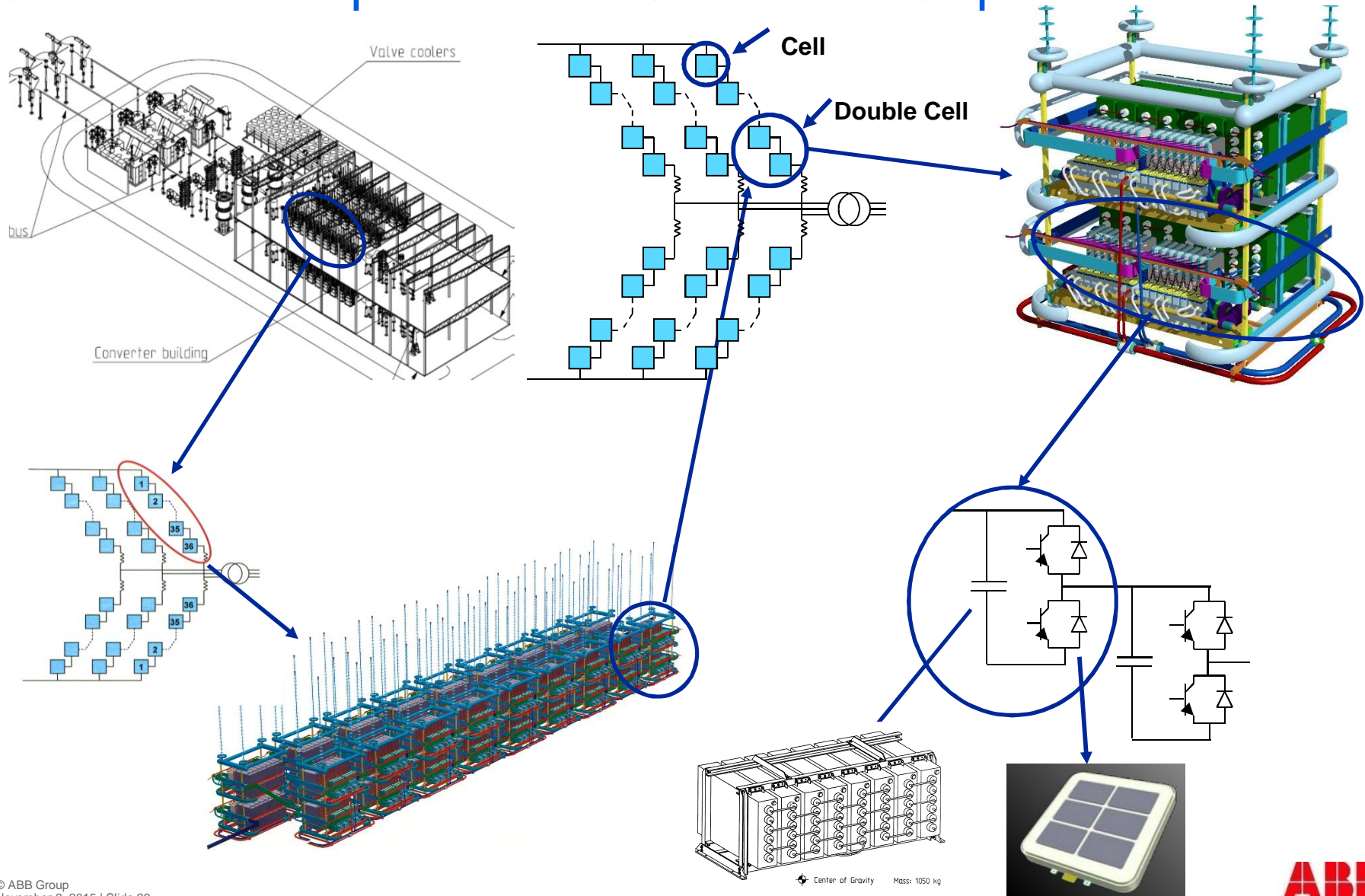
Today's converter design

Converter output voltage

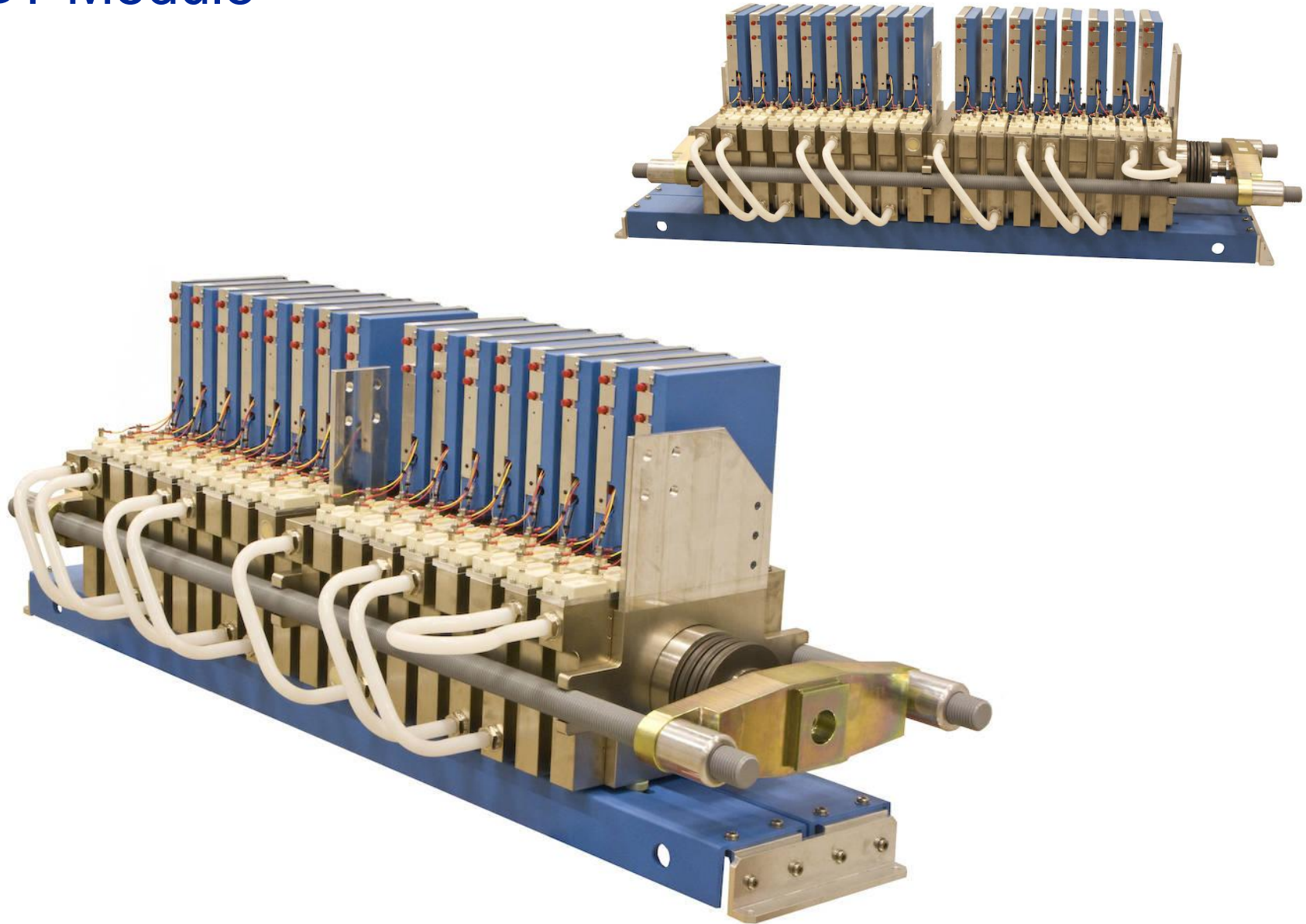


The converter valve

Cell main components – IGBTs and Capacitors



IGBT Module



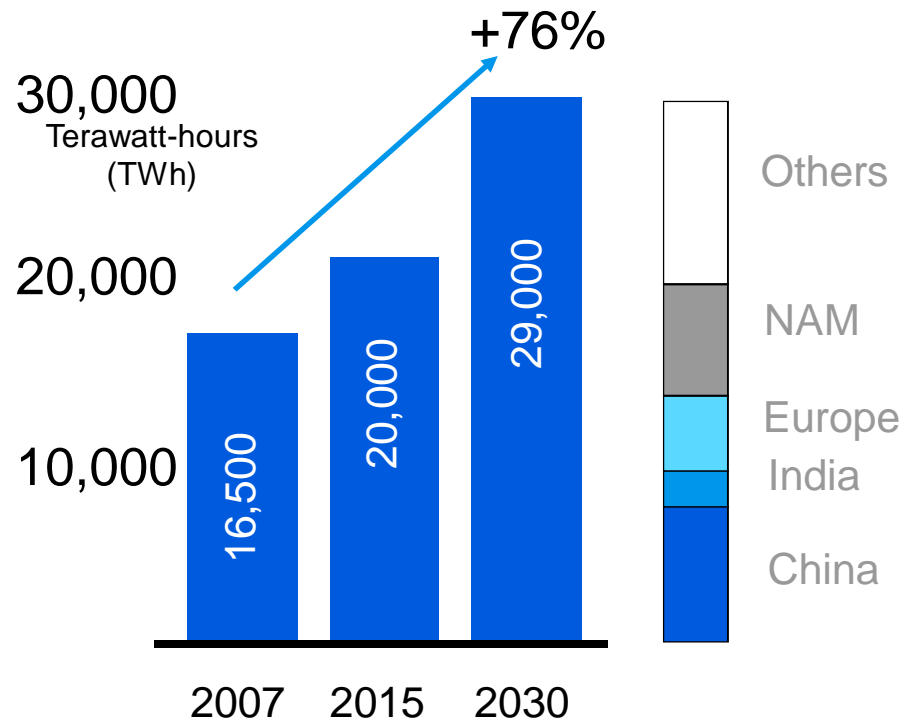
IGBT inner structure



Tackling society's challenges on path to low-carbon era means helping utilities do more using less

Forecast rise in electricity consumption by 2030

Source: IEA, World Energy Outlook 2009



Solutions are needed for:

- Rising demand for electricity – more generation
- Increasing energy efficiency - improving capacity of existing network
- Reducing CO₂ emissions – Introduce high level of renewable integration

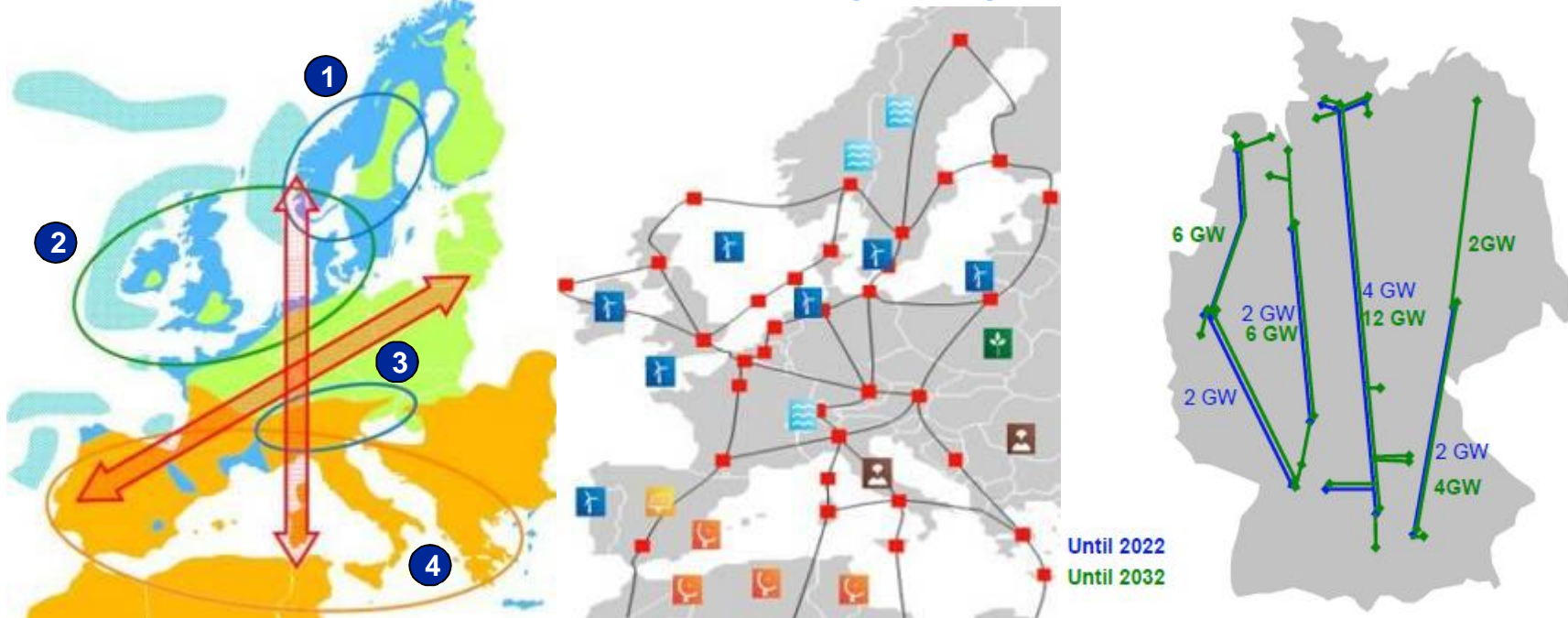
Meeting the rise in demand will mean adding a 1 GW power plant and all related infrastructure every week for the next 20 years

IEA World Energy Outlook 2012 - 2035

- **5 890 GW of capacity additions (> the total installed capacity in 2011) is required**
- One-third of this is to replace retiring plants; the rest is to meet growing electricity demand.
- Renewables represent half : 3000 GW. Gas 1400 GW.
- The power sector requires investment of \$16.9 trillion,
- Investment in generation capacity, > 60% is for renewables: wind (22%), hydro (16%), solar PV (13%).

The evolution of HVDC grids: Connect remote renewables

Europe & Germany are planning large scale HVDC



Source: DG Energy, European Commission

European Visions

- 1 Hydro power & pump storage -Scandinavia
- 2 >50 GW wind power in North Sea and Baltic Sea
- 3 Hydro power & pump storage plants - Alps
- 4 Solar power in S.Europe, N.Africa & Middle East

Germany (draft grid master plan)

- Alternatives to nuclear-distributed generation
- Role of offshore wind / other renewables
- Political commitment
- Investment demand and conditions
- Need to strengthen existing grid

Lecture 1

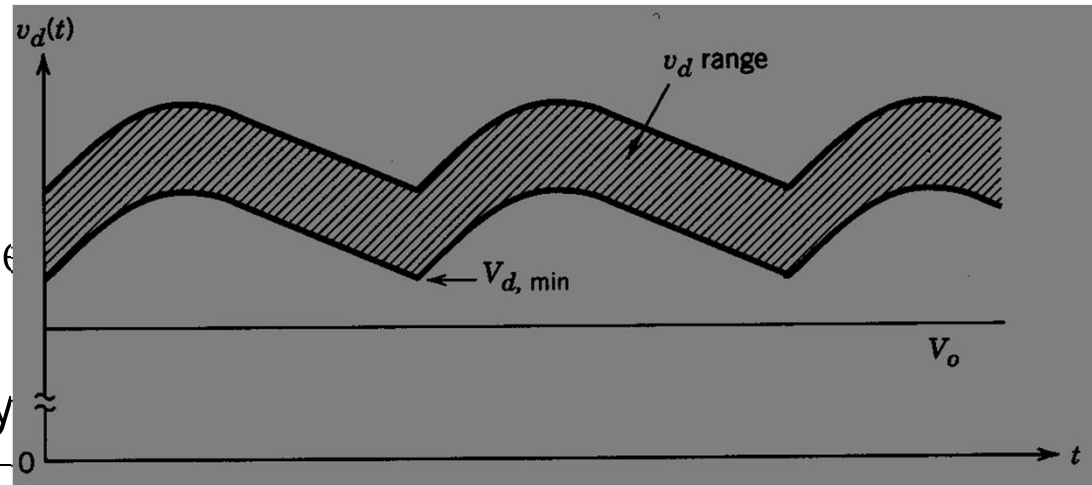
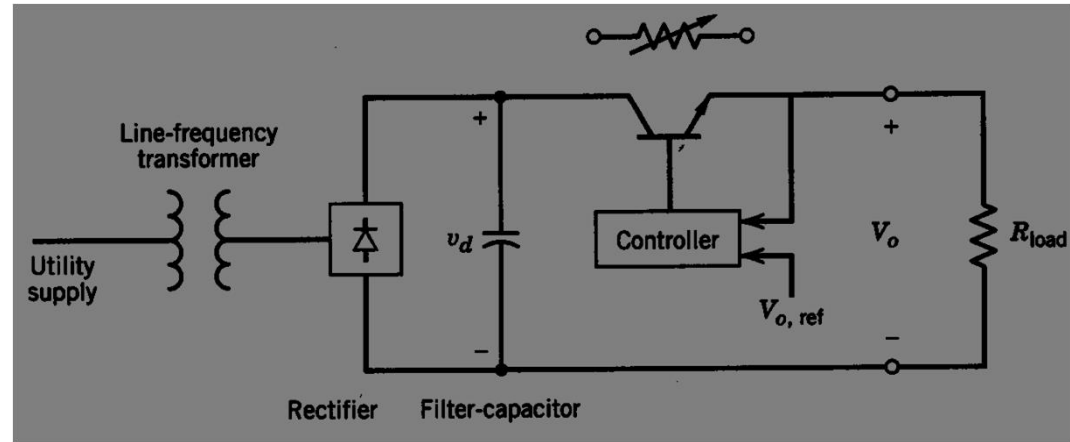
Power electronic systems {Ch1}

Power basics

Circuit theory

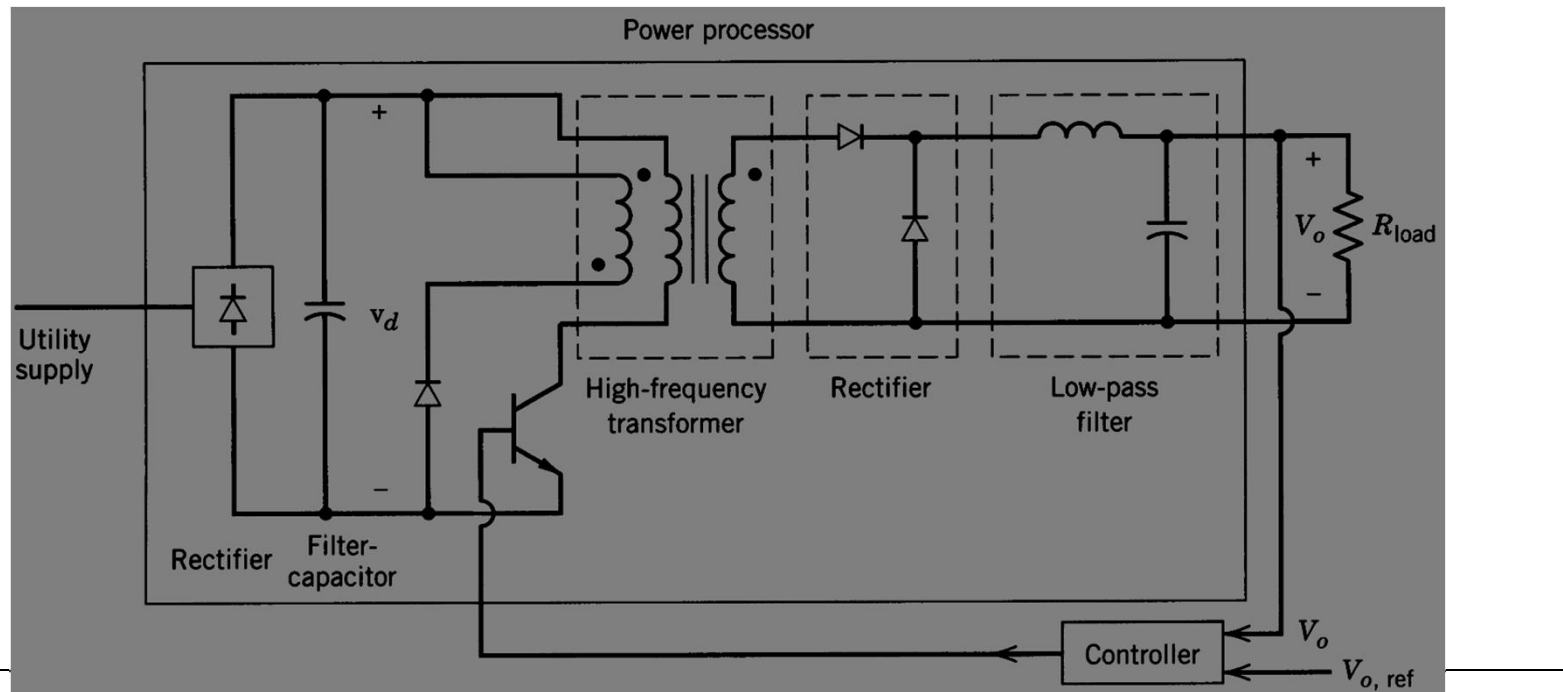
Example: Power Supply

- Goal
 - Fixed DC voltage
 - Accept variation on input voltage
- Linear power supply
 - Adjustable resistor implemented using a transistor
 - Low efficiency, lot of power dissipated in transistor
 - Bulky line-frequency transformer



Example: Power Supply

- Switch-mode power supply
 - Transistor only used as switch
 - High efficiency, small size



Goal of power conversion

- Translate input voltage into expected waveform of output voltage
- Dissipate little/no power
- Technology: semiconductors, inductors, capacitors, (resistors)
- Should not use semiconductors as resistances

Symbol definitions

- u_{ab}, U_{ab} Voltage. U_{ab} is the voltage between points a and b.
- V_a Potential. The voltage to ground at point a.
- OBS, the course book uses american standard: v for voltages in general.
- i_a, I_a Current in path (phase) a.
- p_a, P_a Power. Active power
- Lower case symbols denotes instantaneous values
- Upper case symbols denotes average or RMS values

Power Basics

- For AC signal (pure sinusoidal)

$$u(t) = \hat{U} \sin(\omega t + \phi_u) [V]$$

$$i(t) = \hat{I} \sin(\omega t + \phi_i) [A]$$

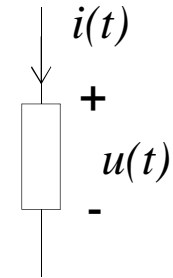
$$\text{where } \omega = 2\pi f = \frac{2\pi}{T}$$

$$P = \int_0^T p(t) dt = \frac{\hat{U}}{\sqrt{2}} \cdot \frac{\hat{I}}{\sqrt{2}} \cos(\phi_u - \phi_i) = U_e * I_e * \cos\phi [W]$$

- For DC signals

$$P = UI$$

$$p(t) = u(t) * i(t)$$



Average power and rms current

Instantaneous
power

$$p(t) = u(t) \cdot i(t)$$

Average
power

$$P_{av} = \frac{1}{T} \int_0^T p(t) dt = \frac{1}{T} \int_0^T u(t) \cdot i(t) dt$$

$$P_{av} = R \frac{1}{T} \int_0^T i^2(t) dt$$

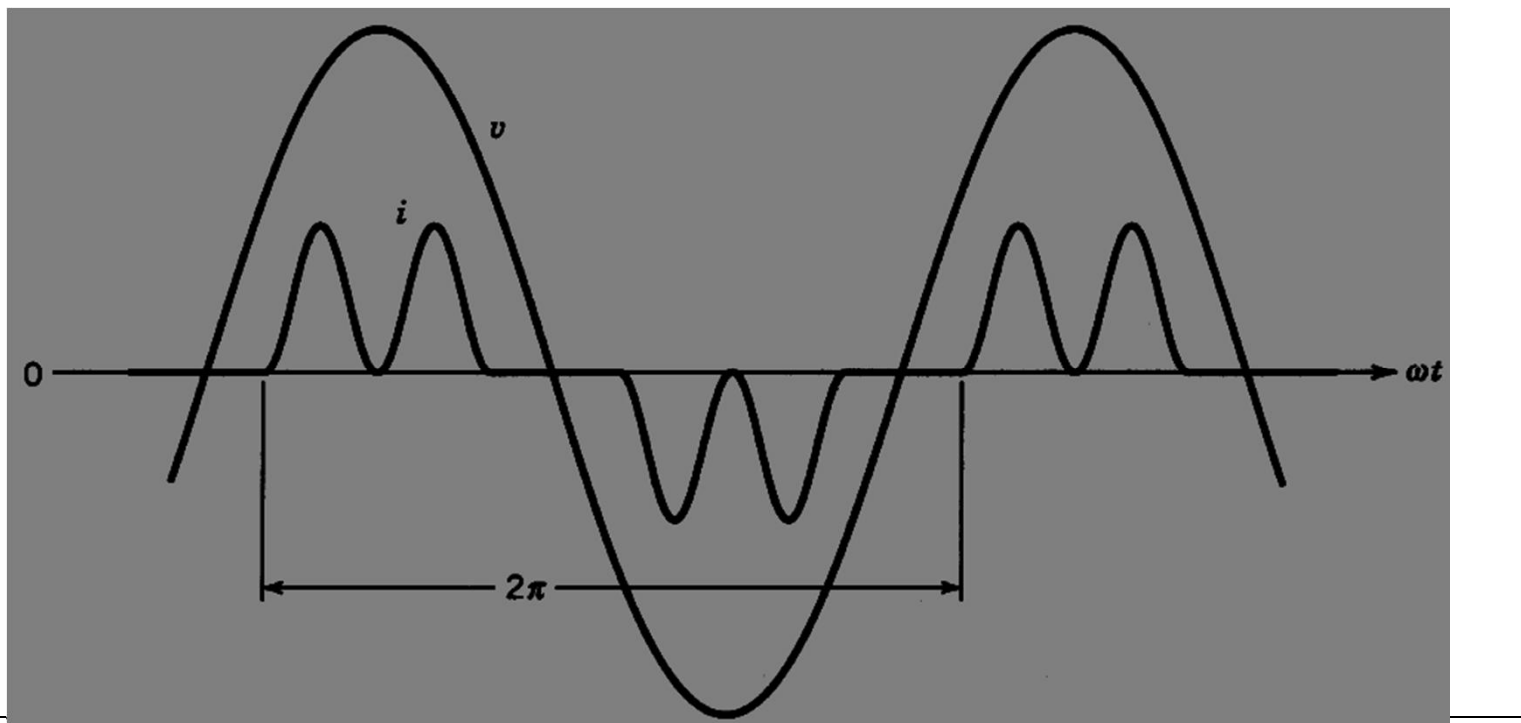
$$P_{av} = RI^2$$

RMS current:
the current value
that defines the
average power

$$I = \sqrt{\frac{1}{T} \int_0^T i^2(t) dt}$$

Steady state voltages and currents

- Assume repeating waveform
- Ignore startup sequence (steady state)



Fourier analysis

Table 3-1 Use of Symmetry in Fourier Analysis

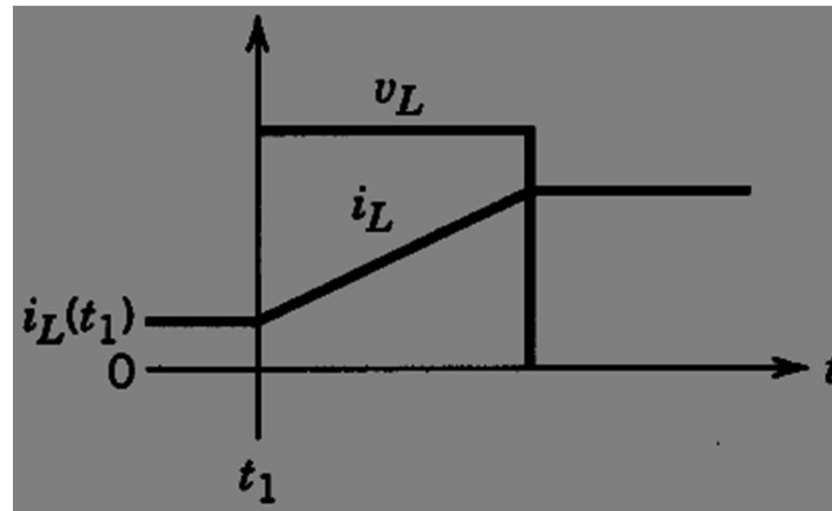
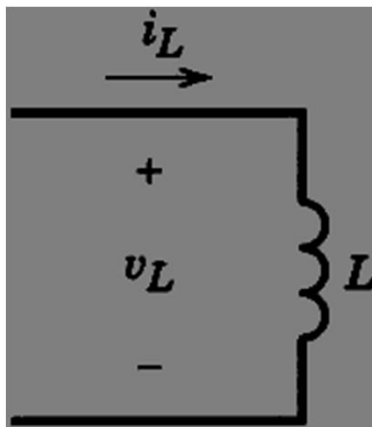
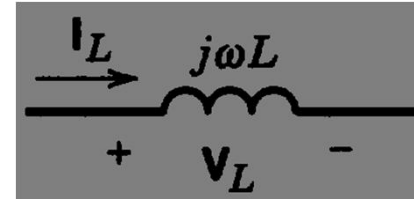
<i>Symmetry</i>	<i>Condition Required</i>	<i>a_h and b_h</i>	
Even	$f(-t) = f(t)$	$b_h = 0$	$a_h = \frac{2}{\pi} \int_0^{\pi} f(t) \cos(h\omega t) d(\omega t)$
Odd	$f(-t) = -f(t)$	$a_h = 0$	$b_h = \frac{2}{\pi} \int_0^{\pi} f(t) \sin(h\omega t) d(\omega t)$
Half-wave	$f(t) = -f(t + \frac{1}{2}T)$	$a_h = b_h = 0$ for even h	$a_h = \frac{2}{\pi} \int_0^{\pi} f(t) \cos(h\omega t) d(\omega t)$ for odd h
			$b_h = \frac{2}{\pi} \int_0^{\pi} f(t) \sin(h\omega t) d(\omega t)$ for odd h
Even quarter-wave	Even and half-wave	$b_h = 0$ for all h	$a_h = \begin{cases} \frac{4}{\pi} \int_0^{\pi/2} f(t) \cos(h\omega t) d(\omega t) & \text{for odd } h \\ 0 & \text{for even } h \end{cases}$
Odd quarter-wave	Odd and half-wave	$a_h = 0$ for all h	$b_h = \begin{cases} \frac{4}{\pi} \int_0^{\pi/2} f(t) \sin(h\omega t) d(\omega t) & \text{for odd } h \\ 0 & \text{for even } h \end{cases}$

Inductor behaviour

- Frequency and time domain

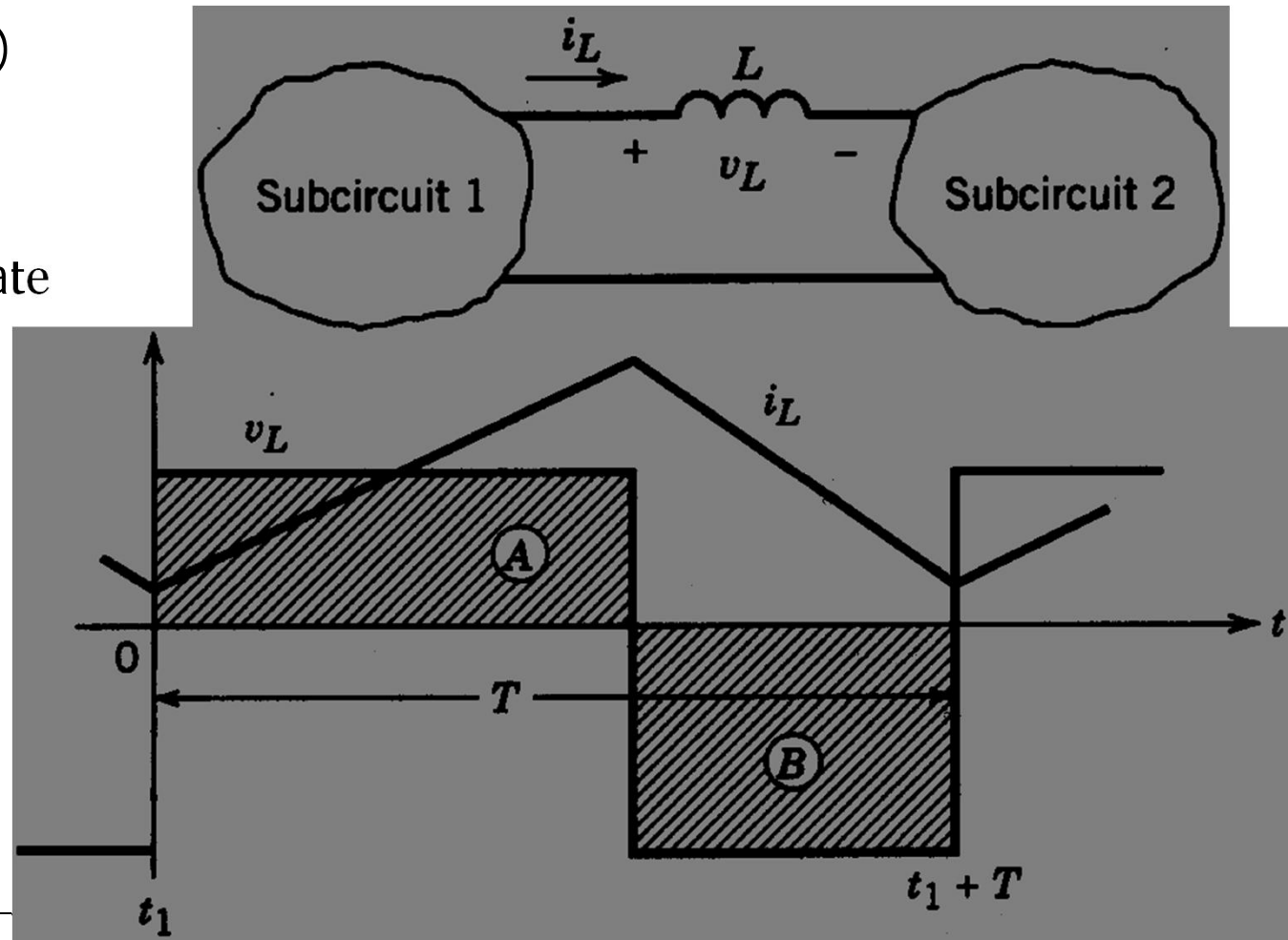
- $v_L = L \frac{di_L}{dt}$ $V_L = j\omega L I_L$

$$i_L(t) = i_L(t_1) + \frac{1}{L} \int_{t_1}^t v_L d\xi$$



Inductor in steady state

- $v(t+T) = v(t)$
- $i(t+T) = i(t)$
- $A = B$
in steady state

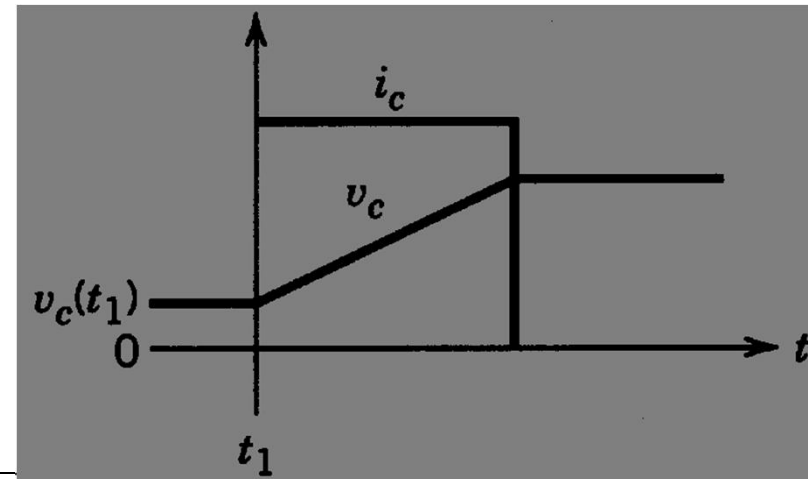
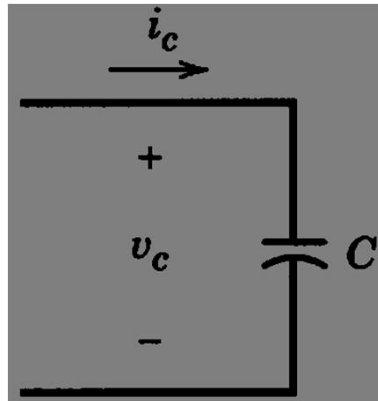
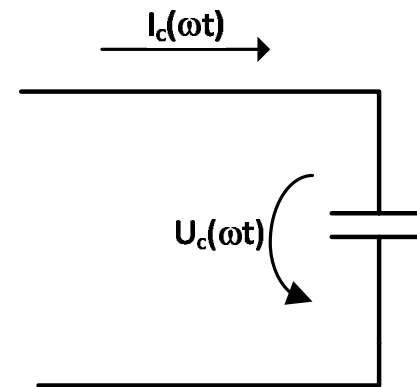


Capacitor behavior

- Frequency and time domain

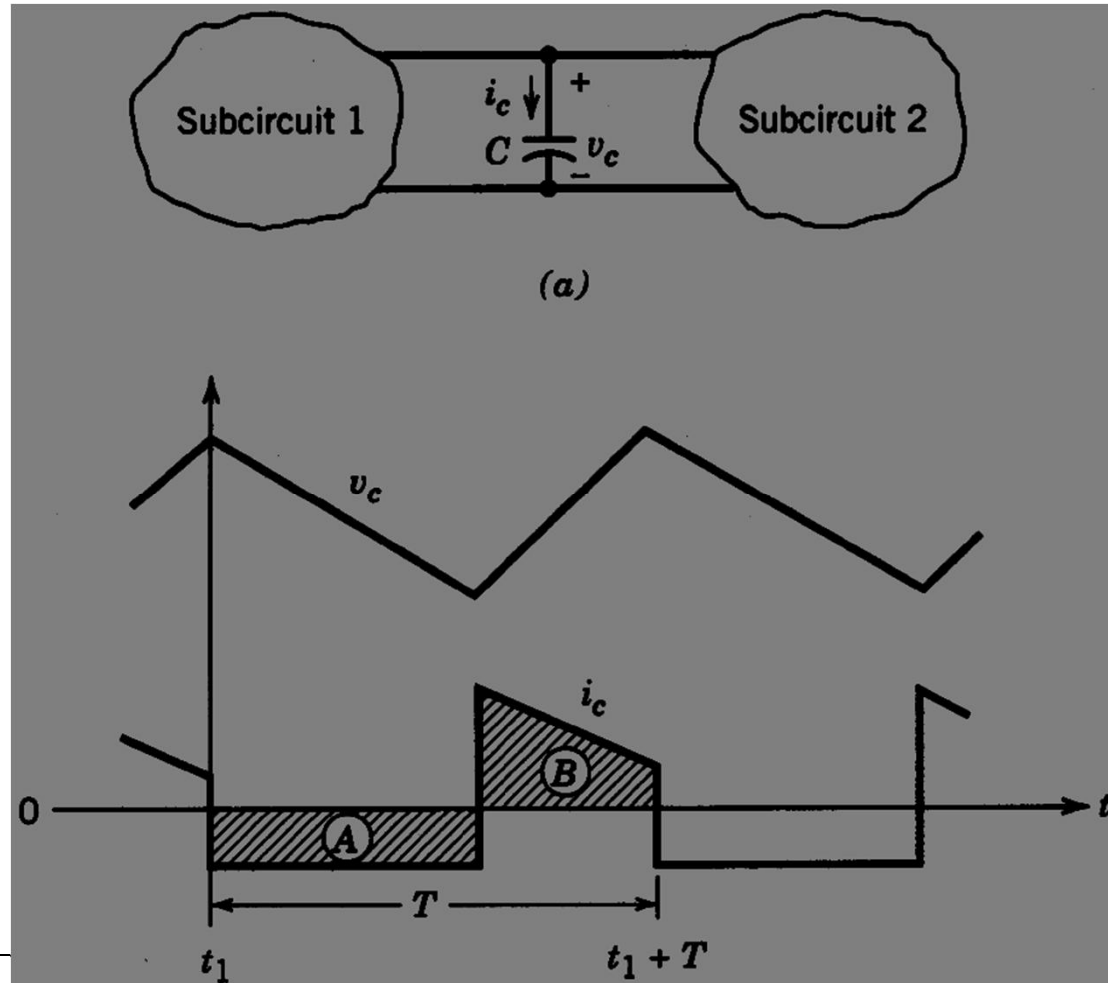
$$V_C = \frac{1}{j\omega C} I_C$$

$$v_C(t) = v_C(t_1) + \frac{1}{C} \int_{t_1}^t i_C d\xi$$



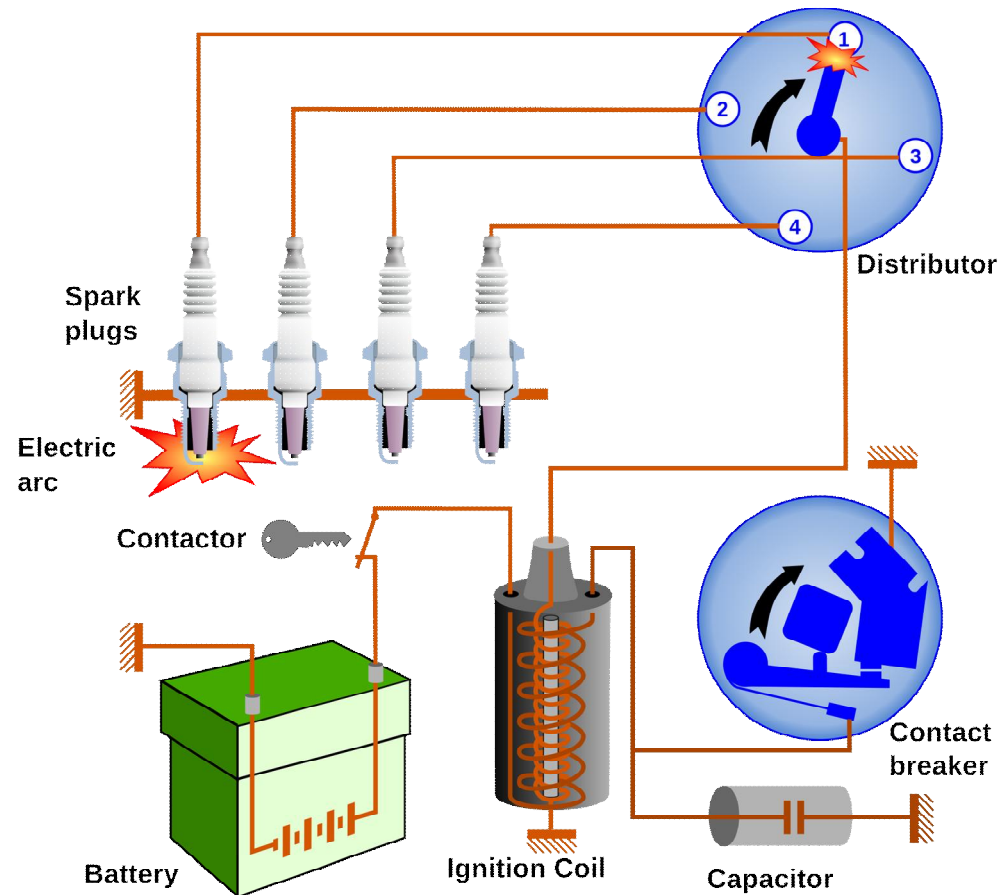
Capacitor in steady state

- $v(t+T) = v(t)$
- $i(t+T) = i(t)$
- $A = B$
in steady state



Car ignition system

- Sudden opening of the contact breaker give high di/dt through the ignition coil
- 20-50kV obtained at the spark plug
- Capacitor protects the contact breaker from excessive voltage

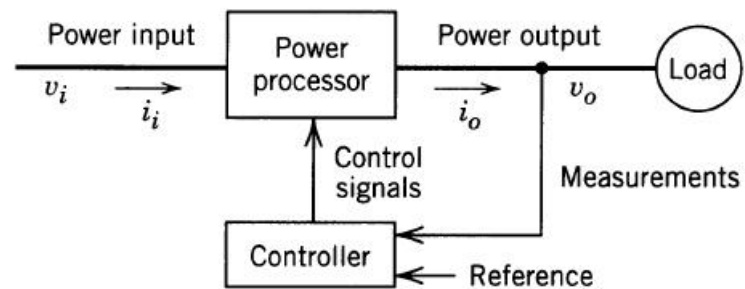


Exercises, lecture 1

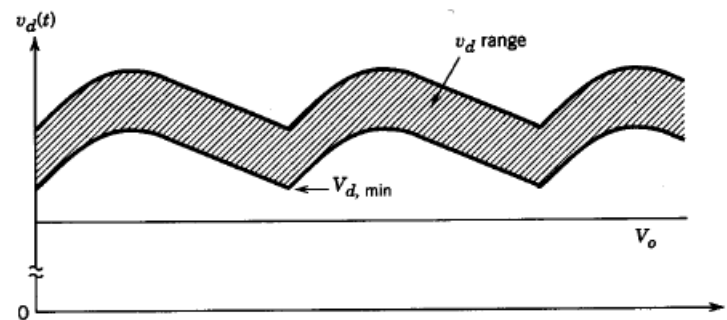
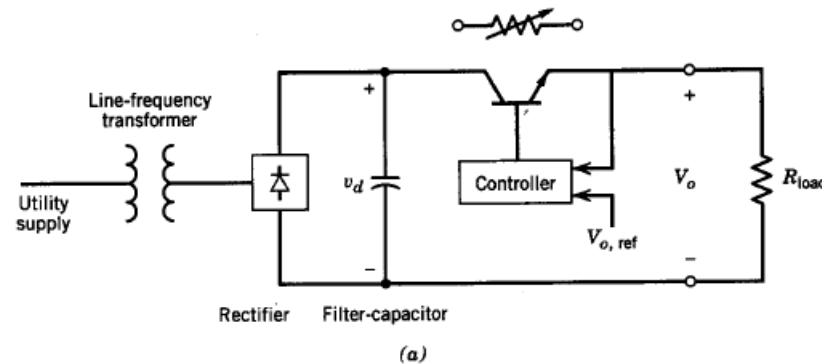
1-1, 1-2, 1-3, 1-4, 1-5

3-3, 3-4, 3-5

1-1 In the power processor of Fig. 1-1, the energy efficiency is 95%. The output to the three-phase load is as follows: 200 V line-to-line (rms) sinusoidal voltages at 52 Hz and line current of 10 A at a power factor of 0.8 (lagging). The input to the power processor is a single-phase utility voltage of 230 V at 60 Hz. The input power is drawn at a unity power factor. Calculate the input current and the input power.

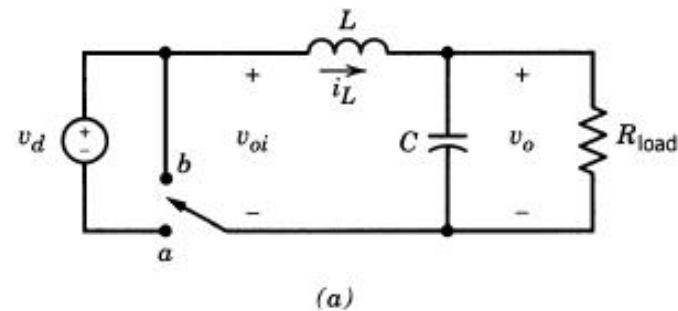


- 1-2 Consider a linear regulated dc power supply (Fig. 1-2a). The instantaneous input voltage corresponds to the lowest waveform in Fig. 1-2b, where $V_{d,\min} = 20\text{ V}$ and $V_{d,\max} = 30\text{ V}$. Approximate this waveform by a triangular wave consisting of two linear segments between the above two values. Let $V_o = 15\text{ V}$ and assume that the output load is constant. Calculate the energy efficiency in this part of the power supply due to losses in the transistor.



- 1-5 In Problem 1-4, assume the output voltage to be a pure dc $V_o = 15$ V. Calculate and draw the voltage and current associated with the filter inductor L , and the current through C . Using the capacitor current obtained above, estimate the peak-to-peak ripple in the voltage across C , which was initially assumed to be zero. (*Hint: Note that under steady-state conditions, the average value of the current through C is zero.*)

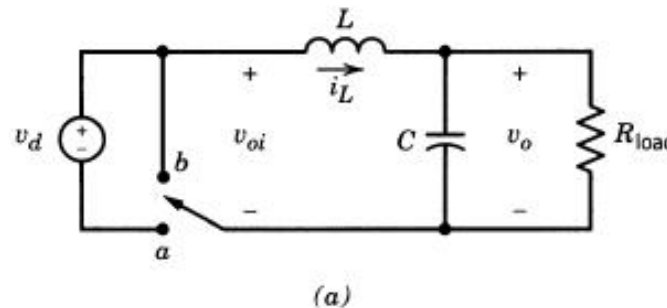
$V_d = 20$ V
 Duty cycle $D = 0.75$
 $f_s = 300$ kHz
 $L = 1.3$ μ H
 $C = 50$ μ F
 $P_{load} = 240$ W



Extra questions:

- What is the efficiency?
- Calculate rms values for v_{oi} and i_L

- 1-3 Consider a switch-mode dc power supply represented by the circuit in Fig. 1-4a. The input dc voltage $V_d = 20$ V and the switch duty ratio $D = 0.75$. Calculate the Fourier components of v_{oi} using the description of Fourier analysis in Chapter 3.
- 1-4 In Problem 1-3, the switching frequency $f_s = 300$ kHz and the resistive load draws 240 W. The filter components corresponding to Fig. 1-4a are $L = 1.3$ μ H and $C = 50$ μ F. Calculate the attenuation in decibels of the ripple voltage in v_{oi} at various harmonic frequencies. (*Hint: To calculate the load resistance, assume the output voltage to be a constant dc without any ripple.*)



$V_d = 20$ V
 Duty cycle $D = 0.75$
 $f_s = 300$ kHz
 $L = 1.3$ μ H
 $C = 50$ μ F
 $P_{load} = 240$ W

3-3

- For the waveforms in Fig. P3-3, calculate their average value and the rms values of the fundamental and the harmonic frequency components.

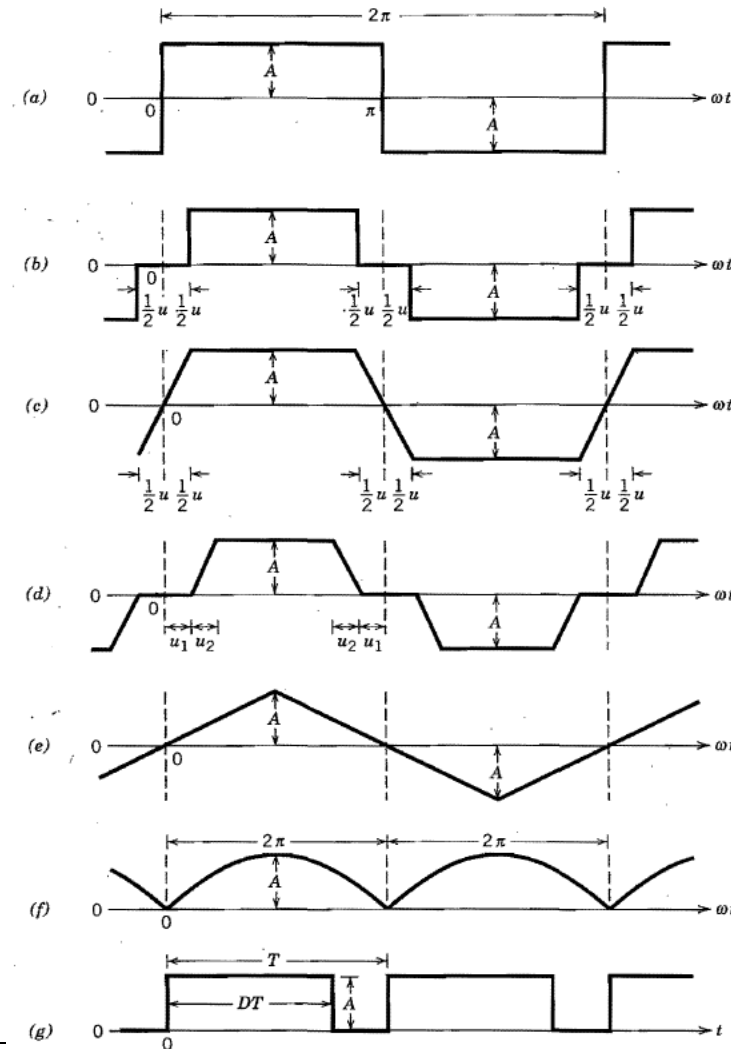


Figure P3-3

3-4

In the waveforms of Fig. P3-3 of Problem 3-3, $A = 10$ and $u = 20^\circ$ ($u_1 = U_2 = u/2$), where applicable. Calculate their total rms values as follows:

- a) By using the results of Problem 3-3 in Eq. 3-28.
- b) By using the definition of the rms value as given in Eq. 3-5.

3-5

Refer to Problem 3-4 and calculate the following:

- a) For each of the waveforms $a-e$, calculate
 - i. the ratio of the fundamental frequency component to the total rms value
 - ii. the ratio of the distortion component to the total rms value.
- b) For the waveforms f and g , calculate the ratio of the average value to the total rms value.

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