

# Lecture 7, ANIK

### **Operational amplifiers 2**

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### What did we do last time?

**Operational amplifiers** 

**Top-level** aspects

Compensation

Phase margin, stability, etc.



### What will we do today?

**Operational amplifiers continued** 

Circuit-level aspects

Implementation details



# **Operational amplifiers, revisited**

Operational transconductance amplifier (OTA) Drive capacitive load, typically on-chip

Operational amplifiers (OP)

Drive resistive load, typically off-chip

#### **Spec**ifications

Differential input, opt. differential output Infinite gain Infinite input impedance Infinite (OTA) / Zero (OP) output impedance

### Always used in feedback (otherwise it is a comparator)!





### Why do you want controlled feedback?

#### Gain is now under control!

No variation with gm/gds, instead it is given by passive components

"Unlimited" drive capability

Isolation of input and output

Linearization

Remember, it is a regulation loop. It is designed to track the changes, anything added in the loop will be supressed.



# **Operational amplifier architectures**

Telescopic

Two-stage

Folded-cascode

**Current-mirror** 

Essentially just cascaded stages



## **Telescopic OTA**

Stack many cascodes on top of each-other and use gain-boosting, etc.

### Omitted, since it is not applicable for modern processes.

The swing is eaten up.





### Two-stage OP, how it works

#### Gain

Transconductance Impedances

### Swing

Common-mode range Output range Input range



KÖPINGA



# **Current-mirror OP/OTA, how it works**

#### Gain

Transconductance Impedances

### Swing

Common-mode range Output range Input range





## Why folded-cascode?



Consider the CMR in buffer configuration

In telescopic OTA, the swing will be very small since bias transistor "locks" the voltage level

 $V_{in}$ 

 $V_{out}$ 



### Folded-cascode, how it works

#### Gain

Transconductance Impedances

### Swing

Common-mode range Output range Input range



### **Other practical concerns wrt. current**

#### Feedback with resistors

An OP given with a certain current drive capability.

What is the maximum swing?

What is the DC level?



# **Other practical concerns wrt. bandwidth**

#### Various unwanted effects

Limited gain

Offset error

Bandwidth



## **OP/OTA** Compilation



#### Cookbook recipes

Hand-outs with step-by-step explanation of the design of OP/OTAs <u>http://www.es.isy.liu.se/courses/ANIK/download/opampRef/ANTIK\_0NNN\_LN\_opampHandsouts\_A.pdf</u>

Compensation techniques <u>http://www.es.isy.liu.se/courses/ANIK/download/opampRef/ANTIK\_0NNN\_LN\_o</u> <u>pampCompensationTable\_A.pdf</u>



### What did we do today?

**Operational amplifiers** 

Circuit-level aspects

Simulation aspects

Some terminology

Some top-level tips-and-tricks



### What will we do next time?

#### Noise

Circuit noise

Thermal noise

Flicker noise

#### Distortion

What sets the (non)linearity in our CMOS devices?





# Lecture 8, ANIK

#### Noise and distortion

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