### TSTE17 System Design, CDIO

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- Lecture 4
  - Project hints and deadline suggestions

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- Modulation, cont.
- Channel coding

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<table-cell><section-header><page-header><list-item><list-item><list-item><list-item><list-item><list-item>2 **General project hints Output Output** 

# General project hints, cont. • Final presentation and demonstration - All group members should participate • Next thing to do - Complete the first requirement specification - Create project plan and time plan TSTE17 System Design, CDIO Kent Palmkvist kent.palmkvist@isy.liu.se www.isy.liu.se/edu/kurs/TSTE17 Department of Electrical Engineering l.u Linköping University 4 **Behavioral Model**

- Describe external behavior of each block in the design
- Used to verify block diagram and function in the complete system
- Internals not of interest



## Behavour Example Filter vs scrambler

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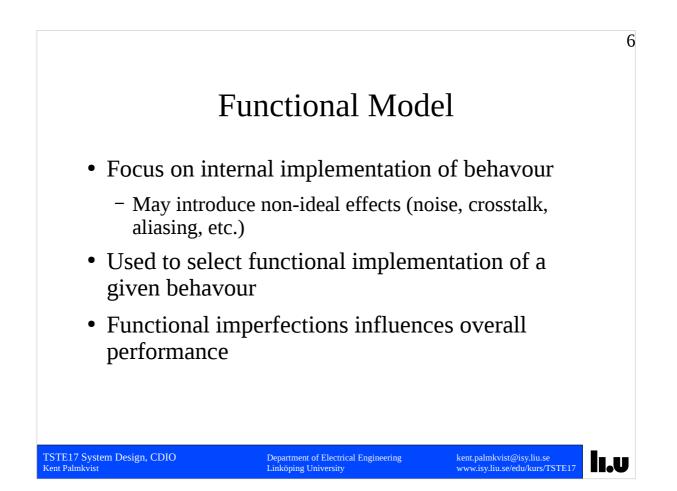
- Filter descriptions
  - mathematical expression (transfer function)
  - May use complex blocks in simulink
  - No description of algorithm to use
- Scrambler descriptions

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- shift register with feedback (structure)
- vector of bits xor:ed once with complete input

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#### 7 Functional Example Filter vs scrambler • Filter - Filter structure (sequence of operations) - Scaling of filter Scrambler • - shift register with feedback - multiple bit state machine TSTE17 System Design, CDIO Kent Palmkvist kent.palmkvist@isy.liu.se www.isy.liu.se/edu/kurs/TSTE17 Department of Electrical Engineering l.u Linköping University 8

### Bit-True Model

- Model function as implemented in digital environment
- Include truncation, overflow, latency etc.
- Do not describe limits on clock frequencies

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# Bit-True Example Filter vs scrambler • Filter - Filter architecture (what hardware units, how they are interconnected, etc.) • Scrambler - Same as functional. - May introduce extra pipelining etc. TSTE17 System Design, CDIO Kent Palmkvist kent.palmkvist@isy.liu.se www.isy.liu.se/edu/kurs/TSTE17 Department of Electrical Engineering l.u Linköping University 10 General project hints, cont. Models sorted by complexity - Model 4: Most complicated - Model 1 - Model 2 - Model 3: Least complex • Complexity also dependent on what is included in each model - Synchronisation, channel estimation

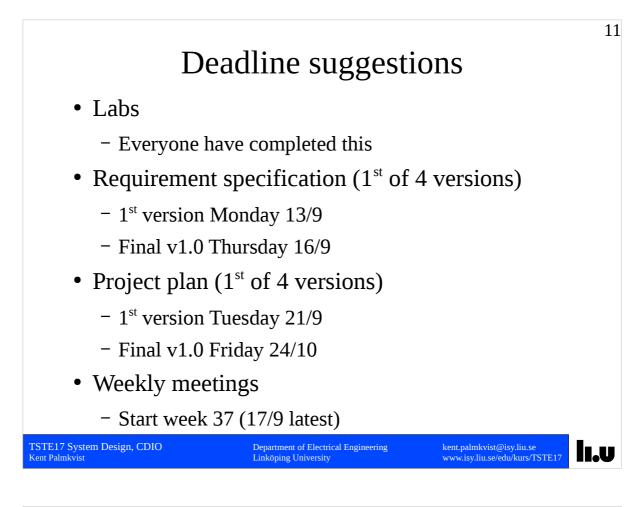
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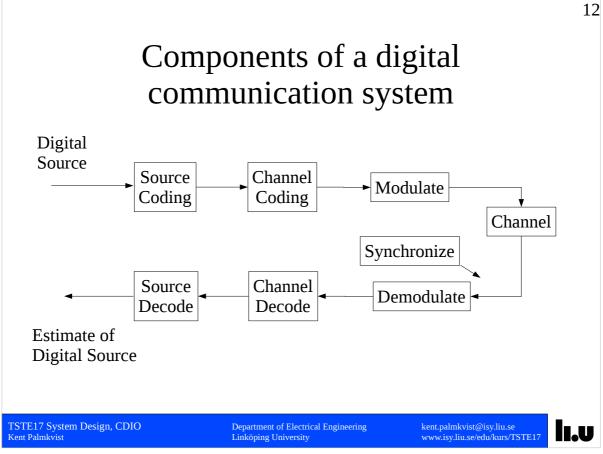
- Timing

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# Quadrature Amplitude Modulation (QAM)

- Modulate both amplitude and phase
- Use equal distance between all points

16-QAM

• Each point represents transmission of one sinusoidal waveform with unique amplitude and phase combination

Coherent and non-coherent modulation

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- Coherent modulation
  - requires a phase lock between transmitter and reciever RF carrier waves.
  - Gives higher performance
  - Requires more complex reciever structure
- Non-coherent modulation
  - Simpler reciever structure
  - Can not use QAM, PSK, ASK

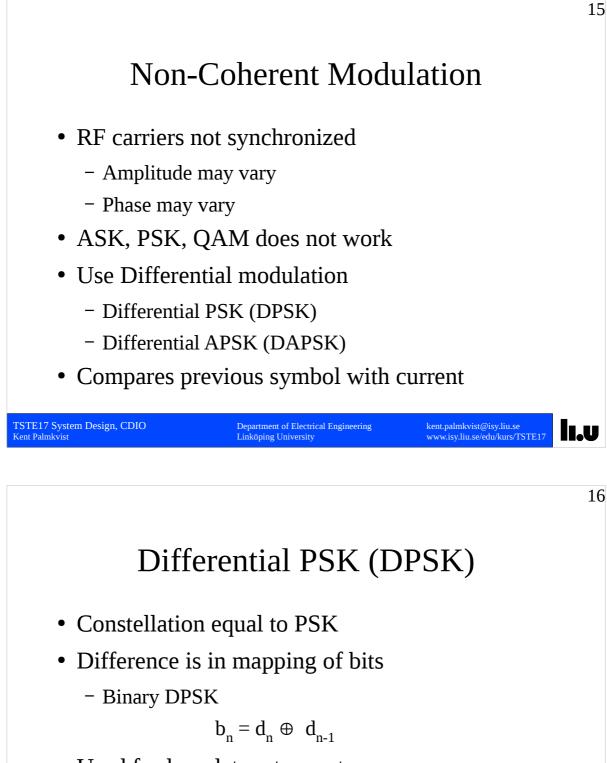
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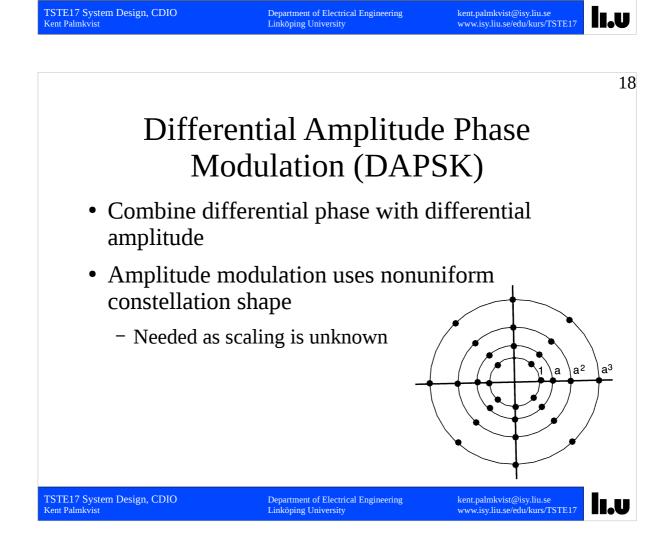


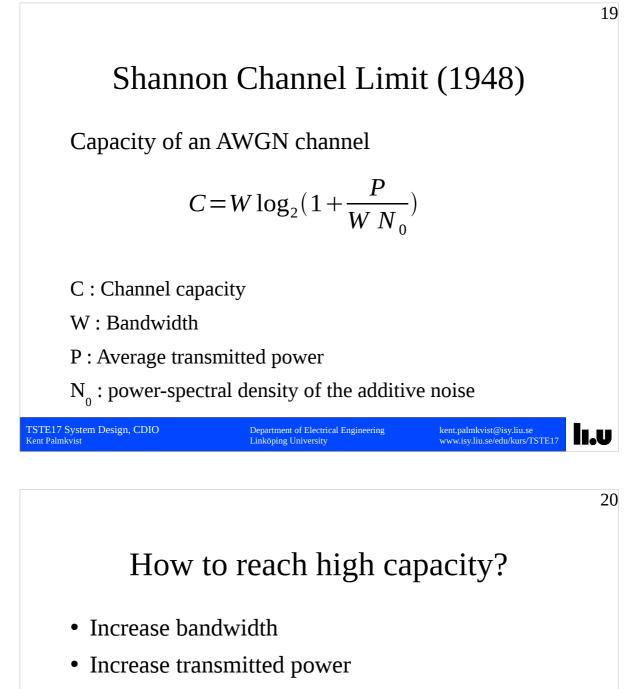
- Used for low data rates systems
- Used if simple receiver structure is needed



# **Differential Modulation Detection**

- Two step procedure
  - Remove differential encoding
  - Use normal demodulation as in coherent modulation
- Two symbols used for each detection
- Double amount of noise per detected symbol

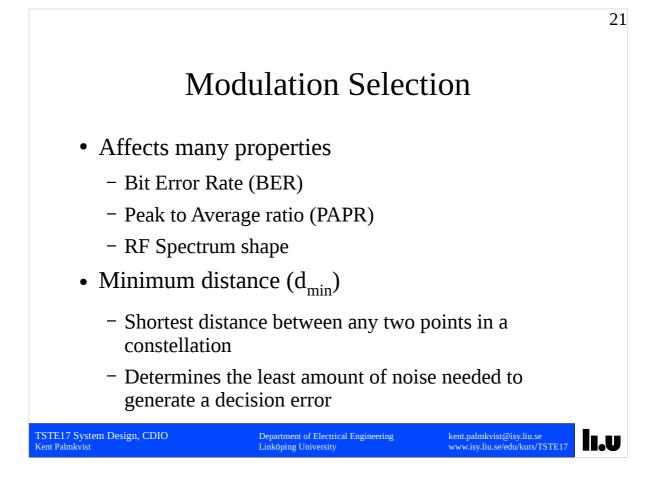


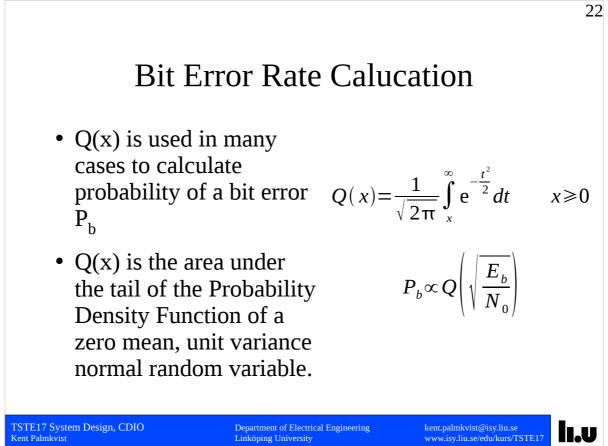


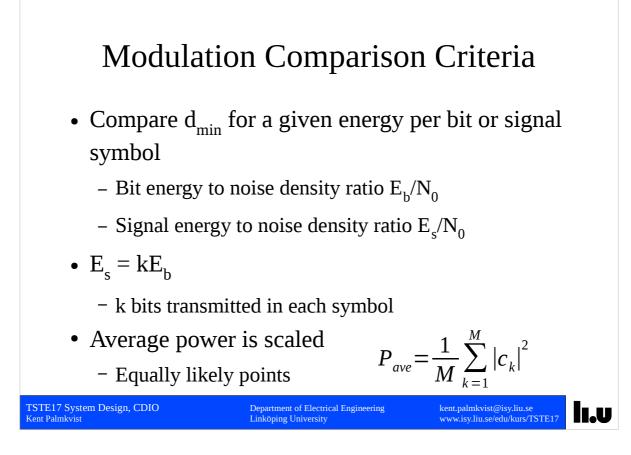
- Reduce additive noise
  - Noise sources includes physical media, amplifiers, filters, etc.
- Note: Shannon capacity is an upper limit!
  - Most modulation techniques are far from the limit

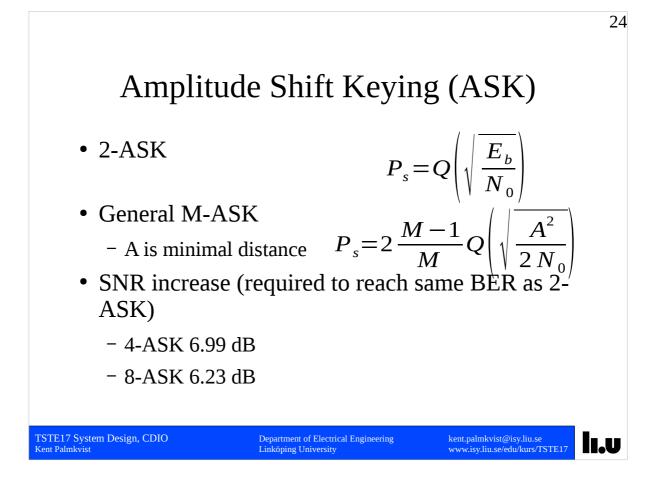
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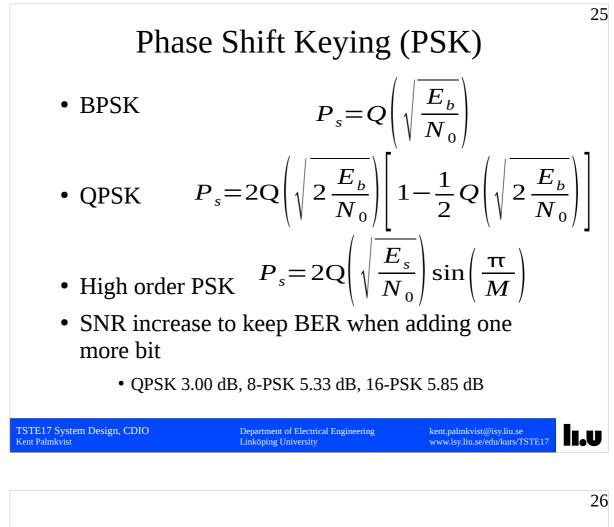












# Quadrature Amplitude Modulation (QAM)

• M-QAM

$$P_{s} \approx 4 \left( 1 - \frac{1}{\sqrt{M}} \right) Q \left( \sqrt{\frac{3E_{s}}{(M-1)N_{0}}} \right)$$

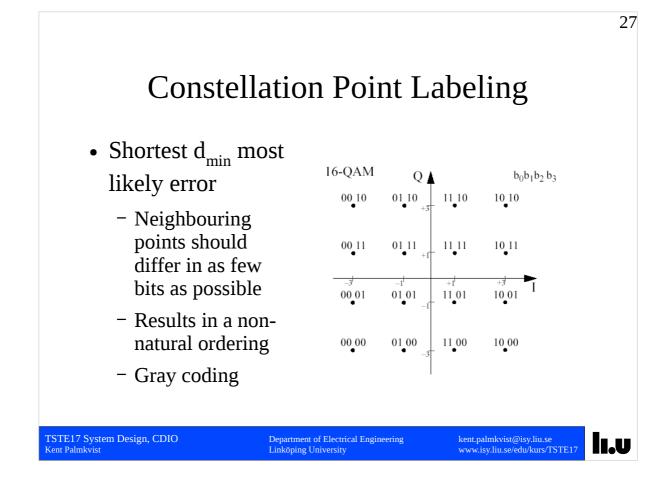
• SNR increase for each additional bit (initially QPSK)

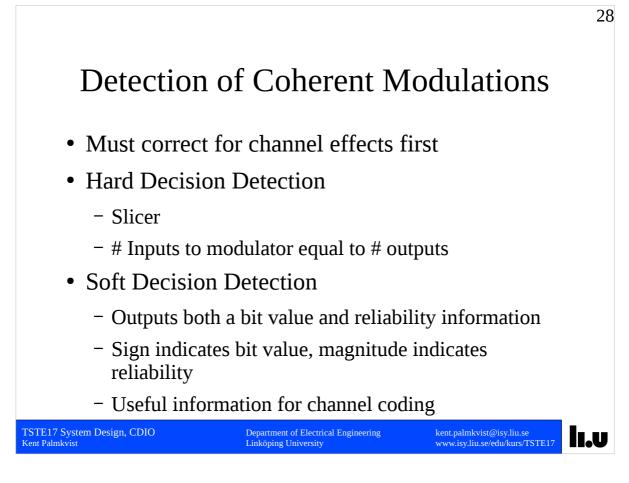
- 8-QAM 4.77 dB

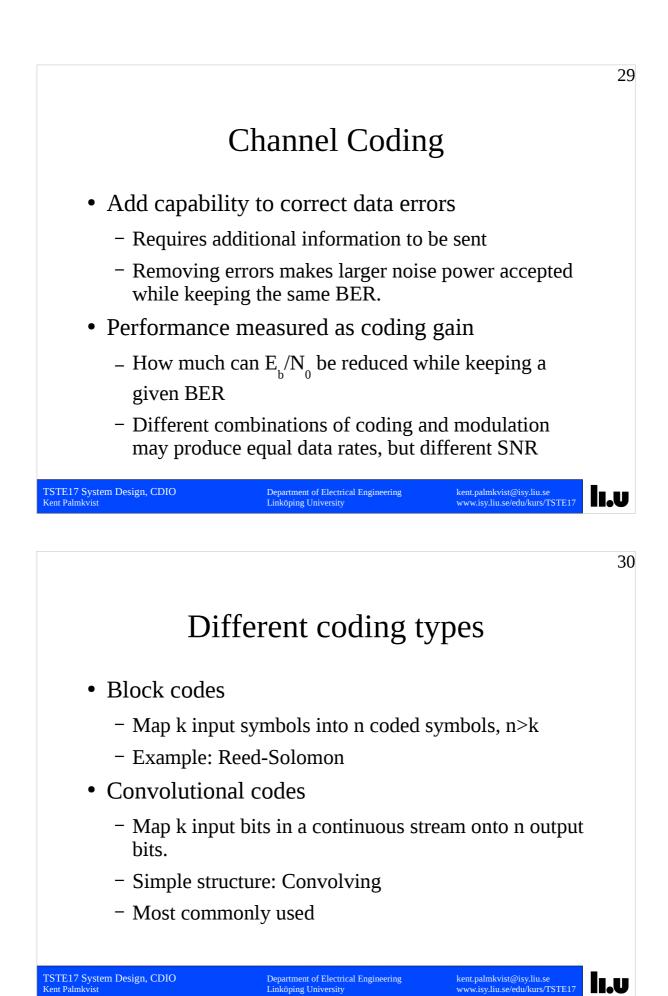
- 16-QAM 2.22 dB
- 32-QAM 3.01 dB

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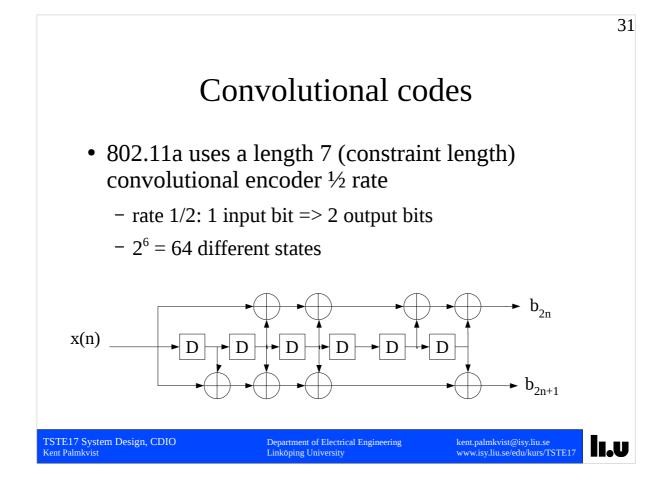


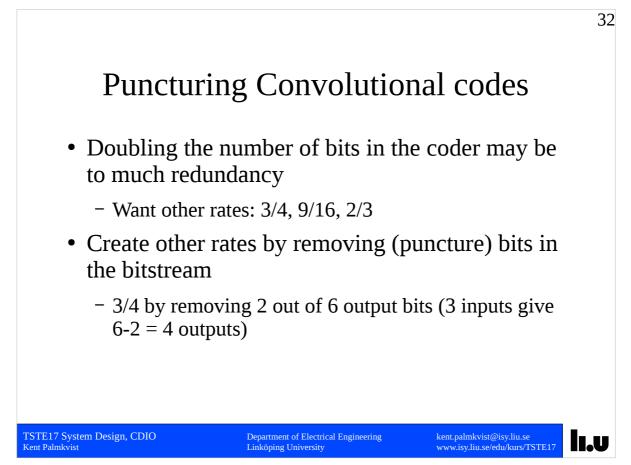


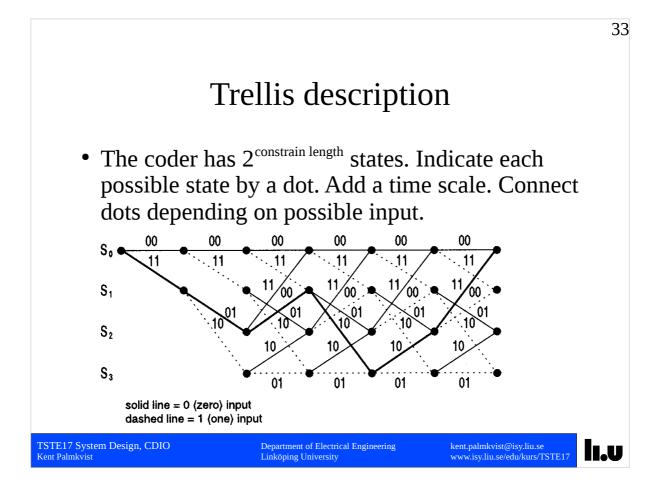


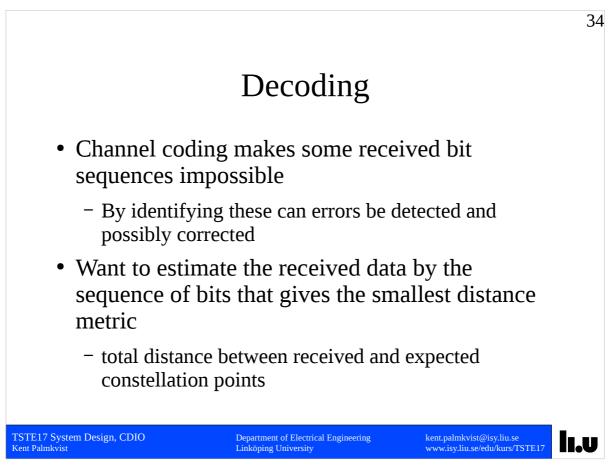
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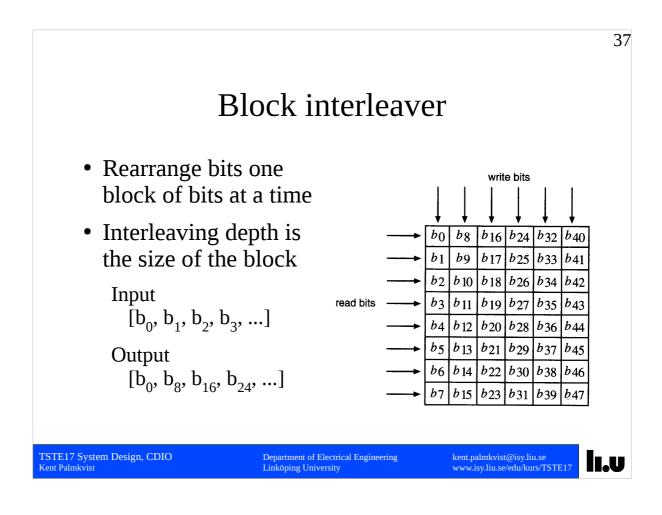


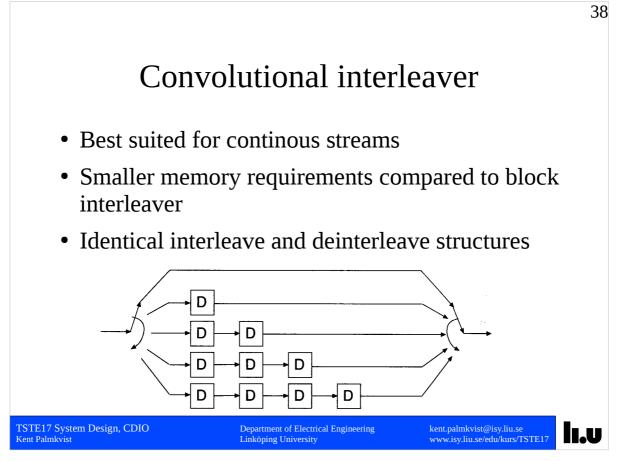


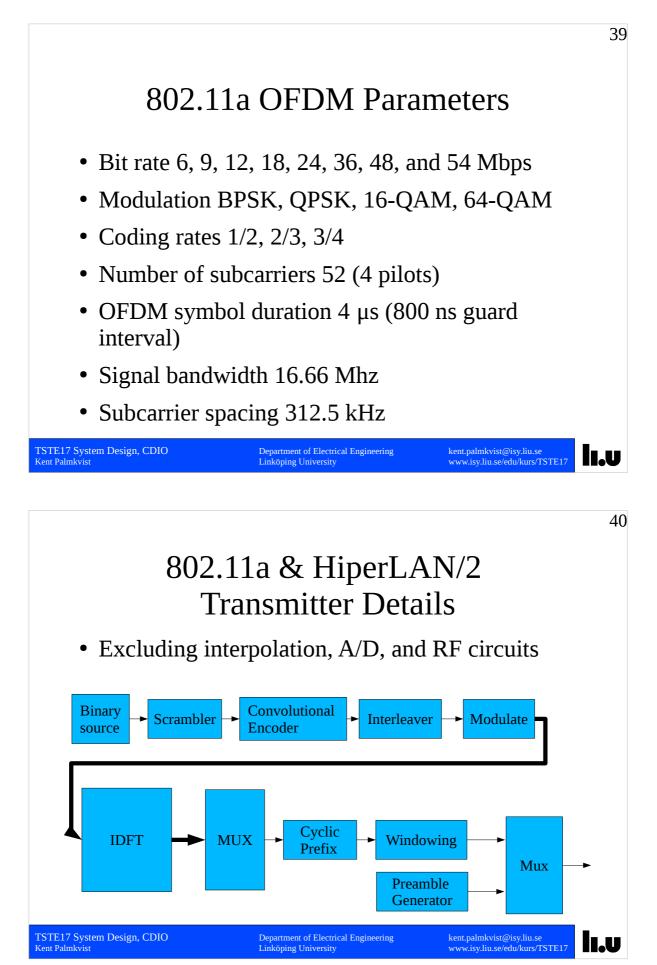


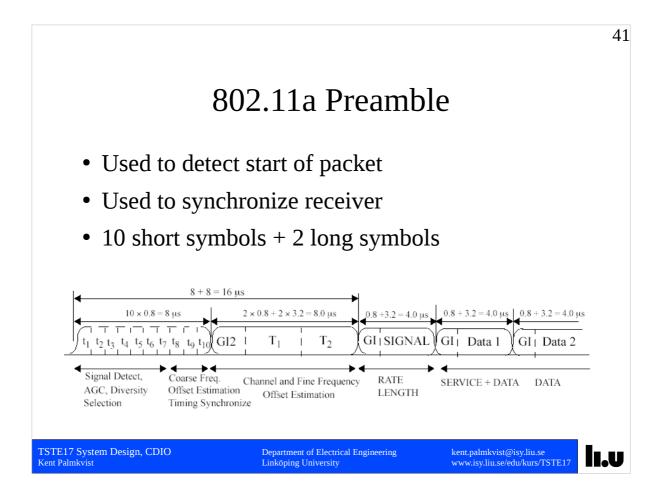
### 35 Viterbi algorithm Measure distance between signals at each sampling instant t<sub>i</sub> and all paths entering each state or node at time t<sub>i</sub> • Save the path with the lowest distance for each state or node at time t<sub>i</sub>. Save the sum of the distances for each saved path. • Advance deeper in the trellis. The surviving path is then the most likely bitstream. TSTE17 System Design, CDIO Kent Palmkvist kent.palmkvist@isy.liu.se www.isy.liu.se/edu/kurs/TSTE17 Department of Electrical Engineering II.U Linköping University 36 Interleaving Want to avoid get bursts of bit errors - Helps getting good results in channel coding by changing error distribution • Interleaving increases delay - More efficient with large interleave - Acceptable delay often limited phone to phone delay < 20 ms</li>

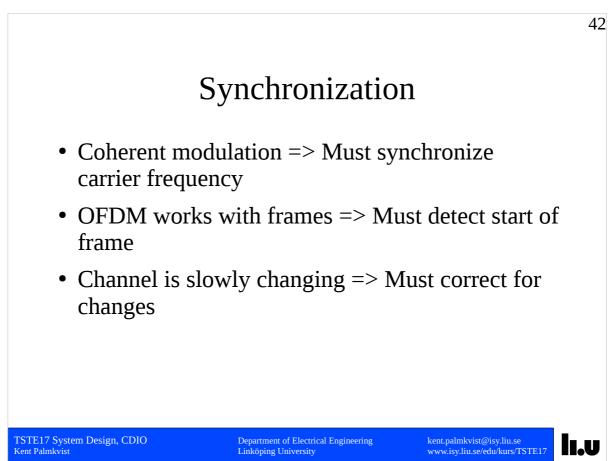


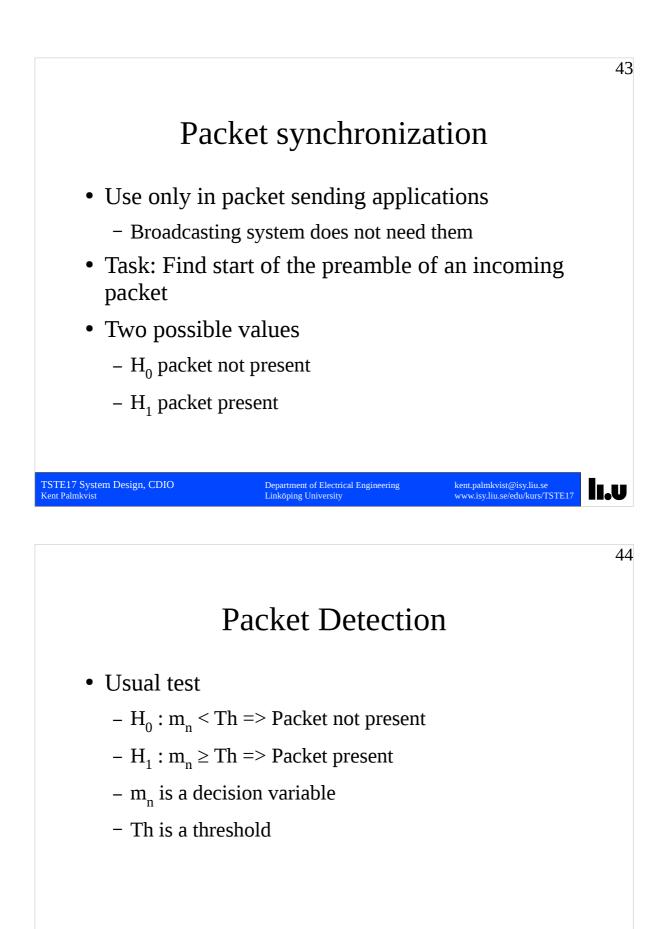










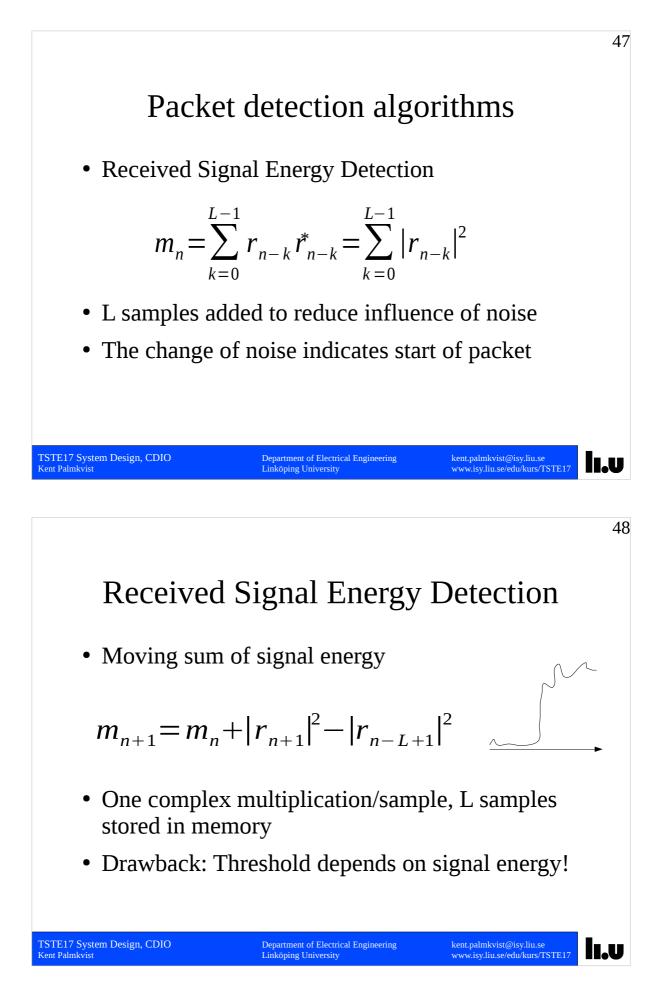


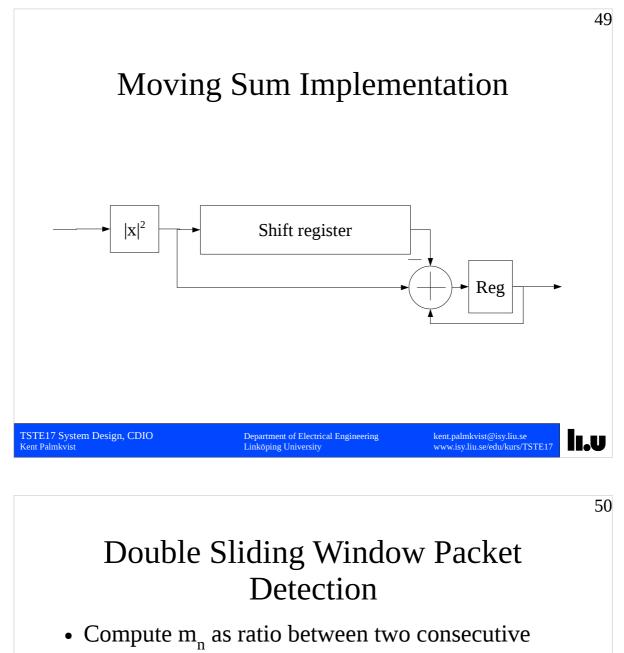
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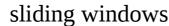
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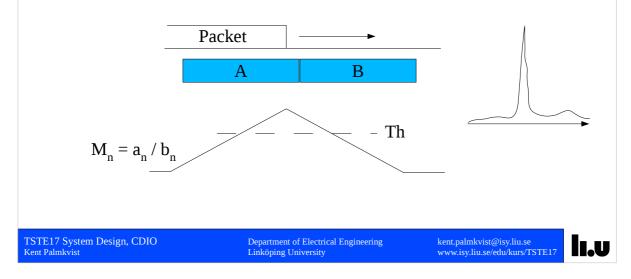
# Packet detection performance • Probability of detection P<sub>D</sub>, should be as large as possible • Probability of false alarm P<sub>FA</sub>, should be as low as possible • Want high $P_D$ and low $P_{FA}$ , but increasing $P_D$ generally increases P<sub>FA</sub> • Generally worse with low P<sub>D</sub> TSTE17 System Design, CDIO Kent Palmkvist kent.palmkvist@isy.liu.se www.isy.liu.se/edu/kurs/TSTE17 Department of Electrical Engineering II.U Linköping University 46 Packet detection algorithms • Received Signal Energy Detection • Double Sliding Window Packet Detection • Using the preamble structure

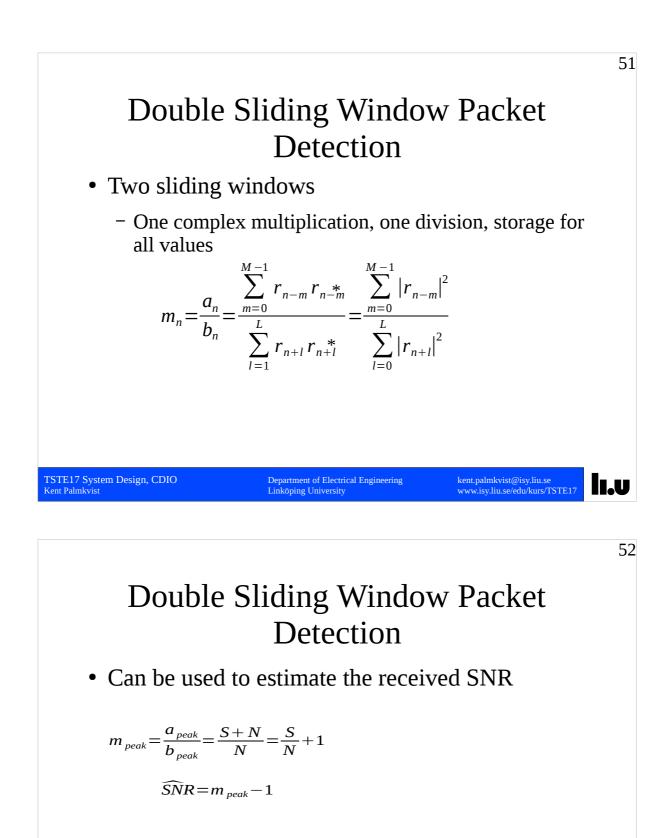










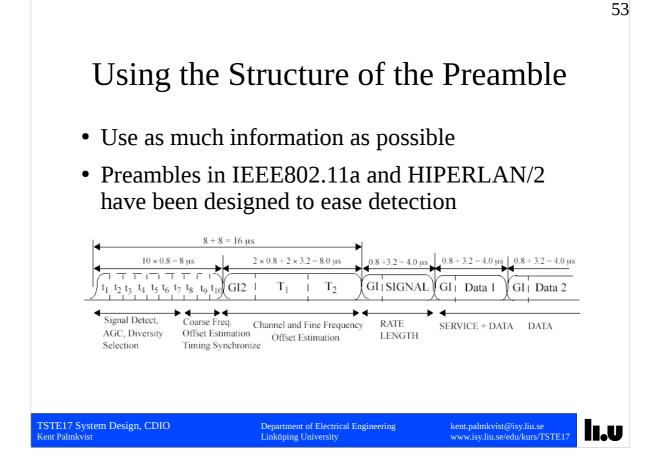


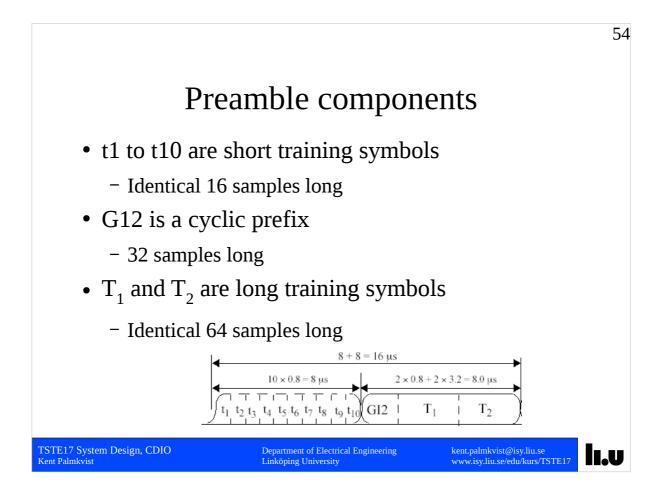
• Does not use known information about expected format of the preamble

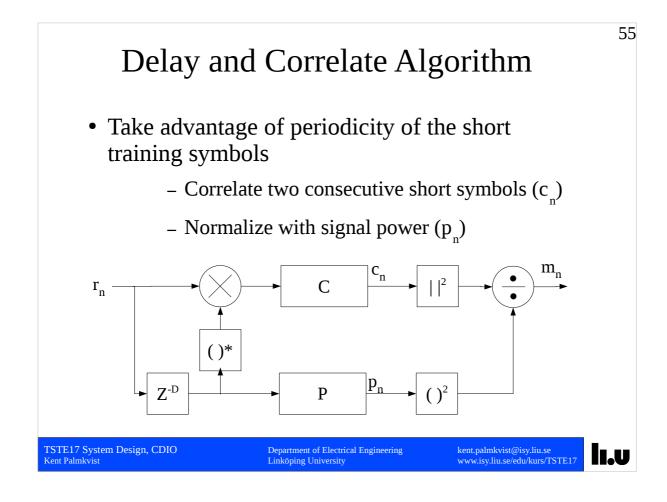
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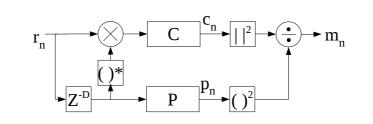


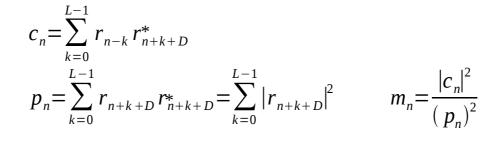












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