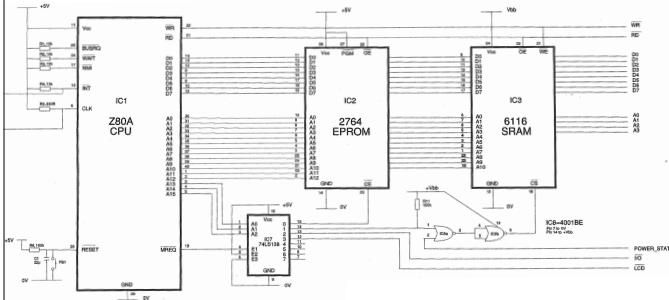
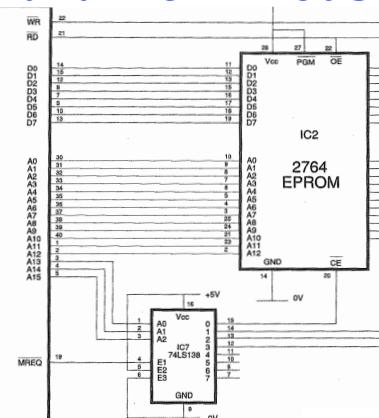


## Parallel "buss"



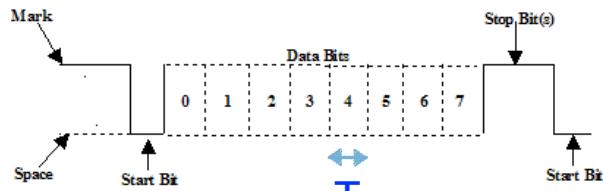
(Electronics World)

## Parallel "buss"



(Electronics World)

## RS232



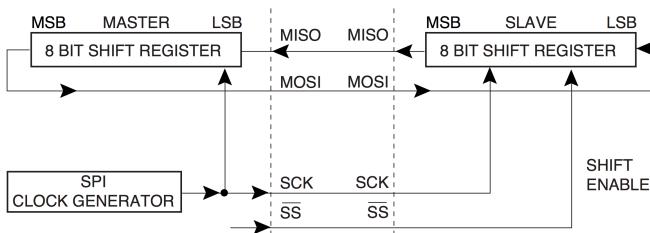
Baud rate = 1/T

(wesnet.com)

## RS232 – ATMega16A

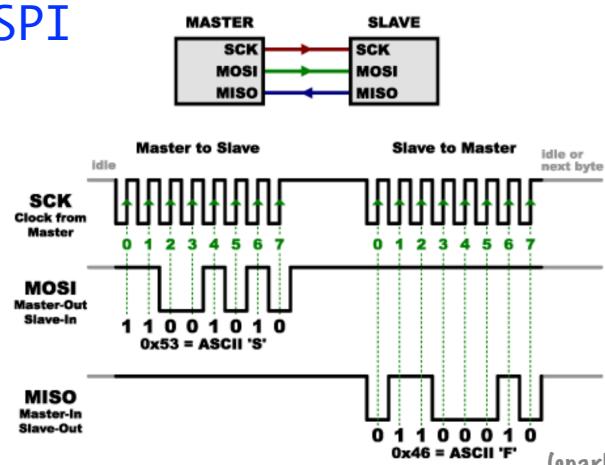
XTAL1	<input type="checkbox"/>	13
(RXD)	<input type="checkbox"/>	PD0
(TXD)	<input type="checkbox"/>	PD1
(INT0)	<input type="checkbox"/>	PD2

## SPI – Serial Peripheral Interface



(atmel.com)

## SPI

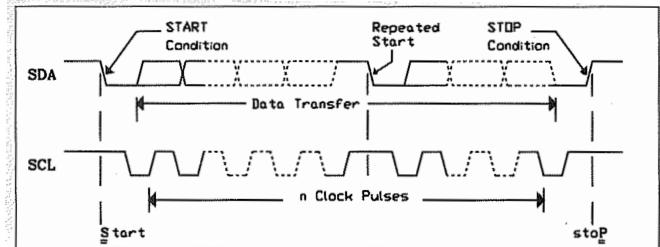


(sparkfun)

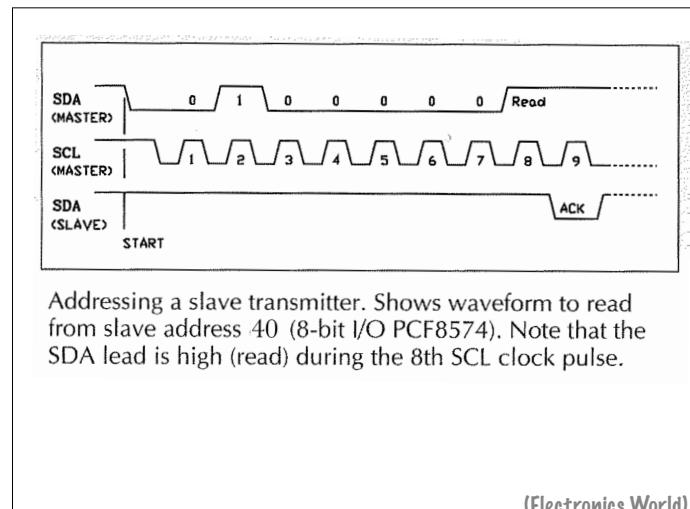
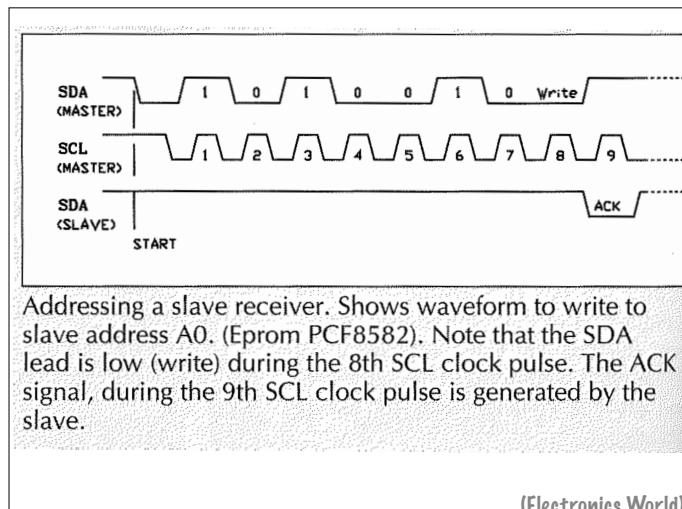
# SPI – ATMega16A

(INT2/AIN0)	PB2	<input type="checkbox"/>	3
(OC0/AIN1)	PB3	<input type="checkbox"/>	4
(SS)	PB4	<input type="checkbox"/>	5
(MOSI)	PB5	<input type="checkbox"/>	6
(MISO)	PB6	<input type="checkbox"/>	7
(SCK)	PB7	<input type="checkbox"/>	8
RESET		<input type="checkbox"/>	9
VCC		<input type="checkbox"/>	10
GND		<input type="checkbox"/>	11

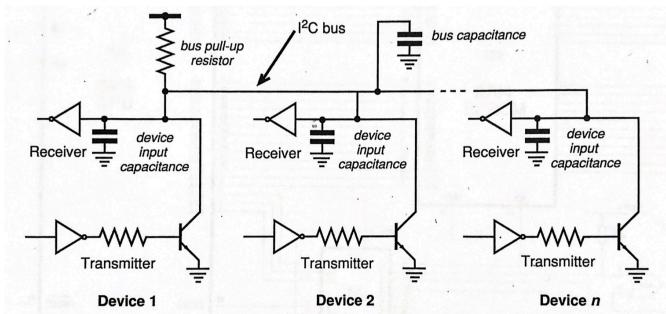
## I2C/TWI – Two Wire Interface



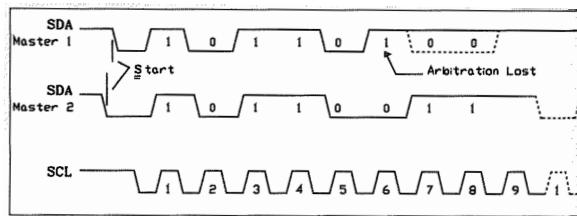
Start and stop conditions shows the relationship of the start, repeated start and stop conditions on the SDA lead with reference to the SCL Lead. The repeated start condition is used when a master needs to retain control of the bus during a combined write/read transfer, for example, when accessing a memory device. (Electronics W)



I2C/TWI – Elektriskt



## I<sup>2</sup>C/TWI – Bus Arbitration



(Electronics World)

## I2C/TWI – ATMega16A

25	<input type="checkbox"/> PC3 (TMS)
24	<input type="checkbox"/> PC2 (TCK)
23	<input type="checkbox"/> PC1 (SDA)
22	<input type="checkbox"/> PC0 (SCL)
21	<input type="checkbox"/> PD7 (OC2)