

$$A_{V} = \frac{R_{L}}{2R_{S}}$$
(i) Noise from MI:  $\overline{V_{n,outmi}^{2}} = \frac{4kT_{S}}{Sm} \left(\frac{R_{L}}{R_{S}+\frac{1}{Sm}}\right)^{2} = kT_{S}\frac{R_{L}^{2}}{R_{S}}$ 
Noise from  $R_{L} = \overline{V_{n,out,RL}^{2}} = 4RTR_{L}$ 
(ii) NF:  $I = \frac{V_{n,out,RL}^{2}}{R_{V}^{2} \cdot \overline{V_{n,RS}^{2}}} = \frac{4kT_{S}}{R_{S}}$ 

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1c.

3 dB, see Razavi, chapter 6.1.2

2.

As a start, see Tutorial 6, problem 2. But here not matched,  $gm \neq R_{S.}$  This is actually Problem 5.8 from the book.

1. Calculate the votlage gain

$$V_{out}$$

$$V_{x}$$

$$V_{x}$$

$$V_{x}$$

$$V_{x}$$

$$V_{x}$$

$$V_{x}$$

$$V_{x}$$

$$F_{1}$$

$$V_{x}$$

$$F_{1}$$

$$V_{x}$$

$$F_{1}$$

$$V_{x}$$

$$F_{1}$$

$$V_{x}$$

$$F_{1}$$

$$F_{1}$$

$$V_{y}$$

$$F_{1}$$

$$F_{1}$$

$$F_{1}$$

$$F_{1}$$

$$F_{1}$$

$$F_{1}$$

Since  $R_{in} = \frac{1}{g_{m1}}$ , we have the voltage gain from Vin to Vout:

$$A_{V} = \frac{\frac{1}{g_{m1}}}{R_{S} + \frac{1}{g_{m1}}} A_{X} = \frac{g_{m1}R_{1}}{1 + R_{S}g_{m1}}$$

- 2. Calculate noise figure The noise contributions are from M1, R1, and Rs.
  - a. Calculate output noise from M1



2. (continued)

 $A_{M1} = -\frac{R_1}{R_S + \frac{1}{g_{m1}}}, \text{ hence the output noise of M1 can be obtained from}$  $\overline{V_{n,out}^2}\Big|_{M1} = \frac{4kT\gamma}{g_{m1}}A_{M1}^2 = \frac{4kT\gamma}{g_{m1}}(\frac{R_1}{R_S + \frac{1}{g_{m1}}})^2$ 

b. Calculate output noise from R1

$$\left. \overline{V_{n,out}^2} \right|_{R_1} = 4kTR_1$$

The noise of  $R_S$  is multiplied by the gain when referred to the output, and the result is divided by the gain when referred to the input.

We thus have:

$$NF = \frac{1}{4kTR_{s}} \frac{\overline{V_{n,out}^{2}}}{A_{v}^{2}}$$
$$= 1 + \frac{4kTR_{1}}{4kTR_{s}(\frac{g_{m1}R_{1}}{1 + R_{s}g_{m1}})^{2}} + \frac{\frac{4kT\gamma}{g_{m1}}(\frac{R_{1}}{R_{s} + \frac{1}{g_{m1}}})^{2}}{4kTR_{s}(\frac{g_{m1}R_{1}}{1 + R_{s}g_{m1}})^{2}}$$
$$= 1 + \frac{(1 + R_{s}g_{m1})^{2}}{R_{s}R_{1}g_{m1}^{2}} + \frac{\gamma}{g_{m1}R_{s}}$$

З.

- a. See Example 5.3 in Razavi. New value for Q = 5400/(5900-4900) = 5.4
- b. On-chip L:s are usually much more lossy than on-chip C:s.
- c. In the L, the Q value is mainly limited by the series resistance in the metallization and, at higher frequencies, the losses in the substrate.

4.

- DC phase shift =  $180^{\circ}$  (frequency  $\rightarrow 0$ ) (a) Open loop circuit contains one pole => Frequency dependent phase shift = 90° (at frequency  $\rightarrow \infty$ ) Total phase shift =  $90^{\circ} + 180^{\circ} = 270^{\circ} \implies$  No oscillation. DC phase shift =  $0^{\circ}$  (frequency  $\rightarrow 0$ ) (b) Open loop circuit contains two poles => Frequency dependent phase shift =  $90^{\circ} + 90^{\circ} = 180^{\circ}$  (at frequency  $\rightarrow \infty$ ) Total phase shift =  $0^{\circ} + 180^{\circ} = 180^{\circ} \implies$  No oscillation. (c) DC phase shift =  $180^{\circ}$  (frequency  $\rightarrow 0$ ) Open loop circuit contains two poles => Frequency dependent phase shift =  $90^{\circ} + 90^{\circ} = 180^{\circ}$  (at frequency  $\rightarrow \infty$ ) Total phase shift =  $180^\circ + 180^\circ = 360^\circ$ But as frequency  $\rightarrow \infty$  the loop gain vanishes => No oscillation. DC phase shift =  $180^{\circ}$  (frequency  $\rightarrow 0$ ) (d)
- Open loop circuit contains three poles => Frequency dependent phase shift = 90° + 90° + 90° = 270° (at frequency  $\rightarrow \infty$ ) Total phase shift = 180° + 270° = 450° or 90° However at  $f = f_{p1,2,3} < \infty$ , where  $f_p$  is the cut-off frequency of a stage, the frequency dependent phase shift = 45° + 45° + 45° = 135°

Therefore for some  $f_p < f < \infty$  the circuit may oscillate with a sufficient loop gain.

5.

(a) Ignoring higher frequency terms:

$$i_{LO}(t) = \frac{1}{2} + \frac{2}{\pi} \cos \omega_{LO}(t) - \frac{2}{3\pi} \cos 3\omega_{LO}(t) + \dots$$
 and  $i_{RF}(t) = I_{RF} \cos \omega_{RF}(t) + I_{BIAS}(t)$ 

Therefore in case of switching the output voltage at IF is given by:

$$i_{IF}(t) = \left[I_{RF}\cos\omega_{RF}(t) + I_{BIAS}\right] \times \left[\frac{1}{2} + \frac{2}{\pi}\cos\omega_{LO}(t)\right]$$
$$i_{IF}(t) = \frac{I_{RF}}{2}\cos\omega_{RF}(t) + \frac{I_{BIAS}}{2} + \frac{2I_{BIAS}}{\pi}\cos\omega_{LO}(t) + \frac{I_{RF}}{\pi}\cos(\omega_{LO} - \omega_{RF})t$$

Applying  $V_{IF}(t) = -g_m R V_{RF}$ , The conversion gain is given by:

$$G_{C} = \left| \frac{V_{IF}(t)}{V_{RF}(t)} \right| = \left| \frac{R \times i_{IF}(t)}{\frac{i_{RF}(t)}{g_{m}}} \right| = \frac{\frac{1}{\pi} g_{m} R I_{RF}}{I_{RF}} = \frac{1}{\pi} g_{m} R$$

$$(b) \quad \overline{V}_{nout,M3}^{2} = \overline{I}_{n,M3}^{2} R^{2} = 4KT \gamma g_{do} R^{2} \Delta f$$

$$\overline{V}_{nout,R_{S}}^{2} = \overline{V}_{n,R_{S}}^{2} A_{V}^{2} = 4KT R_{S} (g_{m} R)^{2} \Delta f$$

$$\overline{V}_{nout,R}^{2} = 4KTR \Delta f$$

The noise factor is given by:

$$F = \frac{\overline{V}_{nout,M3}^{2} + \overline{V}_{nout,R_{s}}^{2} + \overline{V}_{nout,R}^{2}}{(G_{c})^{2}\overline{V}_{n,R_{s}}^{2}} = \pi^{2} \left(1 + \frac{\gamma}{g_{m}^{2}R_{s}} + \frac{1}{g_{m}^{2}RR_{s}}\right)$$

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6.

- a. A Class-A has the best linearity among the linear classes (A, AB, B, C). By DC-biasing it to half the full output signal, any frequency signal would just swing around this middle point, with no limitations (unless very large). Class-B is off half the cycle, it is very non-linear.
- b. A Class-A: see above. Class-D is a switching amplifier, it has only on/off levels, and therefore very bad linearity.
- c. AB Class-A has 50 % maximum theoretical efficiency, class-B 78.5 %, and the class AB somewhere between.
- d. A Both class-A and class-E have voltage peaks (on the drain of the transistor above Vdd, but A no more than about 2, while class-E is over 3.5.
- e. DE = RF-power out / DC power in. PAE = (RF-power out - RF-power in) / DC power in

So PAE also takes into account the input power. With high gain, then DE >> PAE, with high gain DE  $\approx$  PAE, but PAE can never be higher than the DE.

From the lecture notes:

