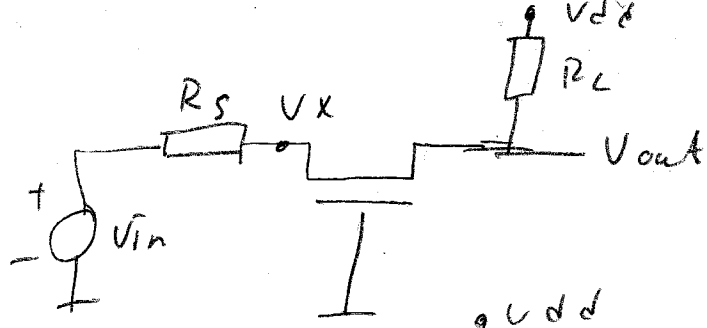
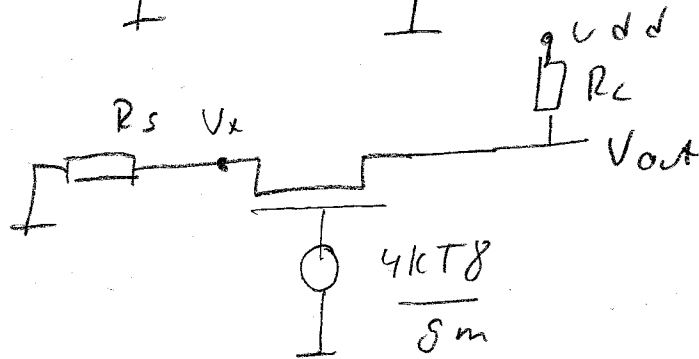


Solutions.

(a) Circuit:



For noise



(i) Gain? $\frac{V_{out}}{V_x} = g_m \cdot R_L$

$$A_v = \frac{V_{out}}{V_{in}} = g_m \cdot R_L \left(\frac{\frac{1}{g_m}}{\frac{1}{g_m} + R_s} \right) = g_m \cdot R_L \left(\frac{1}{1 + g_m \cdot R_s} \right)$$

When used as an LNA, select $g_m = \frac{1}{R_s} \Rightarrow$

$$A_v = \frac{R_L}{2R_s}$$

(ii) Noise from MI: $\overline{V_{n,out,MI}^2} = \frac{4kT\gamma}{g_m} \left(\frac{R_L}{R_s + \frac{1}{g_m}} \right)^2 = kT\gamma \frac{R_L^2}{R_s}$

Noise from $R_L = \overline{V_{n,out,RL}^2} = 4kTR_L$

(iii) NF: $1 + \frac{\overline{V_{n,out,MI}^2} + \overline{V_{n,out,RL}^2}}{A_v^2 \cdot \overline{V_{n,RS}^2}} =$

(1 a) cont.

$$= 1 + \frac{KT\gamma \frac{R_L^2}{R_S} + 4KT R_L}{\left(\frac{R_L}{2R_S}\right)^2 \cdot 4KT R_S}$$

$$= 1 + \frac{KT R_L^2}{R_S}$$

$$= \boxed{1 + \gamma + 4 \frac{R_S}{R_L}} \quad NF$$

1 b) For gate noise, add another voltage source on the gate:

$$\overline{V_{n,out,MIS}^2} = \frac{4KT R_G}{3} \cdot \left(\frac{R_L}{2R_S}\right)^2 =$$

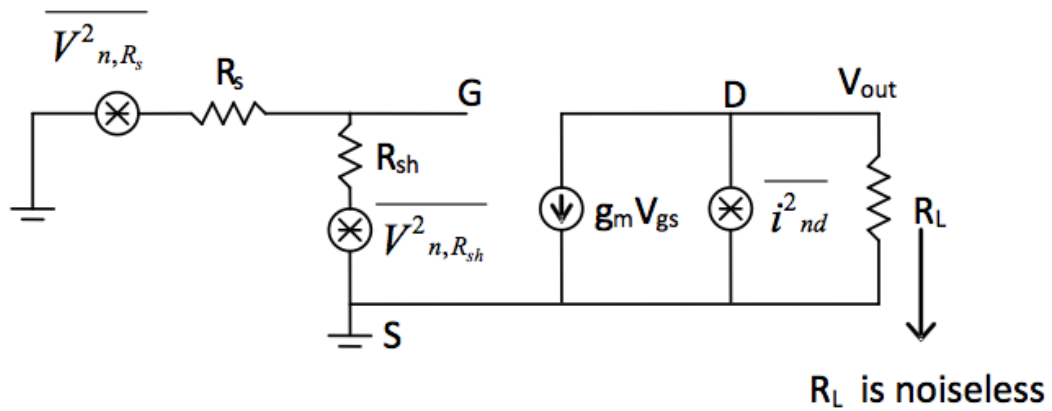
$$= \frac{KT \cdot R_G \cdot R_L^2}{3 R_S^2}$$

$$\Rightarrow NF = 1 + \frac{KT\gamma \frac{R_L^2}{R_S} + \frac{KT R_G \cdot R_L^2}{3 R_S^2} + 4KT R_L}{KT \frac{R_L^2}{R_S}} =$$

$$\boxed{1 + \gamma + \frac{R_G}{3R_S} + 4 \frac{R_S}{R_L}} \quad NF$$

2.

a.



Gain:

$$Gain|_{Gate} = -g_m R_L$$

$$A = -g_m R_L \left(\frac{R_{sh}}{R_s + R_{sh}} \right)$$

Z_{in} : When the gate capacitance is not included in the small-signal model (above), the input impedance is purely resistive: $Z_{in} = R_{sh}$.

Noise Figure:

$$F = \frac{\text{Total output noise power}}{\text{Output noise due to input source}}$$

$$\overline{V^2_{n,R_s}} = 4kTR_s$$

$$\overline{V^2_{n,R_{sh}}} = 4kTR_{sh}$$

$$\overline{i^2_{nd}} = 4kT\gamma g_m$$

Using superposition, only one noise source is considered at a time and other sources should be shorted (voltage noise source) / open (current noise source).

$$\overline{V_{no,R_s}^2} = \overline{V_{n,R_s}^2} \times g_m^2 R_L^2 \times \left(\frac{R_{sh}}{R_s + R_{sh}} \right)^2$$

$$\overline{V_{no,R_{sh}}^2} = \overline{V_{n,R_{sh}}^2} \times g_m^2 R_L^2 \times \left(\frac{R_s}{R_s + R_{sh}} \right)^2$$

$$\overline{V_{no,d}^2} = \overline{i_{nd}^2} \times R_L^2$$

$$F = \frac{\overline{V_{no,R_s}^2} + \overline{V_{no,R_{sh}}^2} + \overline{V_{no,d}^2}}{\overline{V_{no,R_s}^2}} = 1 + \frac{\overline{V_{no,R_{sh}}^2} + \overline{V_{no,d}^2}}{\overline{V_{no,R_s}^2}}$$

$$F = 1 + \frac{4kTR_{sh} \frac{g_m^2 R_L^2 R_s^2}{(R_s + R_{sh})^2}}{4kTR_s \frac{g_m^2 R_L^2 R_{sh}^2}{(R_s + R_{sh})^2}} + \frac{4kT\gamma g_m R_L^2}{4kTR_s \frac{g_m^2 R_L^2 R_{sh}^2}{(R_s + R_{sh})^2}} =$$

$$1 + \frac{R_{sh} \frac{g_m^2 R_L^2 R_s^2}{(R_s + R_{sh})^2}}{R_s \frac{g_m^2 R_L^2 R_{sh}^2}{(R_s + R_{sh})^2}} + \frac{\gamma g_m R_L^2}{R_s \frac{g_m^2 R_L^2 R_{sh}^2}{(R_s + R_{sh})^2}} = 1 + \frac{R_{sh} g_m^2 R_L^2 R_s^2}{R_s g_m^2 R_L^2 R_{sh}^2} + \frac{\gamma g_m R_L^2 (R_s + R_{sh})^2}{R_s g_m^2 R_L^2 R_{sh}^2} =$$

$$1 + \frac{R_s}{R_{sh}} + \frac{\gamma (R_s + R_{sh})^2}{g_m R_s R_{sh}^2}$$

Incorrect in first version!

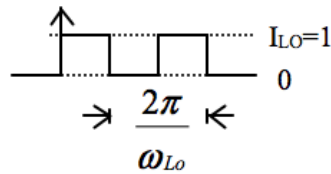
b. Best LNA performance in the system is achieved when $Z_{in} = 50 \Omega \Rightarrow R_s = R_{sh} = 50 \Omega$.

$$F = 1 + 1 + \frac{\gamma (R_s + R_{sh})^2}{g_m R_s R_{sh}^2} = 2 + \frac{4\gamma}{g_m R_s}$$

Incorrect in first version!

3.

LO-IF feedthrough: measured level of the 900-MHz output component in the absence of an RF signal.



$$i_{LO}^+(t) = \frac{1}{2} + \frac{2}{\pi} \cos \omega_{LO}(t) - \frac{2}{3\pi} \cos 3\omega_{LO}(t) + \frac{2}{5\pi} \cos 5\omega_{LO}(t) - \dots$$

$$i_{LO}^-(t) = \frac{1}{2} - \frac{2}{\pi} \cos \omega_{LO}(t) + \frac{2}{3\pi} \cos 3\omega_{LO}(t) - \frac{2}{5\pi} \cos 5\omega_{LO}(t) + \dots$$

$$i_{RF}(t) = I_1 + I_{RF} \cos \omega_{RF} t$$

No RF signal: $I_{RF} = 0 \Rightarrow i_{RF}(t) = I_1$

The output current at IF is given by:

$$i_{IF}^+(t) = i_{LO}^+(t) \times i_{RF}(t) = \left[\frac{1}{2} + \frac{2}{\pi} \cos \omega_{LO}(t) - \frac{2}{3\pi} \cos 3\omega_{LO}(t) + \frac{2}{5\pi} \cos 5\omega_{LO}(t) - \dots \right] \cdot (I_1)$$

$$= \frac{I_1}{2} + \frac{2I_1}{\pi} \cos \omega_{LO}(t)$$

$$i_{IF}^-(t) = i_{LO}^-(t) \times i_{RF}(t) = \left[\frac{1}{2} - \frac{2}{\pi} \cos \omega_{LO}(t) + \frac{2}{3\pi} \cos 3\omega_{LO}(t) - \frac{2}{5\pi} \cos 5\omega_{LO}(t) + \dots \right] \cdot (I_1)$$

$$= \frac{I_1}{2} - \frac{2I_1}{\pi} \cos \omega_{LO}(t)$$

$$i_{IF}(t) = i_{IF}^+(t) - i_{IF}^-(t) = \frac{4I_1}{\pi} \cos \omega_{LO}(t)$$

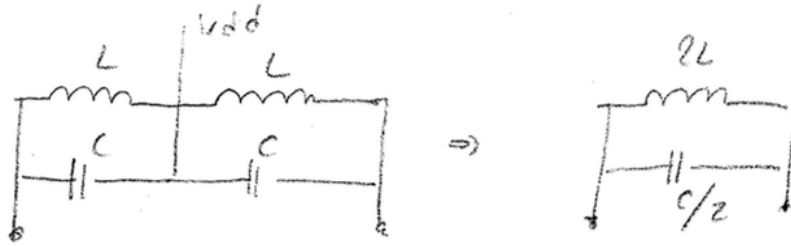
$$v_{IF}(t) = i_{IF}(t) \times R_p = \frac{4}{\pi} I_1 R_p \cdot \cos \omega_{LO}(t)$$

where R_p is the parallel resistance, which models the inductor loss.

$$R_p = Q \omega_o L_p \Rightarrow \text{LO-IF feedthrough} = \frac{4}{\pi} I_1 R_p = \frac{4}{\pi} I_1 Q \omega_{LO} L_p$$

4.

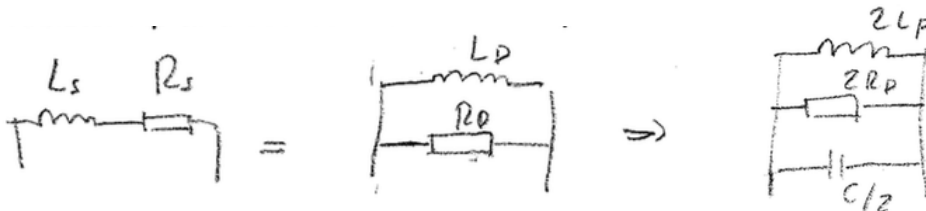
Equivalent circuits of the tank with no resistive loss:



a. Oscillation frequency with losses: $\omega_o = \frac{1}{\sqrt{2L * C/2}}$

=> $f \approx 2.055$ GHz.

b. To include losses and calculate a more accurate oscillation frequency, include parallel resistor R_p and use corrected value L_p :



$$\omega_o = \frac{1}{\sqrt{2L_p * C/2}}$$

$$L_p = (1 + 1/Q^2) * L_s$$

$$\omega_o = \frac{Q}{\sqrt{Q^2 + 1}} \times \frac{1}{\sqrt{L_s C}}$$

=> $f \approx 1.993$ GHz.

The frequency is about 62 MHz, or 3 %, lower.

c. First, we need to determine the required R_p for oscillations:

The parallel resistance $R_p = Q * \omega_o * L_p = 4 * (2 * \pi * 1993E6) * (1 + 1/16) * 2E-9 = 106.4 \Omega$.
To ensure oscillations, M1/M2 circuit needs to provide an $R_{negative}$ of -106.4Ω .

The negative resistance seen by RLC:

$$i_{in} = g_{m1}V_{gs1}, \quad -i_{in} = g_{m2}V_{gs2}$$

$$V_{in} = V_{gs2} - V_{gs1} = \frac{-i_{in}}{g_{m2}} - \frac{i_{in}}{g_{m1}} = -i_{in} \left(\frac{1}{g_{m2}} + \frac{1}{g_{m1}} \right)$$

$$R_{in} = \frac{V_{in}}{i_{in}} = - \left(\frac{1}{g_{m2}} + \frac{1}{g_{m1}} \right) = -\frac{2}{g_m} = -R_p$$

Since $g_m = g_{m1} = g_{m2} \approx \sqrt{2\mu_n C_{ox} I_D (W/L)}$

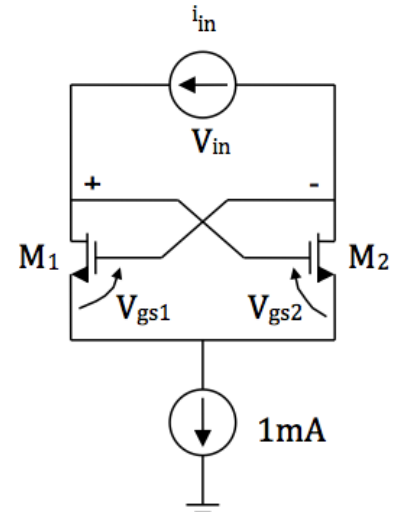
$$\mu_n C_{ox} = 200 \mu A/V^2, \quad I_D = \frac{1 \text{ mA}}{2} = 0.5 \text{ mA}$$

then $\frac{2}{R_p} = \sqrt{2\mu_n C_{ox} I_D (W/L)}$

$$(W/L) = \frac{2}{\mu_n C_{ox} I_D R_p^2}$$

$$(W/L) \cong 1765$$

With $L=0.06 \mu m \Rightarrow W = 106 \mu m$.



5.

a. closed-loop transfer function

$$F(s) = \frac{\frac{1}{sC_1}}{\frac{1}{sC_1} + R_1} = \frac{1}{sR_1C_1 + 1}$$

The close loop Transfer Function:

$$\varphi_{out} = \frac{K_{VCO}K_{PD}}{s} \left(\varphi_{in} - \frac{\varphi_{out}}{M} \right) \left(\frac{1}{sR_1C_1 + 1} \right)$$

$$\frac{\varphi_{out}}{\varphi_{in}}(s) = \frac{K_{VCO}K_{PD}M}{s(sR_1C_1 + 1)M + K_{VCO}K_{PD}}$$

$$= \frac{K_{VCO}K_{PD}M}{s^2R_1C_1M + sM + K_{VCO}K_{PD}} = \frac{\frac{K_{VCO}K_{PD}}{R_1C_1}}{s^2 + s\frac{1}{R_1C_1} + \frac{K_{VCO}K_{PD}}{R_1C_1M}} = \frac{\frac{K_{VCO}K_{PD}}{R_1C_1}}{s^2 + 2\xi\omega_n s + \omega_n^2}$$

b. damping factor ζ

$$\xi = \frac{1}{2} \sqrt{\frac{\omega_{LPF}M}{K_{VCO}K_{PD}}}$$

c. natural frequency ω_n

$$\omega_n = \sqrt{\frac{K_{VCO}K_{PD}\omega_{LPF}}{M}}$$

d. loop bandwidth = $\zeta * \omega_n = 1/2 * \omega_{LPF} = 1 / (2RC)$.

6.

a. C B D A E

(0.5 p for each correct amplifier class.)

b. A class-AB power amplifier is biased between class-A and class-B.

$V_{g,bias}$ for a class-A amplifier is selected to some value $>V_{TH}$ to achieve a standby current of $I_{D,max}/2$ (with no RF input signal).

$V_{g,bias}$ for a class-B amplifier is selected to V_{TH} to conduct 50 % of the cycle (conduction angle of 180°) (assuming a symmetrical input swing signal $\pm V_p$). The standby current is 0 (with no RF input signal).

$V_{g,bias}$ for a class-AB is selected somewhere between these two values, which can also be expressed as a conduction angle between π and 2π .

c. Efficiency vs. linearity.

("Trade-off" means that we have two properties that goes better/worse, worse/better. Need both properties.)

Missed in first
version!

d. To determine the optimum load for best PA performance (which is often maximum linear output power (P-1dB), or maximum efficiency). When doing it for the input (which is rather linear from the beginning), this separate measurement may be called "source-pull".